

Tudományos önéletrajz

Dr. Mester Gyula



Név: Mester Gyula
Születés ideje: 1945. június 10.
Születési hely: Torontálvásárhely (Debelja a, Jugoszlávia)
Nemzetisége: magyar

Egyetemi tanulmányait a Belgrádi Tudományegyetem, Gépészeti Karán fejezte be 1970-ben, oklevél száma: 2831.

Mester Gyula, okleveles gépészmérnök, posztgraduális tanulmányait a Belgrádi Tudományegyetem, Természettudományi Karán folytatta, ahol 1975. június 21-én a magiszteri munka megvédése után a:

mechanikai tudományok magisztere

fokozatot szerezte meg, oklevélszáma: 466/2.

Az Újvidéki Egyetem, M szaki Tudományok Karán, 1977. június 24-én a **doktori disszertáció** megvédése után a:

m szaki tudományok doktora

tudományos fokozatot szerezte meg, oklevélszáma: 834.

Az Oktatási Minisztérium Magyar Ekvivalencia és Információs Központja, MEIK-589-1/2001-es számú (2001.03.30) határozata szerint Mester Gyula Magyarországon doktori címét a következő formában használhatja:

M szaki tudományok doktora (Újvidéki Tudományegyetem, Jugoszlávia).

A honosítási határozatot:

- Doktor (PhD),
- m szaki tudományok tudományterülete,
- gépészeti tudományok tudományág, 28/2005,

a Budapesti M szaki és Gazdaságtudományi Egyetem, Egyetemi doktori tanácsa 2005. május 27-én hozta, az Újvidéki Tudományegyetem által m szaki tudományok tudományterületén, 1977-ben kibocsátott 834-es számú doktori oklevele alapján.

1977-ben az Újvidéki M szaki F iskolán, 1978-ban a Szabadkai M szaki F iskolán:

f iskolai tanárnak

nevezték ki.

Dr. Mester Gyulát az **Újvidéki Tudományegyetem** 1978-ban:

egyetemi docensnek,

majd 1983-ban:

rendkívüli egyetemi tanárnak

és 1988-ban

rendes egyetemi tanárnak

nevezték ki.

Dr. Mester Gyula jelenleg érvényes kinevezései:

Magyarországon:

- f iskolai tanár, 2004 id ponttól,
- **tudományos f munkatárs**, 2012 id ponttól.
- 2013. november 27-t 1 a **Magyar Mérnökakadémia rendes tagja**.

Szerbiában:

- **egyetemi tanár**, 1988 id ponttól.

Munkahelyek:

Szabadkai M szaki F iskola

- 1974-2011, f iskolai tanársegéd, el adó, f iskolai tanár,
- 2000-t l az Informatikai Intézet vezet je,
- 2003-2011 között az Informatikai Tanszék vezet je.

Oktatott tantárgyak:

- mechanika,
- mehanika (szerb és horvát nyelven),
- internet technológiák,
- internet tehnologije (szerb és horvát nyelven),
- multimédia rendszerek,
- multimedjiski sistemi (szerb és horvát nyelven),
- intelligens rendszerek,
- intelligentni sistemi (szerb és horvát nyelven),
- intelligens irányító rendszerek,
- intelligentni upravlja ki sistemi (szerb és horvát nyelven),
- bevezetés a robotikába,
- osnovi robotike (szerb és horvát nyelven),
- robotika,
- robotika (szerb és horvát nyelven).

Újvidéki Tudományegyetem

- 1979-2004, egyetemi docens, egyetemi tanár, oktatott tantárgyak:

Épít mérnöki Kar, Szabadka:

- mechanika,

Műszaki Kar „Mihajlo Pupin”, Nagybecskerek:

robotika (szerb és horvát nyelven).

Dunaújvárosi F iskola:

2004-2005, f iskolai tanár, az Általános Informatikai Tanszék vezet je, oktatott tantárgy:

- informatika alapjai,

Szegedi Tudományegyetem

Szegedi Élelmiszeripari F iskolai Kar:

- 2000-2005, els kent bevezetett és oktatott tantárgyak:
- robotika,
- intelligens rendszerek,
- web alkalmazásfejlesztés

Természettudományi Informatikai Kar:

- 2005-2011, els kent bevezetett és oktatott tantárgyak:
- robotika,
- intelligens rendszerek,
- mechatronika.

Mérnöki Kar:

- 2012., els kent bevezetett és oktatott tantárgyak:
- válogatott fejezetek robotikából,
- intelligens robotok.

1976-ban a Szabadkai M szaki F iskolán bevezette a:

magyar nyelv gépész- és villamos mérnökképzést.

Az 1983-1988 közötti id szakban a Szabadkai M szaki F iskola:
Automatika Kutatóintézetének
vezetje.

Az 1988-2001 közötti id szakban, a Szabadkai M szaki F iskola **f igazgatója**, ebben az id szakban a:

Szabadkai M szaki F iskola, Jugoszlávia legjobb f iskolájának számított.

Ma, a legújabb (2014. július):

Webometrics

elnevezés, fels oktatási világgranglista szerint, a Szabadkai M szaki Szakf iskola, els sorban a fiatal generáció tudományos teljesítményének köszönhet en, Szerbia legjobban rangsorolt szakf iskolája, a szerbiai fels oktatási rangsorban:

12-ik

pozíciót található. A ranglista megtekintet a következ web címen:

<http://www.webometrics.info/en/Europe/Serbia>.

1997-2000 között a szabadkai:

„Neuro-Fuzzy-Genetic Intelligent Control Research Center”,

Európában regisztrált, ERUDIT tag, vezetje.

2010-t 1 a Szegedi Tudományegyetemen,

„European Robotics Research Network”

rendszerébe tartozó:

Laboratory of Robotics

koordinátora.

1996-ban internet kapcsolatot létesített a Szabadkai M szaki F iskolán, 1997-ben beindította a F iskolán a mérnök informatikusképzést (szerb és magyar nyelven). A Szabadkai fels oktatási testület alelnöki tisztségét töltötte be.

1978 - 1982 között Az Újvidéki Egyetem, Müszaki Karának, gépészmeérn ki szakán, a F iskolán kihelyezett tagozatát vezette (a 3-ik évfolyamra beiratkozott (F iskolát végzett) hallgatók közül 40 hallgató szerzett oklevelet (okleveles gépészmeérnök)).

A Szabadkai M szaki F iskolán/Szakf iskolán 2000-t 1 az Informatikai Intézetet, majd 2004-t 1 2011-ig, mint tanszékvezet, az Informatikai Tanszéket vezette.

Nyelvismerete:

- angol középfokú, 1991 Oxford (St. Joseph's Hall),
- német középfokú,
- szerb és horvát fels fokú.

Külföldi tanulmányutak:

- Németország, Aachen University, 1986, 30 nap.
- Anglia, University of Salford, 1992, 30 nap.
- University of Maribor, 2005, Szlovénia, 2 hét.
- Németország, University of Ilmenau, 2005, 2 hét.

Vendégkutatói meghívásai:

- október, 2009, University of Applied Sciences, Berlin, Németország.
- december, 2009, Institute Jozef Stefan, Ljubljana, Szlovénia.
- március, 2010 Belgrádi Tudományegyetem, Szerbia.
- április 2010, Újvidéki Tudományegyetem, Szerbia.

Kitüntetés, szakmai elismerés:

- Jugoszláv informatikai szakértő.
- Bánki Donát/Budapesti Műszaki Főiskola: címzetes főiskolai tanár, 1999-.
- Életrajza megjelent a Marquis „Who's Who in the World” 1997 kiadványban.
- Az UNESCO-t képviseli Svájcban, Lausanne, 18th International Symposium on Industrial Robots, 1988.

DAAD Mechatronics, Németország, University of Ilmenau, 2003-2005

- Mint bíráló, a műszaki és informatikai tudományok területén a Szerb Akkreditációs Bizottság tagja, 2006-.
- Az American Biographical Institute részéről elnyerte az „Év embere 1997” (Man of the Year 1997) és az „Év embere 2011” (Man of the Year 2011) címeket.
- 2009-től a Belgrádi Egyetem 'Institute Mihajlo Pupin' kutatóintézetének kutatóprofesszora, <http://www.pupin.rs/RnDProfile/people.html>
- 2009 Annual Award – éves díj nanorobotok témakörből, a XII-ik ICDQM – 2009 nemzetközi konferencián, Belgrád 2009 június 25-26.
- 2013. november 27-től a Magyar Mérnökakadémia rendes tagja.

Dr. Mester Gyula 1975 óta foglalkozik tudományos kutatómunkával. Tudományometriai adatai a következők:

248 tudományos közleményt jelentett meg,
publikációira **502** közleményben hivatkoztak,
h indexe: **12**,
g indexe: **13**,
i10 indexe= **13**.

Tudományometriai adatai alapján (tudományos közlemények száma, idézetei száma, h index, g index és i10 index) Dr. Mester Gyula Szerbia legjobb 5 robotikusa közzé tartozik.

2009-2013 között **négy Springer könyvben** írt könyvfejezetet.

Tudományos közleményeit és hivatkozásait felvitte a Magyar Tudományos Művek Tárába.

Kutatási témakörei:

- Rugalmas csuklójú merev szegmensű ipari robotok.
- Kerekben gördülő intelligens autonóm mobil robotok.
- Humanoid robotok.
- Robotszerű helikopterek,
- Mikro- és nanorobotok.
- Adaptív irányítások.
- Fuzzy rendszerek.

- Neurális hálózatok.
- Genetikus algoritmusok.
- Intelligens rendszerek.

Dr. Mester Gyula szerepvállalása **doktori iskolák m ködtetésében, doktorképzésben:**

1. Szegedi Tudományegyetem, Informatika Doktori Iskola

PhD hallgatói: Szépe Tamás, 2008-2011, abszolvált: 2011. Pintér Róbert, 2007-2009.

Posztdoktor kutatója:

Prof. Dr. Sci. Samy Farid Mohamed Assal, 2010-2011, 2006-ban Japánban doktorált robotika téma körb 1 és az egyptomi Tanta Egyetemen (Aleksandria) dolgozik.

Tárgyel adó négy tárgyban. **Doktori kurzusai:**

1. Kerekeken gördül mobil robotok.
2. Humanoid robotok.
3. Vízi robotok.
4. Mikro- és nanorobotok.

Három doktori témaban témavezet :

1. Kerekeken gördül mobil robotok ütközésmentes irányítása ismeretlen változó környezetben.
2. Humanoid robotok ütközésmentes irányítása ismeretlen változó környezetben.
3. Robotszer helikopter irányítása.
4. Négy rotoros autonóm robothelikopter modellje, ütközésmentes navigációja, pályatervezése és irányítása.

2. Óbudai Egyetem, Biztonság tudományi Doktori Iskola

Tárgyel adó két tárgyban. **Doktori kurzusai:**

- Intelligens robotok,
- Autonóm robothelikopterek ütközésmentes irányítása.

Egy doktori témaban témavezet :

1. Négy rotoros autonóm robothelikopter modellje, ütközésmentes navigációja, pályatervezése és irányítása.

Részvétel doktori bizottságokban:

1. Zrínyi Miklós Nemzetvédelmi Egyetem, Katonai M szaki Doktori Iskola, Budapest, 2009. Kucsra Péter, 'Autonóm m k dés szárazföldi robotok védelmi célú alkalmazása', PhD értekezés, bíráló bizottsági tag.
2. Újvidéki Tudományegyetem, 2011. Piroska Stani Molcer, 'Integrated Component of Digital Signal Processing Education System implemented in Network Environment', 'Integrirana komponenta sistema u enja digitalne obrade signala implementirana u mrežnom okruženju', PhD értekezés, bíráló bizottsági tag.
3. Anna University-Chennai, Tamilnadu, India, 2014. S. Albert Alexander, "Certain Investigations on Power Quality Improvement Techniques for a Solar Fed Cascaded Multilevel Inverter", PhD Thesis, for thwe award of PhD Degree, external examiner.
4. Anna University-Chennai, Tamilnadu, India, 2013. A, Satheesh "Certain Investigations on Power System Voltaage Stability and Power Loss Minimization Employing Intelligenet Techniques and Facts Controllers". PhD Thesis, for thwe award of PhD Degree, external examiner.

5. Anna University, Chennai, Tamil Nadu, India, 2013.
„Intelligent Control of Robot Manipulators Using Soft Computing Techniques”
V. Chandrasekaran, PhD Thesis, for thwe award of PhD Degree, external examiner.
6. Anna University, Chennai, Tamil Nadu, India, 2013.
E. Mariappane, “Application of Bacteria Foraging Algorithm for Power System Problems”, PhD Thesis, for thwe award of PhD Degree, external examiner.
7. Anna University, Chennai, Tamil Nadu, India, 2013.
S. Rajan, „Stability and Stabilization of Linear Time Invariant System Using Marden Table”, PhD Thesis, for thwe award of PhD Degree, external examiner.
8. ,Department of Electrical and Electronics Engineering at P.A. College of Engineering and Technology, India, 2012.
M. Sathiskumar, „Radial Distribution Network Reconfiguration and Phase Balancing Through Hybrid Heuristic Techniques”, PhD Thesis, for thwe award of PhD Degree, external examiner.
9. Department of Electrical Engineering, Annamalai University, India, 2011.
R. K. Shanthi, ’Soft Computing Techniques Applied to Power System Economics’, PhD Thesis, for thwe award of PhD Degree, external examiner.
10. Department of Electrical and Electronics Engineering, Info Institute of Engineering, Coimbatore, India. India, 2009.
S. Thiruvenkadam, ’Web Application for Radial Distribution Network Reconfiguration Through Hybrid Heuristic Techniques’, PhD Thesis, for thwe award of PhD Degree, external examiner.
11. Department of Electronics and Computer Engineering, Indian Institute of Technology Roorke, India, 2009.
Srinivasan A.,’Intelligent Control of Robot Manipulators Using Soft Computing Techniques’, PhD Thesis, for thwe award of PhD Degree, external examiner.

Dr. Mester Gyula összesen 35 tudományos projektben vett részt, mint projektvezet , témavezet vagy kutató.

Projektvezet :

1. "Istraživanje i razvoj optimalnog reda elektromehani kih prenosnika na bazi komponovanja zajedni kih elemenata", SZNRV, 1981-85. god.
2. "Istraživanje kompleksnog ispitivanja kvaliteta elektromehani kih prenosnika",1986-1987. god.
3. "Istraživanje vibracija i šumnosti elektromotora srednjih i velikih snaga", 1987-1988. god.
4. "Istraživanje i razvoj sistema savremenih elektromehani kih prenosnika", 1986-1990. god.
5. "Istraživanje i razvoj savremenih pogonskih sistema", 1991.-1993.god.
6. "Nova metodologija prora una, projektovanja i optimizacije jednofaznih kaveznih asinhronih motora za regulisane elektromotorne pogone", 1993-2000. god.
7. „Intelligens rendszerek fuzzy modellezése és irányítása”, MTA, Arany János Közalapítvány, Budapest, 2001.
8. Internet technológiák, MTA, Arany János Közalapítvány, Budapest, 2002.

Témavezet /kutató:

1. „Matemati ke strukture, modeli i njihova primena”, SzNR Srbije, 1975 – 1980.
2. "Izbor optimalne varijante hidrauli nog servosistema u okviru primene u mašinogradnji", SzNRV,1979-1980. god.

3. "Neki problemi oscilacija zup astih prenosnika sa elektromotornim pogonom", SzNRV, 1979-1980. god.
4. "Izbor optimalne varijante hidrauli nog servosistema u alternaciji sa volumetrijskom regulacijom frekvencije izvršnog organa", SzNRV, 1980-1981. god.
5. "Istraživanje algoritma upravljanja sistema sa vremenski promenljivim parametrima primenom hibridnog ra unara.", SzNRV, 1979-1981. god.
6. "Istraživanje uticaja neuravnoteženosti rotora elektromotora na vibracije elektromehani kih prenosnika u nekim uslovima eksploatacije", SzNRV, 1980-1981. god.
7. "Istraživanje u oblasti projektovanja elektromehani kih prenosnika pri uticaju prinudnih nelinearnih parametarskih oscilacija", SzNRV, 1980-1981. god.
8. "Istraživanje algoritma upravljanja sistema sa vremenski promenljivim parametrima primenom hibridnog ra unara", 1980-1981. god.
9. Mehani ki sistemi i njihova primena, Matemati ki Institut, Beograd, 1981-1982.
10. "Istraživanje uticaja najnepovoljnijih vidova optere enja od gonjene mašine na naprezanje prenosnih elemenata elektromehani kih prenosnika", SzNRV, 1981-1982. god.
11. "Istraživanje u oblasti projektovanja dinami ko optere enih temelja elektromehani kih prenosnika", SzNRV, 1981-1985. god.
12. „Istraživanje u oblasti bezbednosti saobracaja – uzroci stradanja pešaka i biciklista u SAP Vojvodini”, SzNRV, 1981-1985. god.
13. "Istraživanje uticaja mehani kih spojnica na pogonski sistem", 1986-1988. god.
14. "Digitalna simulacija sopstvenih vrednosti pogonskog sistema", 1986-1988. god.
15. "Istraživanje uticaja radnih mašina na pogonski sistem", 1986-1990. god.
16. "Razvoj softverskog paketa za digitalnu simulaciju dinamike pogonskog sistema", 1986-1990. god.
17. "Istraživanje dinamike elektromotora u pogonskom sistemu", 1986-1990. god.
18. " Istraživanje i razvoj pogonskih sistema industrijskih robota sa elasti nim zglobovima", 1991-1993. god.
19. Távoktatási képzési csomag kidolgozása a Szegedi Tudományegyetem, Szegedi Élelmiszeripari Főiskolai Karán, SZTE-SZÉF, Szeged, 2002-2003.
20. Distant Learning, University of Novi Sad, Mihajlo Pupin Faculty of Engineering, 2002-2003.

Elnyert tudományos pályázatai az utóbbi években:

1. DF e-tananyag, Apertus Közalapítvány, Budapest, 2004.
2. Mechatronics, 2002-2006, participants.
3. FP-7 Prosense, 2008-2010, supervisor.
4. Tudásszint kiegynlít , rövid ciklusú e-Learning kurzusok kifejlesztése, 2007, participants.
5. Sensor Network Based Data Collection and Information Processing, sub-project: Intelligent Mobil Robots, 2009-2011, sub-project leader.
6. Mechedu, IPA, 2010-2011, participants.
7. Development of Anthropomorphic Robotic Platform for Socially Acceptable and Adequate Interaction in Human's Working Environment, 2011-2014, participants.

M szaki alkotás

1. Mester Gyula, „Metoda suksesivnih aproksimacija za približno određivanje frekvencije glavnih oblika oscilacija sistema sa više stepeni slobode kretanja“, Univerzitet u Beogradu, Mašinski Fakultet, Beograd, 1974.
2. Mester Gyula, „Primena Hamiltonovog principa za izvodjenje diferencijalnih jednačina različitih problema oscilovanja elastičnih tela“, Univerzitet u Beogradu, Mašinski Fakultet, Beograd, 1974.
3. Mester Gyula, "Stručna ekspertiza u međunarodnom sporu Sever-SEW", Szabadka, 1982.
4. Mester Gyula, "Idejni projekat spoljašnjeg transporta fabrike Aluminijum-ambalaže u Subotici" Szabadka, 1978.
5. Mester Gyula..., "Sanacija temelja kondenzatora TE Nikola Tesla, B", Obrenovac, 1985.
6. Mester Gyula..., "Nostrifikacija projektne dokumentacije krana GANZ MHD", Budapest, 1985.
7. Mester Gyula, "Istraživanje i razvoj novog reda elektromehanika prenosnika", Sever, Szabadka, 1985.
8. Mester Gyula..., "Sanacioni elaborat temelja moto-reduktora", Törökkanizsa, 1985.
9. Mester Gyula..., "Dinamička analiza ramovskog temelja kompresora snage 5.5 MW", Zorka-Azotara, Szabadka, 1986.
10. Mester Gyula..., "Nostrifikacija projektne dokumentacije krana GANZ MHD", Budapest, 1986.
11. Mester Gyula..., "Izveštaj o merenju nivoa vibracija posle sanacije", Törökkanizsa, 1986.
12. Mester Gyula, "Prikaz softverskog paketa DINPOS". Hannover Messe, Németország, 1988.
13. Mester Gyula..., "Razvoj softverskog paketa za simulaciju dinamike pogonskog sistema", Szabadka, 1990.
14. Mester Gyula..., "Razvoj softverskog paketa ADAPTSIM za simulaciju adaptivnog upravljanja robota sa elastičnim zglobovima". Szabadka, 1993.
15. Mester Gyula, Razvoj e-Learning sadržaja u LAMP okruženju, Szabadka, 2004.

Dr. Mester Gyula tagsága tudományos szervezetekben:

- Technical Committee on Computational Cybernetics within System, Man and Cybernetics Society, 2014-, http://conf.uni-obuda.hu/SMC_TC_CC/.
- Magyar Tudományos Akadémia köztestületi tag, 2000-.
- MTA Szegedi Bizottság Mérnöki Szakbizottsági tag,
- Magyar Robottechnikai Társasági tag, 1993-2002.
- Neumann János Számítógép-tudományi Társaság, John von Neumann Computer Science Society, Robotika Szakosztály tag, 2014-.
- Magyar Fuzzy Társaság, Hungarian Fuzzy Association tag, 2014-.
- The New York Academy of Sciences tag, 1994-.
- Pannon Applied Mathematics and Mechanics, PAMM tag, 1982-2000.
- Gesellschaft für Angewandte Mathematik und Mechanik, GAMM tag, 1982-1988.
- International Federation for the Promotion of Mechanism and Machine Science, IFToMM tag, 1974-1991.
- Yugoslav Society of Mechanics tag, 1974-1991.
- Vajdasági Mechanikai Társaság titkára, 1980-82.
- Vajdasági Magyar Mérnökök Egyesületének tagja, 2014-.
- Vajdasági Magyar Tudományos Társaság tagja, 2007-.

- Magyar Mérnökakadémia rendes tagja, 2013-.

- Magyar Tudományos Akadémia, M szaki Tudományok Osztálya, Automatizálási és Számítástechnikai Tudományos Bizottság tagja, 2012-.

- DAAAM International Vienna tagja, 2014-.

Dr. Mester Gyula szerkeszt bizottsági tagsága és tisztségei tudományos folyóiratoknál:

1. Business Systems Research, Zagreb, Member of Advisory Board, 2013-, www.bsrjournal.org.
2. Acta Polytechnica Hungarica, Budapest, Associate Editor, 2010-, <http://www.uni-obuda.hu/journal/>.
3. IPSI BgD Transactions on Internet Research, New York, Frankfurt, Tokyo, Belgrade, Guest Editor: Special Issue, Intelligent Service Robotic Systems, Volume 8, Number 2, ISSN 1820 – 4503, 2012.
4. IPSI BgD Transactions on Internet Research, New York, Frankfurt, Tokyo, Belgrade, Member of Editorial Board, 2010-,
5. IPSI BgD Transactions on Advanced Research, New York, Frankfurt, Tokyo, Belgrade, Member of Editorial Board, 2010-,
6. Bulletins for Applied Mathematics, Budapest, Member of Editorial Board, 1986-2000.
7. Acta Technica Corviniensis – Bulletin of Engineering, Hunedoara, Scientific Committee & Advisory Board Member, 2010-,
8. Annals Faculty Engineering Hunedoara – International Journal of Engineering, Romania, Scientific Committee & Advisory Board Member, 2010-,
9. Journal Interdisciplinary Description of Complex Systems - INDECS, ISSN 1334-4684, Advisory Board Member, Zagreb, 2013-,
10. - Interdisciplinary Description of Complex Systems, <http://indecs.eu/>, Guest Editor 2015-.
11. M szaki tudományos Füzetek, International DAAAM, VII-XIII, Tudományos Bizottsági tag, Kolozsvár, 2002-2008.
12. FM Transactions, University of Belgrade, Faculty of Mechanical Engineering, Member of Editorial Board, Belgrade, 2015-.

A következő tudományos folyóiratok bírálója:

1. Interdisciplinary Description of Complex Systems, 2014-, <http://indecs.eu/>
2. Journal of Aerospace Engineering, 2013-, <http://www.aeroespacial.org.br/jaes/>
3. International Journal of Advanced Robotic Systems, 2013-, http://www.intechopen.com/journals/international_journal_of_advanced_robotic_systems
4. Journal of Robotics, Hindawi Publishing Corporation, 2012-, <http://www.hindawi.com/journals/jr/>
5. Sensors - Open Access Journal, Basel, Switzerland, 2012-, <http://www.mdpi.com/journal/sensors>
6. Acta Polytechnica Hungarica, Budapest, Hungary, 2012-, <http://www.uni-obuda.hu/journal/>.
7. Intelligent Systems: Models and Applications, Springer-Verlag, 2012-, <http://www.springer.com/engineering/computational+intelligence+and+complexity/book/978-3-642-33958-5>
8. Journal of Inequalities and Applications, Springer 2012-, <http://www.journalofinequalitiesandapplications.com/>
9. Journal of Mechanical Engineering, Strojníški vestnik, 2012, <http://ojs.svjme.eu/index.php/svjme>.
10. Robotics and Computer Integrated Manufacturing, Elsevier 2012-, <http://www.journals.elsevier.com/robotics-and-computer-integrated-manufacturing/>

11. Annals Faculty Engineering Hunedoara – International Journal of Engineering, 2012-,
<http://annals.fih.upt.ro/>
12. Acta Technica Corviniensis – Bulletin of Engineering, Hunedoara, 2012-, <http://acta.fih.upt.ro/>
13. International Journal of Electrical and Computer Engineering Systems (IJECEs), 2012-,
<http://www.etfos.unios.hr/ijeces/index.php/ijeces>
14. IPSI BgD Transactions on Internet Research, 2012-, <http://vipsi.org/ipsi/journals/>
15. IPSI BgD Transactions on Advanced Research, 2012-, <http://vipsi.org/ipsi/journals/>
16. International Journal of Automation and Control, 2009-, <http://www.inderscience.com/jhome.php?jcode=IJAC>
17. Maintenance and Reliability, The Polish Academy of Sciences Branch in Lublin and The Polish Maintenance Society (Warsaw), 2014-, <http://www.ein.org.pl/>
18. Measurement, the Journal of the International Measurement Confederation, Elsevier, 2014-,
<http://www.journals.elsevier.com/measurement/>
19. FME Transactions, University of Belgrade, Faculty of Mechanical Engineering, 2014-,
<http://www.mas.bg.ac.rs/istrazivanje/fme/start>

A következ konferencia kiadványok bírálója:

1. 13th World Multi-Conference on Systemics, Cybernetics and Informatics: WM-SCI '09 Orlando, Florida, USA, 2009.
2. IECON-2010, the 36th Annual Conference of the IEEE Industrial Electronics Society, 2010, Glendale, AZ, USA.
3. International Symposium on Industrial Electronics, ISIE Bari, 2010, Italy.
4. YUINFO, 2011 – 2012, Kopaonik, Serbia.
5. ICIST, 2012 - 2nd International Conference on Information Society Technology, Kopaonik, Serbia.
6. IBC 2012, Internet & Business Conference, Rovinj, Croatia.
7. The 4th International Conference on Information Technology (ICIT 2013), Amman, Jordan.
8. IEEE Symposium Series on Computational Intelligence IEEE SSCI 2013, Singapore.
9. International Workshop on Advanced Computational Intelligence and Intelligent Informatics (IWACIII), 18-21 October 2013, Shanghai, China.
10. IEEE Symposium Series on Computational Intelligence 2014 (SSCI 2014), Orlando, Florida, USA, December 9-12, 2014.
11. IEEE IES Mecatronics14, 10th France - Japan Congress, 8th Europe - Asia Congress on Mecatronics, Tokyo, Japan, November 27-30, 2014, <http://www.comp.sd.tmu.ac.jp/mecatronics2014/index.html>
12. The 7th International Conference on Information Technology, ICIT 2015, Amman, Jordan, ISSN 2306-6105, May 12-15, 2015.

Dr. Mester Gyula szerepe hazai és nemzetközi, kongresszusok, konferenciák rendezésében:

- 20. Jugoslovenski kongres teorijske i primenjene mehanike, 1993, Kragujevac, szervez bizottsági tag.
- First ECPD International Conference on Advanced Robotics, Intelligent Automation and Active Systems, Athens, Greece, 1995, szekció elnök, el adó.
- International Power Electronics & Motion Control Conference, PEMC'96, 1996, Budapest, szervez bizottsági tag.

- International Panel Conference on Soft and Intelligent Computing, SIC'96 1996, Budapest, nemzetközi szervez bizottsági tag.
 - 5th International Workshop on Robotics in Alpe-Adria-Danube Region, RAAD'96, Budapest, 1996, szekció elnök, el adó.
 - Second ECPD International Conference on Advanced Robotics, Intelligent Automation and Active Systems, Vienna, 1996, szekció elnök, el adó.
- Soft and Intelligent Computing in Control Engineering, SICCE'97, Szabadka, 1997, elnök, plenáris el adó.
- Pannonian Applied Mathematical Meeting, Kassa, 1997, szervez bizottsági tag.
 - PEMC'98 Conference, Prága, 1998, nemzetközi publikációs bizottsági tag.
 - Savremene ra unarske tehnologije 2000, Szabadka, 2000, elnök, plenáris el adó.
 - IEEE 1st Serbian- Hungarian Joint Symposium on Intelligent Systems, SISY 2003, September 19-20, 2004, Subotica, Serbia and Montenegro, szekció elnök, programbizottsági tag, el adó.
 - 20th International Scientific Conference «Information Technology in Education of Informatics, Electrical and Mechanical Engineers», 2004, Szabadka, Jugoszlávia, konferencia kiadvány szerkesztje.
 - IEEE 2nd Serbian- Hungarian Joint Symposium on Intelligent Systems, IEEE SISY 2004, October 1-2, 2004, Subotica, Serbia and Montenegro, programbizottsági tag, el adó.
 - IEEE 3rd Serbian- Hungarian Joint Symposium on Intelligent Systems and Informatics, IEEE SISY 2005, August 31- September 1, 2005, Subotica, Serbia and Montenegro, programbizottsági tag, el adó.
 - IEEE 4th Serbian- Hungarian Joint Symposium on Intelligent Systems and Informatics, IEEE SISY 2006, September 29-30, 2006, Subotica, Serbia, szekció elnök, programbizottsági tag, el adó.
 - International Conference on Intelligent Engineering Systems, INES 2006, London, United Kingdom, 2006, szekció elnök.
 - YUINFO 2007, Kopaonik, szekció elnök, el adó.
 - IEEE 5th International Symposium on Intelligent Systems and Informatics, IEEE SISY 2007, August 24-25, 2007, Subotica, Serbia, Intelligent Robotics I, szekció elnök, programbizottsági tag, el adó.
 - 25th International Conference Science in Practice IEEE SiP 2007, Schweinfurt, programbizottsági tag, el adó.
 - 26th International Conference Science in Practice IEEE SiP 2008, Osijek, programbizottsági tag, el adó.
 - IEEE 6th International Symposium on Intelligent Systems and Informatics, IEEE SISY 2008, September 26-27, 2008, Subotica, Serbia, programbizottsági tag, el adó.
 - 27th International Conference Science in Practice IEEE SiP 2009, Pécs, programbizottsági tag, el adó.
 - World University President Summit, IPSI Conference, Belgrade, 2009, tanácsadó, plenáris el adó.
 - IEEE 7th International Symposium on Intelligent Systems and Informatics, IEEE SISY 2009, September 25-26, 2009, Subotica, Serbia, programbizottsági tag, el adó.
 - International Conference on Computing, Communications and Control Technologies, Invited Session: Intelligent Robot Motion Control in Unstructured Environments, szekciószervez, Orlando, Florida, USA, April 6-9, 2009.

- 28th International Conference Science in Practice IEEE SiP 2010, Szabadka, elnök, f szerkeszt , programbizottsági tag, el adó.
- IEEE 8th International Symposium on Intelligent Systems and Informatics, IEEE SISY 2010, September 10-11, 2012, Subotica, Serbia, programbizottsági tag, el adó.
- YUINFO 2011, Kopaonik, szekció elnök.
- IEEE 9th International Symposium on Intelligent Systems and Informatics, IEEE SISY 2011, September 08-10, 2011, Subotica, Serbia, programbizottsági tag, , el adó.
- Mech Edu, 2011.12.8-10, Szabadka, tudományos bizottsági tag.
- IBC 2012, Internet & Business Conference, Rovinj, Croatia, szervez bizottsági tag, el adó.
- IEEE 10th International Symposium on Intelligent Systems and Informatics, IEEE SISY 2012, September 20-22, 2012, Subotica, Serbia, programbizottsági tag.
- YUINFO 2013, Kopaonik, Serbia, programbizottsági tag.
- ICIST 2013, Kopaonik, Serbia, programbizottsági tag.
- Workshop on Modern Approach to Product Development and Business Improvement, Balatonfüred, 2013, szekcióvezet .
- IEEE 11th International Symposium on Intelligent Systems and Informatics, SISY 2013, September 26-28, 2013, Subotica, Serbia, programbizottsági tag.
- IEEE 12th International Symposium on Intelligent Systems and Informatics, SISY 2014, September 11-13, 2014, Subotica, Serbia, programbizottsági tag.
- International Workshop on Advanced Computational Intelligence and Intelligent Informatics (IWACIII), 18-21 October 2013, Shanghai, China, programbizottsági tag.
- International Workshop on Advanced Computational Intelligence and Intelligent Informatics (IWACIII), 18-21 October 2013, Shanghai, China, szekciószervez : Intelligent Interaction and Visualization,
spec. szekciószervez : Modeling, PathPlanning, Navigation and Autonomous Flight Control of Quadrotor Microcopter
- International Workshop on Advanced Computational Intelligence and Intelligent Informatics (IWACIII), 18-21 October 2013, Shanghai, China, plenáris el adó.
- YUINFO 2014, Kopaonik, Serbia, programbizottsági tag.
- ICIST 2014, Kopaonik, Serbia, programbizottsági tag.
- SISY 2014, IEEE 12th International Symposium on Intelligent Systems and Informatics, 11-13 September, 2014, Subotica, Serbia, programbizottsági tag.
- IEEE Symposium on Robotic Intelligence in Informationally Structured Space (RiiSS 2014) 9-12 December 2014, Orlando, Florida. USA, programbizottsági tag.
- YUINFO 2015, Kopaonik, Serbia, programbizottsági tag.

Mester Gyula közleményeinek és idézeteinek jegyzéke

Jelölések:

MTMT = Magyar Tudományos Művek Tára

WOS - Web of Science, Thomson Reuters

GooSch = Google Scholar

A. Monográfia

- A1. Gyula Mester, Rigid-Link Flexible-Joint Robot Dynamics and Control, Monograph, p. 1-100, Institut of Electro-Mechanical Systems, Subotica, Yugoslavia, 1993. **MTMT/1.0**

B. Monográfiai fejezetek

- B1. **GooSch** Aleksandar Rodic, Gyula Mester, Ivan Stojković, Qualitative Evaluation of Flight Controller Performances for Autonomous Quadrotors, pp. 115-134, Intelligent Systems: Models and Applications, Endre Pap (Ed.), Topics in Intelligent Engineering and Informatics, Vol. 3, Part. 2, TIEI 3, ISSN 2193-9411, e-ISSN 2193-942X, ISBN 978-3-642-33958-5, e-ISBN 978-3-642-33959-2, DOI 10.1007/978-3-642-33959-2_7, Springer-Verlag Berlin Heidelberg, http://link.springer.com/chapter/10.1007/978-3-642-33959-2_7, 2013. **MTMT/0.4**

c1⁽¹⁾ Josip Stepanić, Josip Kasać, Jelena Čosić Lesičar, What is Taken for Granted about Quadrotors: Remarks about drive and communication, Proceedings of the 3rd International Workshop on Advanced Computational Intelligence and Intelligent Informatics (IWACIII 2013), pp. 1-4, ISSN2185-758X, N. Kubota, Shanghai, China, October 18 to 21 in 2013. “Among a variety of types of UAVs, in this article we restrict the consideration to quadrotors. Quadrotors are the type of UAVs with four propellers, the blades of which function as lift-generating surfaces [3-6]. There are several reasons why groups of UAVs, and consequently group of quadrotors, obtain larger reliabilities in general task conduction than a single UAV [1, 7].” **MTMT**

- B2. **GooSch**, **WOS** link, Gyula Mester, Istvan Matijevics, Tamas Szepe, Janos Simon, Computer Communications and Networks, Application and Multidisciplinary Aspects of Wireless Sensor Networks Concepts, Integration, and Case Studies, Book Chapter 16: Wireless Sensor-Based Robot Control, Part 4, pp. 275-277, Eds: Liljana Gavrilovska; Srdjan Krco; Veljko Milutinovic; Ivan Stojmenovic; Roman Trobec, DOI: 10.1007/978-1-84996-510-1_16, ISBN: 978-1-84996-509-5, © Springer Verlag, London, 2011. **MTMT/0.06**

c1⁽²⁾ Krisztián Lamár, György Morva, Hardware and Software Functions of Standalone Field Data Acquisition Devices for the Low Voltage Power Distribution Grid, Carpathian Journal of Electronic and Computer Engineering Vol. 6, No. 1, pp. 22-27, ISSN 1844 – 9689, 2013. **MTMT**

c2⁽³⁾ Krisztián Lamár, András Gergő Kocsis, Implementation of Brushed DC Motor Control in LabVIEW FPGA, Carpathian Journal of Electronic and Computer Engineering Vol. 6, No. 2, pp. 32-37, ISSN 1844 – 9689, 2013. **MTMT**

c3⁽⁴⁾ Zhenxing Luo, Paul S. Min, and Shu-Jun Liu, Target Localization in Wireless Sensor Networks for Industrial Control with Selected Sensors, International Journal of Distributed Sensor Networks, Volume 2013 (2013), Article ID 304631, 9 pages, DOI:10.1155/2013/304631, <http://dx.doi.org/10.1155/2013/304631>. „In many ICSs, a wireless sensor network (WSN) is laid out to control the robotics [4–6] or to track human motion [7].”, **WOS** link. **MTMT**

c4⁽⁵⁾ Janos Simon, Višekriterijsko neizrazito upravljanje mikroklimom plastenika pomoću autonomne mobilne mjerne stanice, PhD Dissertation, 162 pages, Sveučilište Josipa Jurja Strossmayera u Osijeku, Elektrotehnički Fakultet Osijek, mentor: Goran Martinović, 2013. **MTMT**

c5⁽⁶⁾ Simon jános, Mobil robotok Web 2.0 és Android környezetben, A Magyar Tudomány Napja a Délvidéken 2013, VMTT, pp. 710-721, ISBN 978-86-88077-06-4, Újvidék, Szerbia, 2014.

- B3. **GooSch** Gyula Mester, Piroska Stanic Molcer, Vlado Delic, Educational Games, Computer Games as Educational and Management Tools: Uses and Approaches, Chapter 15, pp. 247-262, DOI: 10.4018/978-1-60960-569-8.ch015, ISBN 978-1-60960-569-8, Information Science Reference, IGI Global, 2011. **MTMT/0.32**

c1⁽⁷⁾ Darko Pekar; Dragiša Mišković; Dragan Knežević; Nataša Vučnović Sedlar; Milan Sečujski and Vlado Delić, Applications of Speech Technologies in Western Balkan Countries (Book chapter), pp. 105-122, Advanced in Speech Recognition (Book), pp. 1-164, 2011, Edited by Noam R. Shabtai, Published by Sciendo, ISBN 978-953-307-097-1, <http://tainguyen.vnu.edu.vn/jspui/handle/123456789/6196>, 2011. „At <http://www.AudioGames.net>, one of the best known web sites with audio games, there are more than 300 audio games and their classification and examples are given in (Mester et al.).” **MTMT**

- c2⁽⁸⁾ Branko Lučić; Nataša Vučnović Sedlar and Vlado Delić, Computer Game Lugram-Version for Blind Children, Telfor Journal, Vol. 3, No. 1, pp. 54-59, 2011., „In developed countries a lot of attention is devoted to the inclusion of people with disabilities and for that reason many educational and entertainment computer audio games have been developed [1], [2].” **MTMT**
- c3⁽⁹⁾ Branko Lučić; Nataša Vučnović Sedlar; Vlado Delić, Računarska igra Lugram - verzija za slepu decu, Telekomunikacioni forum TELFOR 2010, Proceedings of the Telekomunikacioni forum TELFOR 2010, 1173-1176, Srbija, Beograd, novembar 23.-25., 2010. „U svetu se dosta pažnje posvećuje inkluziji osoba sa invaliditetom, te su u sklopu toga razvijene i mnoge kompjuterske audio igre edukativnog i zabavnog karaktera [1], [2].” **MTMT**
- c4⁽¹⁰⁾ Vlado Delić; Milan Sečujski; Nikša Jakovljević; Marko Janev; Radovan Obradović and Darko Pekar, Speech Technologies for Serbian and Kindred South Slavic Languages (Book chapter), pp. 141-164, Advanced in Speech Recognition (Book), 2011, Edited by Noam R. Shabtai, Published by Sciendo, ISBN 978-953-307-097-1, <http://tainguyenso.vnu.edu.vn/jspui/handle/123456789/6196>, 2011. „Besides the applications mentioned in the previous sections, the AlfaNum TTS engine, coupled with the AlfaNum ASR engine, was also used to create new computer games designed for entertainment and education of visually impaired children (Delić & Vučnović Sedlar, 2010; Lučić et al., 2009; Mester et al.).” **MTMT**
- c5⁽¹¹⁾ Branko Lučić; Nataša Vučnović Sedlar and Vlado Delić, Possibilities of application speech technologies in the development of educational software in schools, Proceedings of the 20th Telecommunications Forum TELFOR, pp. 1468 - 1471 , ISBN 978-1-4673-2983-5, DOI 10.1109/TELFOR.2012.6419496, Belgrade, Serbia, 20-22 Nov. 2012. **MTMT**
- c6⁽¹²⁾ Branko Lučić; Molcer P. Stanić; Delic V., Case Study of a Cost-Effective on-line Learning Environment Development for Laboratory Class Enhancement, Elektronika ir Elektrotehnika, Issue: 9, Pages: 73-78, ISSN 1392 – 1215, DOI: 10.5755/j01.eee.115.9.753, 2011, “The formative evaluation will improve a project during the development and implementation phases [15].” **WoS link MTMT**
- c7⁽¹³⁾ Molcer Piroska Stanić; Delic Vlado., Exploring the Effectiveness of Interactive On-line Exercises in Project Accomplishing in the Course: Intelligent Control Systems, International Journal of Engineering Education, Volume: 27, Issue: 2, pp. 257-265, 2011, **WoS link MTMT**
- c8⁽¹⁴⁾ Molcer Piroska Stanić, Integrated component of digital signal processing education system implemented in network environment, Proceedings of the 19th Telecommunications Forum (TELFOR), pp. 675-682, ISBN: 978-1-4577-1499-3, DOI: 10.1109/TELFOR.2011.6143637, Belgrade, Serbia, 22-24 Nov. 2011. **MTMT**
- c9⁽¹⁵⁾ Stantic Molcer Piroska, Integrisana komponenta sistema ucenja digitalne obrade signala implementirana u mrežnom okruzenju, doktorska disertacija, pp. 1-100, Univerzitet u Novom Sadu, Fakultet Tehnickih Nauka, 2011. **MTMT**
- c10⁽¹⁶⁾ Kurbjuhn, Bastian; Kramer, Frederik; Turowski, Klaus, Challenges for Cloud-Based Simulation Games, Published in: 47th IEEE Hawaii International Conference on System Sciences (HICSS), pp. 1251-1257, DOI 10.1109/HICSS.2014.162, Waikoloa, HI, USA, 6-9 Jan. 2014. « For validation concerns on the conceptual site, the feedback of the participants (for instance in form of a survey) [2; 21:254] or during play testing [2] may be substantial for artefact improvements.» **MTMT**

B4. **GooSch WOS**, Gyula Mester, Aleksandar Rodic, Autonomous Locomotion of Humanoid Robots in Presence of Mobile and Immobile Obstacles, Studies in Computational Intelligence, Towards Intelligent Engineering and Information Technology, Part III Robotics, Volume 243/2009, pp. 279-293, ISBN 978-3-642-03736-8, Library of Congress: 2009933683, DOI 10.1007/978-3-642-03737-5, Springer, 2009.

MTMT/0.3

- c1⁽¹⁷⁾ Szepe Tamás, Sensor Based Control of an Autonomous Wheeled Mobile Robot, Proceedings of the PROSENSE 3rd Seminar Ljubljana, pp. 34-35, Slovenia, November 17-21, 2009. **MTMT**
- c2⁽¹⁸⁾ Szepe Tamás, Robotírányítás támogatása távoli érzékelőrendszerrel, VMIT Konferencia, 2009.11.07, Konferenciakiadvány, 2010, pp. 527-532, ISBN 978-86-88077-00-2, Újvidék, Szerbia. **MTMT**
- c3⁽¹⁹⁾ Borovac Branislav; Raković Mirko and Nikolić Milutin, Use of Support Vector Machine for Humanoid Robot Motion Synthesis, Intelligent Service Robotic Systems, Ipsi Journal, Transactions on Internet Research, TIR, Volume 8, Number 2, pp. 18-25, ISSN 1820 - 4503, New York, Frankfurt, Tokyo, Belgrade, <http://internetjournals.net>, 2012. **MTMT**
- c4⁽²⁰⁾ Annamária R. Várkonyi-Kóczy, A Complexity Reduced Hybrid Autonomous Navigation Method for Indoor Robots, Intelligent Service Robotic Systems, Ipsi Journal, Transactions on Internet Research, TIR, Volume 8, Number 2, pp. 32-39, ISSN 1820 - 4503, New York, Frankfurt, Tokyo, Belgrade, <http://internetjournals.net>, 2012.... Nowadays the topic of autonomous navigation has become popular among researchers all over the world (see e.g. [1]). **MTMT**
- c5⁽²¹⁾ Mester G, Intelligent Mobile Robot Motion Control in Unstructured Environments, Acta Polytechnica Hungarica, Vol. 7, No. 4, pp.153-165, ISSN 1785-8860, 2010, **WOS link MTMT**
- c6⁽²²⁾ Gyula Mester, "Modelling of the Humanoid Robot Motion", Ipsi Journal, Transactions on Advanced Research, TAR, New York, Frankfurt, Tokio, Belgrade, Volume 7, Number 1, pp. 21-25 , ISSN 1820 - 4511, 2011. **MTMT**
- c7⁽²³⁾ Ristic-Durrant, D., Grigorescu, S. M., Graser, A., Cojbasic, Z., Nikolic, V., " Robust Stereo-Vision Based 3D Object Reconstruction for the Assistive Robot FRIEND ", Advances in Electrical and Computer

- c8⁽²⁴⁾ Engineering, Volume 11, Issue 4, pp. 15-22 , Digital Object Identifier: 10.4316/AECE.2011.04003, ISSN: 1582-7445, e-ISSN: 1844-7600, Available online: 2011-11-30, 2011, **WOS** link. **MTMT**
- c8⁽²⁴⁾ Gyula Mester, Design of the Fuzzy Control Systems Based on Genetic Algorithm for Intelligent Robots, Interdisciplinary Description of Complex Systems 12 (3), pp. 245-254, 2014, ISSN 1334-4676, DOI: 10.7906/indecs.12.3.4 DOI: 10.7906/indecs.12.3.4
- B5. **GooSch** Gyula Mester, Intelligent Mobil Robot Control in Unknown Environments, Intelligent Engineering Systems and Computational Cybernetics, Part I Intelligent Robotics, pp. 15-26, ISBN 978-1-4020-8677-9, Library of Congress: 2008934137, DOI 10.1007/978-1-4020-8678-6_2, Springer, 2009. **MTMT/0.24**
- c1⁽²⁵⁾ Gincsáne Szadeczky-Kardoss Emese: Real-Time Motion Planning for Nonlinear Nonholonomic Mechatronic Systems Using Time-Scaling, Budapest University of Technology and Economics, Ph.D. Thesis, pages 124, Budapest, Hungary, 2009. **MTMT**
- c2⁽²⁶⁾ Szepe Tamas, Sensor Based Control of on Autonomous Wheeled Mobile Robot, Proceedings of the PROSENSE 3rd Seminar Ljubljana, Institute Joze Stefan, pp. 34-35, Slovenia, November, 17-21, 2009. **MTMT**
- c3⁽²⁷⁾ Szepe Tamas, Robotirányítás támogatása távoli érzékelőrendszerrel, VMIT Konferencia, 2009.11.07, Konferenciakiadvány, 2010, pp. 527-532, ISBN 978-86-88077-00-2, Újvidék, Szerbia. **MTMT**
- c4⁽²⁸⁾ Sandor Csikos, Robot Remote Control Over the Internet, Proceedings of the SIP 2010, 28th International Conference Science in Practice, pp. 41-43, ISBN 978-86-85409-53-0, Subotica, Serbia, June 3-4, 2010. **MTMT**
- c5⁽²⁹⁾ Dusko Katic, Cooperative Multi Robot Systems for Contemporary Shopping Malls, Volume 8, Number 2, pp. 10-17, Intelligent Service Robotic Systems, Ipsi Journal, Transactions on Internet Research, TIR, ISSN 1820 - 4503, New York, Frankfurt, Tokyo, Belgrade, <http://internetjournals.net>, 2012.... The main concept of multi-robot systems for shopping malls is based on the representation of a multi-purpose robotic system for service applications with advanced perception and action capabilities [20-23]. **MTMT**
- c6⁽³⁰⁾ Mester G Intelligent Mobile Robot Motion Control in Unstructured Environments, Acta Polytechnica Hungarica, Journal of Applied Sciences, Vol. 7, No. 4, pp. 153-165, ISSN 1785-8860, 2010. **WOS** link **MTMT**
- c7⁽³¹⁾ Gyula Mester, "Modelling of the Humanoid Robot Motion", Ipsi Journal, Transactions on Advanced Research, TAR, New York, Frankfurt, Tokio, Belgrade, Volume 7, Number 1, pp. 21-25 , ISSN 1820 - 4511, 2011. **MTMT**
- c8⁽³²⁾ Gyula Mester, Aleksandar Rodic, "Sensor-Based Intelligent Mobile Robot Navigation in Unknown Environments", International Journal of Electrical and Computer Engineering Systems, Volume 1, Number 2, pp. 55-62, ISSN: 1847-7003, 2010. **MTMT**
- c9⁽³³⁾ Rudra Anil Kumar, G.Murali Krishna, S.Chandra Sekhar , An Efficient Navigation Test Based Remote Control Strategy, International Journal of Reviews on Recent Electronics and Computer Science, pp. 908-912, IJRRECS, October 2013, Volume 1,Issue 6, ISSN 2321-5461, www.ijrreecs.com , 2013.
„And the above operation takes place in the laboratory based aspect with the particular scenario in a well oriented fashion where the it is ready for the calibration aspect respectively [2][3].” **MTMT**
- c10⁽³⁴⁾ Gyula Mester, Design of the Fuzzy Control Systems Based on Genetic Algorithm for Intelligent Robots, Interdisciplinary Description of Complex Systems 12 (3), pp. 245-254, 2014, ISSN 1334-4676, DOI: 10.7906/indecs.12.3.4 DOI: 10.7906/indecs.12.3.4.
- c11⁽³⁵⁾ Milica Djekic, Cyber rizici po e-tiketing sisteme u sredstvima gradskog prevoza, Tehnika, No. 5, pp. 1-7, 2014.

C. Könyvek, könyvfejezetek

- C1. Gyula Mester, Robotika a felhőkben, Magyar Tudomány Napja a Délvidéken 2014, VMITT, pp., ISBN , Újvidék, Szerbia, 2013.11.15.
- C2. Gyula Mester, Aleksandar Rodic, Négyrotoros robothelikopter modellje és irányítása, A Magyar Tudomány Napja a Délvidéken 2012, VMITT, pp. 469-476, ISBN 978-86-88077-04-0, Újvidék, Szerbia, 2012.11.24.
- C3. Gyula Mester, Robotika, p. 150, ISBN 978-963-279-515-7, Typotex Kiadó, Budapest, 2011. **MTMT/1.0**
- c1⁽³⁶⁾ Simon János, Kézikönyv a robotikai gyakorlatokhoz, Szabadkai Műszaki Főiskola, pp. 1-121, Szabadka, Szerbia, 2011. **MTMT**
- c2⁽³⁷⁾ Simon János, Priručnik za vežbe iz robotike, Szabadkai Műszaki Főiskola, pp. 1-121, Szabadka, Szerbia, 2011. **MTMT**
- C4. Gyula Mester, Internet technológiák, tankönyv, p. 123, Szabadkai Műszaki Szakfőiskola, Szabadka, Szerbia, 2008.
- C5. **GooSch** Gyula Mester, Intelligens Rendszerek, Szegedi Tudományegyetem, p. 166, Szeged, 2001. **MTMT/1.0**
- c1⁽³⁸⁾ Janos Gyeviki, Kalman Rozsahegyi: Sliding Mode Control of a servopneumatic Positioning System

- University of Szeged, College Faculty of Food Engineering Szegedi Tudományegyetem Szegedi Élelmiszeripari Főiskolai Kar, Tudományos Közlemények 24, pp. 65-69, Szeged, Hungary, 2003. **MTMT**
- c2⁽³⁹⁾ Janos Gyeviki Kalman Rozsahegyi: DSP-based Control of a servopneumatic Positioning System. University of Szeged, College Faculty of Food Engineering Szegedi Tudományegyetem, Szegedi Élelmiszeripari Főiskolai Kar, Tudományos Közlemények 24, pp.60-64, Szeged, Hungary, 2003. **MTMT**
- c3⁽⁴⁰⁾ Janos Gyeviki: Nemlíneáris holtidős szabályozási körök vizsgálata. Proceedings of the SZTE, SZÉF, pp. 11-15, Szeged, Hungary, 2003. **MTMT**
- C6. Gyula Mester, Web alkalmazásfejlesztés, tankönyv, p. 112, Szeged Tudományegyetem, Szegedi Élelmiszeripari Főiskolai Kar, Szeged, 2002. **MTMT/1.0**
- C7. Gyula Mester, Intelligens robotok és rendszerek, tankönyv, p. 236, Szabadkai Műszaki Főiskola, Szabadka, Szerbia és Montenegro, 2001. **MTMT/1.0**
- c1⁽⁴¹⁾ Janos Gyeviki, Zoltan Fabulya, Sarosi Jozsef: Fuzzy logika megvalósítása C-nyelven. Szegedi Tudományegyetem Szegedi Élelmiszeripari Főiskolai Kar Tudományos Közlemények, Vol. 22, pp. 40-45, ISSN 02-38-3756, Szeged, Hungary, 2001. **MTMT**
- c2⁽⁴²⁾ Simon János, Kézikönyv a robotika gyakorlathoz, pp. 121, Szabadkai Műszaki Főiskola, Szabadka 2001. **MTMT**
- C8. Gyula Mester, Web programozás, p. 142, Szabadkai Műszaki Főiskola, Szabadka, Szerbia és Montenegro, 2004. **MTMT/1.0**
- c1⁽⁴³⁾ Zlatko Covic, Janos Simon, Tibor Szakall: Egy főiskolai honlap implementációja különböző WEB szolgáltatásokkal, IKT 2005, Informatika Korszerű Technikái konferencia kiadvány, pp. 147-154, Dunaújváros, november 17-18, 2006. **MTMT**
- C9. Gyula Mester, Inteligentni roboti i sistemi, p. 258, Szabadkai Műszaki Főiskola, Szabadka, Szerbia és Montenegro, 2002. **MTMT/1.0**

D. Folyóiratcikkek

- D1. L. Cveticanin, M. Zukovic, Gy. Mester, I. Biro, Comments on the Symmetric and Asymmetric Oscillator With Quadratic Nonlinearity, Mechanics-Research-Communications, Elsevier, pp. 1-22, ISSN: 0093-6413 (in press, Impact Factor: **1.495**) 2015. $1.495/4=0.37375$
- D2. Gyula Mester, Design of the Fuzzy Control Systems Based on Genetic Algorithm for Intelligent Robots, Interdisciplinary Description of Complex Systems, Vol. 12, No. 3, ISSN 1334-4684, DOI: 10.7906/indecs.12.3.4, pp. 245-254, 2014.
- D3. **WoS** link, Livija Cveticanin, Gyula Mester and Istvan Biro, Parameter Influence on the Harmonically Excited Duffing Oscillator, Acta Polytechnica Hungarica, Journal of Applied Sciences, Vol. 11, No. 5, pp. 145-160, ISSN 1785-8860, http://www.uni-obuda.hu/journal/Cveticanin_Mester_Biro_51.pdf, (Impact Factor: **0.471**), Budapest, Hungary, 2014. **MTMT/0.2**
- D4. **GooSch WoS** link, Aleksandar Rodic, Gyula Mester, Sensor-based Navigation and Integrated Control of Ambient Intelligent Wheeled Robots with Tire-Ground Interaction Uncertainties, Acta Polytechnica Hungarica, Journal of Applied Sciences, Vol. 10, No. 3, pp. 113-133, ISSN 1785-8860, http://www.uni-obuda.hu/journal/Rodic_Mester_41.pdf, (Impact Factor: **0.471**), DOI: 10.12700/APH.10.03.2013.3.9, Budapest, Hungary, 2013. **MTMT/0.3**
- c1⁽⁴⁴⁾ Jih-Gau Juang, Chia-Lung Yu, Chih-Min Lin, Rong-Guan Yeh, Imre J. Rudas, Real-Time Image Recognition and Path Tracking of a Wheeled Mobile Robot for Taking an Elevator, Acta Polytechnica Hungarica Vol. 10, No. 6, pp. 5-23, 2013. ‘In recent years, the wheeled mobile robot (WMR) has been frequently discussed in mobile robot researches such as easy control, high-speed mobility, and energy storage capacity [1, 2], which are better than for the legged robot.’ **WoS** link. **MTMT**
- c2⁽⁴⁵⁾ Josip Stepanić, Josip Kasać, Jelena Čosić Lesičar, What is Taken for Granted about Quadrotors: Remarks about drive and communication, Proceedings of the 3rd International Workshop on Advanced Computational Intelligence and Intelligent Informatics (IWACIII 2013), pp. 1-4, ISSN2185-758X, N. Kubota, Shanghai, China, October 18 to 21 in 2013. ‘Among a variety of types of UAVs, in this article we restrict the consideration to quadrotors. Quadrotors are the type of UAVs with four propellers, the blades of which function as lift-generating surfaces [3-6]. There are several reasons why groups of UAVs, and consequently group of quadrotors, obtain larger reliabilities in general task conduction than a single UAV [1, 7].’ **MTMT**
- c3⁽⁴⁶⁾ Masár Marek and Ivana Budinská, Swarm-Based Heuristics for an Area Exploration, pp.219-240, Advances in Soft Computing, Intelligent Robotics and Control, Eds. János Fodor, Robert Fullér, Topics in Intelligent Engineering and Informatics, Volume 8, ISSN 2193-9411, ISBN 978-3-319-05944-0, DOI

- 10.1007/978-3-319-05945-7, Springer Cham Heidelberg New York Dordrecht London, Springer International Publishing Switzerland 2014. **MTMT**
- c4⁽⁴⁷⁾ Josip Stepanic, Gyula Mester, Josip Kasac, Synthetic Inertial Navigation Systems: Case Study of Determining Direction, Proceedings of 57th ETRAN Conference, Editor: Bratislav Milovanovic, pp. RO 2.7., 1-3, Zlatibor, Serbia, June 3-6, 2013. **MTMT**
- c5⁽⁴⁸⁾ Velibor Karanović, Mitar Jocanović, Vukica Jovanović, Review of Development Stages in the Conceptual Design of an Electro-Hydrostatic Actuator for Robotics, Acta Polytechnica Hungarica, Journal of Applied Sciences, Vol. 11, No. 5, pp. 59-79, ISSN 1785-8860, Budapest, Hungary, 2014. "The development of controllers which take into account the dynamics of the entire robotic system, including interaction effects with environment such as slipping, rolling, resistance, etc. [49, 50] must also be considered." **WOS** link. **MTMT**
- c6⁽⁴⁹⁾ Gyula Mester, Design of the Fuzzy Control Systems Based on Genetic Algorithm for Intelligent Robots, Interdisciplinary Description of Complex Systems 12 (3), pp. 245-254, 2014, ISSN 1334-4676, DOI: 10.7906/indecs.12.3.4 DOI: 10.7906/indecs.12.3.4.
- c7⁽⁵⁰⁾ István Bíró, Gusztáv Fekete, Approximate method for determining the axis of finite rotation between two body segments, Acta Polytechnica Hungarica, Vol. , No., pp.1-12, ISSN 1785-8860, 2010, **WOS** link.

D5. GooSch Gyula Mester, Aleksandar Rodic, Modeling and Navigation of an Autonomous Quad-Rotor Helicopter, E-society Journal: Research and Applications, Vol. 3, No. 1, pp. 45-53, ISSN 2217-3269, COBISS.SR-ID 255833863, July 2012. **MTMT/0.2**

- c1⁽⁵¹⁾ Josip Stepanić, Josip Kasać, Jelena Čosić Lesičar, What is Taken for Granted about Quadrotors: Remarks about drive and communication, Proceedings of the 3rd International Workshop on Advanced Computational Intelligence and Intelligent Informatics (IWACIII 2013), pp. 1-4, ISSN2185-758X, N. Kubota, Shanghai, China, October 18 to 21 in 2013. "Among a variety of types of UAVs, in this article we restrict the consideration to quadrotors. Quadrotors are the type of UAVs with four propellers, the blades of which function as lift-generating surfaces [3-6]. There are several reasons why groups of UAVs, and consequently group of quadrotors, obtain larger reliabilities in general task conduction than a single UAV [1, 7]." **MTMT**
- c2⁽⁵²⁾ Josip Stepanić, Gyula Mester, Josip Kasac, Synthetic Inertial Navigation Systems: Case Study of Determining Direction, Proceedings of 57th ETRAN Conference, pp. RO 2.7., 1-3, Zlatibor, Serbia, June 3-6, 2013.

D6. GooSch Gyula Mester, Fuzzy-Logic Sensor-Based Navigation of Autonomous Wheeled Mobile Robots in the Greenhouse Environments, Volume 8, Number 2, pp. 26-31, Intelligent Service Robotic Systems, Ipsi Journal, Transactions on Internet Research, TIR, ISSN 1820 - 4503, New York, Frankfurt, Tokyo, Belgrade, http://internet_journals.net, 2012. **MTMT/0.4**

D7. GooSch, Wos link /Scopus link, Aleksandar Rodic, Gyula Mester, The Modeling and Simulation of an Autonomous Quad-Rotor Microcopter in a Virtual Outdoor Scenario, Acta Polytechnica Hungarica, Journal of Applied Sciences, Vol. 8, Issue No. 4, pp. 107-122, ISSN 1785-8860, <http://www.uni-obuda.hu/journal/Issue30.htm>, (Impact Factor: 0.385), Budapest, Hungary, 2011. **MTMT**

- c1⁽⁵³⁾ Gyula Mester, Aleksandar Rodic, 'Navigation of an Autonomous Outdoor Quadrotor Helicopter', Proceedings of the 2nd International Conference on Internet Society Technologie and Management ICIST , ISBN: 978-86-85525-10-0, pp. 259-262, 1-3.03.2012. **MTMT**
- c2⁽⁵⁴⁾ Johannes Meyer, Alexander Sendobry, Stefan Kohlbrecher, Uwe Klingauf, Oskar von Stryk, „Comprehensive Simulation of Quadrotor UAVs Using ROS and Gazebo”, Simulation, Modeling, and Programming for Autonomous Robots Lecture Notes in Computer Science Volume 7628, pp 400-411, DOI 10.1007/978-3-642-34327-8_36, Print ISBN 978-3-642-34326-1, Online ISBN 978-3-642-34327-8 2012, Springer. **MTMT**
- c3⁽⁵⁵⁾ Precup, R.-E., Haidegger, T., Preitl, St., Benyó, B., Paul, A. S. and Kovács, L., Fuzzy Control Solution for Telesurgical Applications, Applied and Computational Mathematics, Vol. 11, No. 3, pp. 378-397, 2012, **WOS** link. **MTMT**
- c4⁽⁵⁶⁾ Chee, K.Y., Zhong, Z.W., 'Control, Navigation and Collision Avoidance for an Unmanned Aerial Vehicle', Sensors and Actuators A - Physical, Volume 190, pp. 66 – 76, DOI: 10.1016/j.sna.2012.11.017 2013, **WOS** link. **MTMT**
- c5⁽⁵⁷⁾ Aleksandar Rodic, Ivan R. Stojkovic 'Dynamic Inversion Control of Quadrotor with Complementary Fuzzy Logic Compensator', Proceedings of the 2012 11th Symposium on Neural Network Applications in Electrical Engineering (NEUREL), Belgrade, Print ISBN: 978-1-4673-1569-2, INSPEC Accession Number: 13266444, DOI: 10.1109/NEUREL.2012.6419963, pp. 53-58, 20-22 Sept. 2012, 'The Fig. 1. shows the structure model [9] [10] in hovering condition, where all the propellers have the same speed of rotation. For the purpose of testing proposed integrated flight controller the following quadrotor parameters are assumed Table II [9] [10]'. **MTMT**
- c6⁽⁵⁸⁾ Jimoh Pedro, John Ekoru, 'NARMA-L2 Control of a Nonlinear Half-Car Servo-Hydraulic Vehicle Suspension System', Acta Polytechnica Hungarica, pp. 5-26, Vol. 10, No. 4, Budapest, Hungary, 2013, 'Therefore, consideration should be given to include acceptably bounded parametric uncertainty in the

- c7⁽⁵⁹⁾ design of control systems for VSS [4; 9; 26; 27; 28].’ **WOS** link. **MTMT**
 Johanna Sápi, Dániel András Drexler, István Harmati, Annamária Szeles, Bernadett Kiss, Zoltán Sápi and Levente Kovács, ‘Tumor growth model identification and analysis in case of C38 colon adenocarcinoma and B16 melanoma’, Proceedings of the 8th IEEE International Symposium on Applied Computational Intelligence and Informatics, pp. 303-308, DOI 8-1-4673-6400-3/13/\$31.00 ©2013 IEEE, May 23–25, 2013, Timisoara, Romania, „Moreover, other modelling aspects will be investigated similar to [34], [35],[36].” **MTMT**
- c8⁽⁶⁰⁾ MA Lukmana, H Nurhadi - Rancang Bangun Unmanned Aerial Vehicle (UAV) Empat Baling-Baling (Quadrotor Arducopter), Modelling, Identification and Control of a Quadrotor Helicopter. Lund University, digilib.its.ac.id, 2012. **MTMT**
- c9⁽⁶¹⁾ Josip Stepanić, Josip Kasać, Jelena Čosić Lesičar, What is Taken for Granted about Quadrotors: Remarks about drive and communication, Proceedings of the 3rd International Workshop on Advanced Computational Intelligence and Intelligent Informatics (IWACIII 2013), pp. 1-4, ISSN 2185-758X, N. Kubota, Shanghai, China, October 18 to 21 in 2013. “Among a variety of types of UAVs, in this article we restrict the consideration to quadrotors. Quadrotors are the type of UAVs with four propellers, the blades of which function as lift-generating surfaces [3-6]. There are several reasons why groups of UAVs, and consequently group of quadrotors, obtain larger reliabilities in general task conduction than a single UAV [1, 7].” **MTMT**
- c10⁽⁶²⁾ Marijana Despotović-Zrakić, Dušan Barać, Zorica Bogdanović, Branislav Jovanić, Božidar Radenković, Software Environment for Learning Continuous System Simulation, Acta Polytechnica Hungarica, Journal of Applied Sciences, Vol. 11, Issue No. 2, pp. 187-202, ISSN 1785-8860, 2014. **MTMT**
- c11⁽⁶³⁾ Mónica Lucia Abarca Abarca, Hexacóptero (Vehículo Aéreo No Tripulado-UAV) Con Sistema De Medición De Calidad De Aire Y Radiaciones Ionizantes, Tesis, pp. 1-68, Pontificia Universidad Católica Del Perú Facultad De Ciencias e Ingeniería 2014. http://tesis.pucp.edu.pe/repositorio/bitstream/handle/123456789/5362/abarca_monica_hexacoptero_vehiculo_aereo_no_tripulado_calidad_aire_radiaciones_ionizantes.pdf?sequence=1, „De esta forma no se necesita un rotor de cola, como en un helicóptero convencional [13].” **MTMT**
- c12⁽⁶⁴⁾ Nemati, A. ; Kumar, M., Modeling and control of a single axis tilting quadcopter, Proceedings of the American Control Conference (ACC), Publisher: IEEE Conference Publications, pp. 3077 - 3082, ISBN 978-1-4799-3272-6, ISSN 0743-1619, DOI: 10.1109/ACC.2014.6859328, Portland, OR, USA, 4-6 June 2014. „Increasing or decreasing the speeds of all four rotors simultaneously controls the collective thrust generated by the robot [6, 7].”
- c13⁽⁶⁵⁾ Mehdi Zare, Jafar Sadeghi, Said Farahat, Ehsan Zakeri, Regulating and Helix Path Tracking for Unmanned Aerial Vehicle (UAV) Using Fuzzy Logic Controllers, Journal of Mathematics and Computer Science 13, pp. 71-89, 2014. „Two coordinate frames are considered as a reference frames to obtain the dynamic govern equations. One is inertial frame attached to ground (E-frame), and another one is attached to center of mass of the body (B-frame) (figure 2) [26].” **WOS** link.
- c14⁽⁶⁶⁾ Rafael M. J. A. Souza, Gabriela V. Lima, Josué S. Morais, Aniel S. Morais, ‘Desenvolvimento de um Simulador de Quadricopteros em Plataforma Matlab®’, Proceedings of the Conferencia de Estudo em Engenharia Eletrica XII CEEL, ISSN 2178-8303, Universidade Federal de Uberlândia – UFU, Uberlândia – Minas Gerais – Brasil, pp. 1-5, 13-14 Outubro, 2014.
- c15⁽⁶⁷⁾ Gyula Mester, Aleksandar Rodic, Modeling and Navigation of an Autonomous Quad-Rotor Helicopter, E-society Journal: Research and Applications, Vol. 3, No. 1, pp. 45-53, ISSN 2217-3269, COBISS.SR-ID 255833863, July 2012.

D8. **GooSch** Gyula Mester, Aleksandar Rodic, "Contribution to the Simulation of Humanoid Kondo Robot", Annals of Faculty Engineering Hunedoara – International Journal of Engineering, Tome IX, Fascicule 1, pp. 73-78, ISSN 1584 – 2665, <http://annals.fih.upt.ro/pdf-full/2011/ANNALS-2011-1-08.pdf>, 2011. **MTMT/0.2**

- c1⁽⁶⁸⁾ Gyula Mester, Bipedal Walking in Robots, Proceedings of the Európai Kihívások IV. Nemzetközi Tudományos Konferencia, pp. 703-707, ISBN 978-963-482-857-0, Szeged, Hungary, 2007.
- c2⁽⁶⁹⁾ Gyula Mester, „Lépegető humanoid robotok mozgástervezése”, MTA, VMTT konferencia kiadvány, pp.267-273, Novi Sad, Serbia, 2007.
- c3⁽⁷⁰⁾ Gyula Mester, „Dynamic Modeling for a Walking Robot”, Proceedings of the SIP 2008, 26th International Conference SCIENCE IN PRACTICE, pp.87-89, ISBN 978-953-6032-52-4, Osijek, Croatia, 2008.
- c4⁽⁷¹⁾ Mester Gyula, „Kétkalábon járó robot modellezése”, Informatika a felsőoktatásban 2008, konferencia kiadvány, pp. 1-8, ISBN 978-963-473-129-0, Debrecen, 2008.
- c5⁽⁷²⁾ Gyula Mester, „Simulation of Humanoid Robot Motion”, Proceedings of The KANDÓ CONFERENCE, pp. 1-8, ISBN 978-963-7154-74-4, Budapest, 2008.
- c6⁽⁷³⁾ Gyula Mester, Aleksandar Rodic, “Autonomous Locomotion of Humanoid Robots in Presence of Mobile and Immobile Obstacles”, Studies in Computational Intelligence, Towards Intelligent Engineering and Information Technology, pp. 279-293, ISBN 978-1-642-03736-8, Library of Congress: 2009933683, DOI 10.1007/978-3-642-03737-5_20, Springer, 2009.
- c7⁽⁷⁴⁾ Borovac Branislav; Raković Mirko and Nikolić Milutin, Use of Support Vector Machine for Humanoid Robot Motion Synthesis, Intelligent Service Robotic Systems, Ipsi Journal, Transactions on Internet

D9. **GooSch** Gyula Mester, "Academic Ranking of World Universities 2009/2010", Invited Paper, Volume 7, Number 1, pp. 44-47, Ipsi Journal, Transactions on Internet Research, TIR, ISSN 1820 - 4503, New York, Frankfurt, Tokyo, Belgrade, 2011. **MTMT/0.4**

- c1⁽⁷⁵⁾ Rubén González Crespo, Roberto Ferro Escobar, Sandra Janet Velazco, José Antonio Morerio „Propuesta de una Taxonomía y Ontología para clasificación Inteligente de grupos de investigación”, Sociedad y Utopía. Revista de Ciencias Sociales, No. 40, Noviembre de 2012, pp. 18-50, ISSN: 2254-724X2012.” ... Según la publicación realizada por Gyula Mester, (Mester, 2011) propone un análisis del Ranking Académico de Universidades a nivel mundial, según el Institute of Higher Education de Shanghai Jiao Tong University , el Academic Ranking of World de Universidades de ...” **MTMT**

D10. **GooSch** Gyula Mester, "Modelling of the Humanoid Robot Motion", Invited Paper, Ipsi Journal, Transactions on Advanced Research, TAR, New York, Frankfurt, Tokyo, Belgrade, Volume 7, Number 1, pp. 21-25 , ISSN 1820 - 4511, <http://internetjournals.net/journals/tar/2011/January/Paper%2005.pdf> , 2011. **MTMT/0.4**

- c1⁽⁷⁶⁾ Borovac Branislav; Raković Mirko and Nikolić Milutin, Use of Support Vector Machine for Humanoid Robot Motion Synthesis, Intelligent Service Robotic Systems, Ipsi Journal, Transactions on Internet Research, TIR, Vol. 8, No. 2, pp. 18-25, ISSN 1820 - 4503, New York, Frankfurt, Tokyo, Belgrade, <http://internetjournals.net>, 2012. **MTMT**

- c2⁽⁷⁷⁾ Filipe Borges Marra, Vitri de Fava Souza, Thomas Vergutz, Murilo Mendonça Venâncio, Luis Otávio Brás Tenani, Alézio Martins Guimarães, Rogério Sales Gonçalves Fb Marra, Vdef Souza, T Vergutz, Humanoide Edrom Robocup Kidsize 2011, pp. 1-3, <http://www.cbrobotica.org/Humanoid/91354.pdf>. “Detalhes sobre a obtenção do modelo matemático de robôs humanóides podem ser encontrados em Mester (2008), Torres (2006), Barela (2005) e Nogueira (2005).” **MTMT**

D11. **GooSch** Gyula Mester, Aleksandar Rodic, "Sensor-Based Intelligent Mobile Robot Navigation in Unknown Environments", International Journal of Electrical and Computer Engineering Systems, Volume 1, Number 2, pp. 55-62, ISSN: 1847-7003, <http://www.etfos.hr/ijeces/index.php/ijeces/article/view/22>, 2010. **MTMT/0.2**

- c1⁽⁷⁸⁾ Gyula Mester, Intelligent Mobile Robot Controller Design, Proceedings of the Intelligent Engineering Systems, INES 2006, pp. 282-286, ISBN: 0-7803-9708-8, DOI: 10.1109/INES.2006.1689384 London, United Kingdom, 2006.

- c2⁽⁷⁹⁾ Gyula Mester, "Intelligent Mobil Robot Control in Unknown Environments", Intelligent Engineering Systems and Computational Cybernetics, Part I Intelligent Robotics, pp. 15-26, ISBN 978-1-4020-8677-9, Library of Congress: 2008934137, DOI 10.1007/978-1-4020-8678-6_2, Springer, 2009.

- c3⁽⁸⁰⁾ Aleksandar Rodic, Dusko Katic, Gyula Mester, "Ambient Intelligent Robot-Sensor Networks for Environmental Surveillance and Remote Sensing", Proceedings of the IEEE SISY 2009, pp. 39-44, IEEE Catalog Number: CFP0984C-CDR, ISBN: 978-1-4244-5349-8, Library of Congress: 2009909575, DOI 10.1109/SISY.2009.5291141, Subotica, Serbia, September 25-26, 2009.

- c4⁽⁸¹⁾ Aleksandar Rodic, Gyula Mester, "Virtual WRSN – Modeling and Simulation of Wireless Robot-Sensor Networked Systems". Proceedings of the 8th IEEE International Symposium on Intelligent Systems and Informatics, SISY 2010, pp. 115-120, DOI: 10.1109/SISY.2010.5647245, ISBN: 978-1-4244-7394-6, Subotica, Serbia, September 10-11, 2010. **MTMT**

- c5⁽⁸²⁾ Deepak, B.B.V.L. ; Parhi, Dayal R., " Target Seeking Behaviour of an Intelligent Mobile Robot Using Advanced Particle Swarm Optimizatin". Proceedings of the IEEE International Conference on Control, Automation, Robotics and Embedded System CARE, pp. 1-6, DOI: 10.1109/CARE.2013.6733749, ISBN: 978-1-4244-7394-6, Jabalpur, India, 16-18 Dec. 2013. **MTMT**

- c6⁽⁸³⁾ B. B. V. L. Deepak, Dayal R. Parhi, B. M. V. A. Raju" Advance Particle Swarm Optimization-Based Navigational Controller For Mobile Robot", Arabian Journal for Science and Engineering, pp. 1-11, DOI: 10.1007/s13369-014-1154-z, Print ISSN 1319-8025, Online ISSN 2191-4281, Publisher Springer Berlin Heidelberg, 03 June 2014, <http://link.springer.com/article/10.1007/s13369-014-1154-z>. “Recently, Mester and Rodic [23] have explained a sensor-based intelligent mobile robot navigation in unknown environments. They used Fuzzy Inference System for generating obstacle collision free trajectories within robotic work space. A simulation result of their approach is shown in Fig. 12a regarding the goal seeking and the obstacle avoidance mobile robot paths.”

- c7⁽⁸⁴⁾ B.B.V.L. Deepak, Dayal R. Parhi,Target Seeking Behaviour of an Intelligent Mobile Robot Using Advanced Particle Swarm Optimization, Proceedings of the International Conference on Control, Automation, Robotics and Embedded systems (CARE), pp. 1-6, DOI: 978-1-4673-6153-8/13/\$1.00@2013 IEEE, 2013.

D12. **GooSch WoS** link, Gyula Mester, Intelligent Mobile Robot Motion Control in Unstructured Environments, Acta Polytechnica Hungarica, Journal of Applied Sciences, Vol. 7, Issue No. 4, ISSN 1785-8860, pp. 153-165, http://bmf.hu/journal/Mester_25.pdf, (Impact Factor: 0.284), Budapest, Hungary, 2010. **MTMT/0.6**

- c1⁽⁸⁵⁾ Yi-Jen Mon, Chih-Min Lin, Imre J. Rudas, ANFIS-based Wireless Sensor Network (WSN) Applications for Air Conditioner Control, *Acta Polytechnica Hungarica* Vol. 10, No. 3, pp. 5-16, ISSN 1785-8860, 2013, “Alliance to develop standards for costeffective and low-power consumption WSNs [2-10]. These networks topologies are star, tree and mesh network topologies, which are provided by a framework of application programming interfaces (API) in the application layer [2-10].” **MTMT**
- c2⁽⁸⁶⁾ Gyorgy Csaba; Laszlo Somlyai, Zoltan Vamossy, Mobile Robot Navigation in Unknown Environment Using Structured Light, Proceedings of the 3th IEEE International Symposium on Logistics and Industrial Informatics (LINDI), pp. 249-254, ISBN 978-1-4577-1842-7, DOI 10.1109/LINDI.2011.6031158, Budapest, Hungary, 25-27 August, 2011 ‘The autonomous operation has two main problems, perception of the environment and planning the root [1] [2] [3]’. **MTMT**
- c3⁽⁸⁷⁾ Sinean, A., Preitl, S., Precup, R., Dragos, C., Radac, M., Petriu, E.M., State feedback fuzzy control solution for BLDC drives, Proceedings of the 12th IEEE International Symposium on Computational Intelligence and Informatics (CINTI), pp. 85-90, Budapest, ISBN: 978-1-4577-0044-6, DOI: 10.1109/CINTI.2011.6108477, 21-22 Nov. 2011. **MTMT**
- c4⁽⁸⁸⁾ Gyorgy Csaba, Laszlo Somlyai, Zoltan Vamossy, Differences between Kinect and Structured Lighting Sensor in Robot Navigation, Proceedings of the 2012 IEEE 10th International Symposium: Applied Machine Intelligence and Informatics (SAMI), pp. 85-90, ISBN: 978-1-4577-0196-2, DOI: 10.1109/SAMI.2012.6208934, Herl'any, 26-28 January 2012, ‘After the navigation can be visible the path [4], [5], [6]. **MTMT**
- c5⁽⁸⁹⁾ János Botzheim, Yuichiro Toda, Naoyuki Kubota, Bacterial memetic algorithm for offline path planning of mobile robots, *Memetic Comp.* (2012) 4, pp.73–86, DOI 10.1007/s12293-012-0076-0, 2012, ‘For its practical importance many approaches have been suggested in the literature based mainly on evolutionary computation [2,15,19,21,26,35–37,40–42]’. **MTMT**
- c6⁽⁹⁰⁾ Radu-Emil Precup, Marius-Lucian Tomescu, Emil M. Petriu, Stefan Preitl, Claudia-Adina Dragoş, Stable Design of a Class of Nonlinear Discrete-Time MIMO Fuzzy Control Systems, *Acta Polytechnica Hungarica* Vol. 9, No. 2, pp. 57-76, 2012, ‘Furthermore, the stability analysis method is formulated here so as to be well suited for T-S FC designs dedicated to a wide class of nonlinear processes [16][26].’, **WoS** link. **MTMT**
- c7⁽⁹¹⁾ Chen-Yuan Chen, Bih-Yaw Shih, Chia-Hung Shih, Li-Hui Wang, Human-machine interface for the motion control of humanoid biped robots using a graphical user interface Motion Editor, *Journal of Vibration and Control*, DOI: 10.1177/1077546312437804, February 23, 2012, **WoS** link. **MTMT**
- c8⁽⁹²⁾ Janus S. Liang, Kuo-Ming Chao and Paul Ivey, VR-based wheeled mobile robot in application of remote real-time assembly, *International Journal of Advanced Manufacturing Technology*, DOI: 10.1007/s00170-012-4140-1, 2012, **WoS** link **MTMT**
- c9⁽⁹³⁾ Gyorgy Csaba, Zoltan Vamossy, Fuzzy Based Obstacle Avoidance for Mobil Robots with Kinect Sensor , Poceedings of the 4th IEEE International Symposium on Logistics and Industrial Informatics (LINDI), pp. 135-144, ISBN: 978-1-4673-4520-0, DOI: 10.1109/LINDI.2012.6319476, 5-7 September, 2012, ‘Article [8] describes a wireless, automated control system for avoiding obstacles. The two-wheel driven mobile robot can navigate in an unknown environment using a fuzzy method based on nine rules’, **WoS** link. **MTMT**
- c10⁽⁹⁴⁾ Simon Janos, Istvan Matijevics, Remote Control of Anthropomorphic Robotic Platform for Socially Acceptable and Adequate Interaction in Human’s Working Environment, Proceedings of the SIP 2012, 30th International Conference Science in Practice, pp. 103-107, ISBN 978-963-7298-53-0, Pécs, Hungary, October 29-30, 2012. **MTMT**
- c11⁽⁹⁵⁾ Tafa Zhilbert, Milutinovic Veljko, Detectability of Static and Moving Targets in Randomly Deployed Military Surveillance Networks, *Ad Hoc & Sensor Wireless Networks*, Volume: 13, Issue: 3-4, pp. 291-312, 2011, **WoS** link **MTMT**
- c12⁽⁹⁶⁾ Pozna Claudiu, Precup Radu-Emil, Aspects Concerning the Observation Process Modelling in the Framework of Cognition Processes, *Acta Polytechnica Hungarica*, Budapest, Hungary, Volume: 9, Issue: 1, Special Issue: SI pp. 203-223, 2012, **WoS** link. **MTMT**
- c13⁽⁹⁷⁾ Md. Abdullah Al Ahsan, SK Alamgir Hossain, Ahsan Ullah Siddiquee, Md. Mahbubur Rahman, Obstacles invariant navigation of An Autonomous Robot based on GPS, Proceedings of the 15th International Conference on Computer and Information Technology (ICCIT), pp. 524-532, ISBN: 978-1-4673-4833-122-24, DOI 10.1109/ICCI.Techn.2012.6509782, Chittagong, Bangladesh, 22- 24 Dec. 2012. ‘Autonomous robots [1] are robots that can perform desired tasks in unstructured environments [2] without continuous human guidance [3], [4].’ **MTMT**
- c14⁽⁹⁸⁾ Aleksandar Rodic, Gyula Mester, Sensor-based Navigation and Integrated Control of Ambient Intelligent Wheeled Robots with Tire-Ground Interaction Uncertainties, *Acta Polytechnica Hungarica*, *Journal of Applied Sciences*, Vol. 10, No. 3, pp. 113-133, http://www.uni-obuda.hu/journal/Rodic_Mester_41.pdf, (impakt faktor: 0.588), DOI: 10.12700/APH.10.03.2013.3.9, Budapest, Hungary, 2013, **WoS** link. **MTMT**
- c15⁽⁹⁹⁾ Livija Cveticanin, Gyula Mester and Istvan Biro, Parameter Influence on the Harmonically Excited Duffing Oscillator, *Acta Polytechnica Hungarica* Vol. 11, No. 5, pp. 145-160, Budapest, Hungary, 2014. ‘Using the theoretical consideration of the excited vibration of non-linear systems, it is to be expected

that the obtained results have to be highly repeatable and to satisfy certain rules (see [1]-[13] and References mentioned in them.)"

http://www.uniobuda.hu/journal/Cveticanin_Mester_Biro_51.pdf, WoS link. MTMT

- c16⁽¹⁰⁰⁾ István Nagy, From Exploring to Optimal Path Planning: Considering Error of Navigation in Multi-Agent Mobile Robot Domain, Acta Polytechnica Hungarica Vol. 11, No. 6, pp. 39-55, Budapest, Hungary, 2014. "In the research field of mobile-robot systems, a large amount of papers have been published related to intelligent navigation or parking systems [10]. The direction of movement is selected randomly among the sensing sectors ([1,..,16]). In the research field of mobile-robot systems, a large amount of papers have been published related to intelligent navigation or parking systems [10]." http://www.uniobuda.hu/journal/Nagy_52.pdf, WoS link. MTMT
- c17⁽¹⁰¹⁾ Gyorgy Csaba, Improvement of an adaptive fuzzy-based obstacle avoidance algorithm using virtual and real kinect sensors, Proceedings of the 2013 IEEE 9th International Conference on Computational Cybernetics (ICCC), pp. 113-120, ISBN: 978-1-4799-0060-2, DOI: 10.1109/ICCCyb.2013.6617572 Tihany, Hungary, 8-10 July 2013. "Most of the resources that describe fuzzybased robot controlling systems deal with rule sets for two wheeled vehicles ([7], [8]); controls like this are already being used in traditional systems since quite a while now ([9]). "
- c18⁽¹⁰²⁾ Janus S. Liang, Kuo-Ming Chao, Paul Ivey, VR-based wheeled mobile robot in application of remote real-time assembly, The International Journal of Advanced Manufacturing Technology, Springer-Verlag, Volume 64, Issue 9-12, pp. 1765-1779, Print ISSN 0268-3768, Online ISSN 1433-3015, DOI: 10.1007/s00170-012-4140-1, 2013-02-01.
- c19⁽¹⁰³⁾ Oscar Montiel, Roberto Sepúlveda, Ignacio Murcio, Ulises Orozco-Rosas, Geo-Navigation for a Mobile Robot and Obstacle Avoidance Using Fuzzy Controllers, Series Title: Studies in Computational Intelligence, Book Title: Recent Advances on Hybrid Approaches for Designing Intelligent Systems, part V, Series Volume 547, Series ISSN 1860-949X ISBN 978-3-319-05169-7, pp. 647-669, Springer International Publishing. WoS link.

D13. **GooSch** Gyula Mester, "Intelligent Wheeled Mobile Robot Navigation", Jelenkori társadalmi és gazdasági folyamatok, V. Évfolyam, 1-2 szám, pp. 258-264, ISSN: 1788-7593, SZTE, Szeged, Hungary, 2010. Gyula Mester, Intelligent Wheeled Mobile Robot Navigation", Konferenciakiadvány Európai Kihívások V, pp. 1-5, SZTE, Szeged, Hungary, 2009. MTMT/0.4

- c1⁽¹⁰⁴⁾ Istvan Matijevics, Simon Janos, Autonomni mobilni robot kao merna stanica u okruzenju staklenika, Proceedings of the Conference YUINFO 2010, pp. 1-4, ISBN 978-86-85525-05-6, Kopaonik, Serbia, 2010. MTMT
- c2⁽¹⁰⁵⁾ Janos Simon, Goran Martinovic, Istvan Matijevics, "WSN Implementation in the Greenhouse Environment Using Mobile Measuring Station" International Journal of Electrical and Computer Engineering Systems, Vol. 1, No. 1, pp. 37-44, ISSN 1847-6996, Osijek, Croatia, June, 2010. MTMT
- c3⁽¹⁰⁶⁾ Janos Simon, Istvan Matijevics, "Implementation of Potential Field Method for Mobile Robot Navigation in Greenhouse Environment with WSN Support, Proceedings of the SISY 2010 IEEE 8th International Symposium on Intelligent Systems and Informatics, pp. 319-323, ISBN: 978-1-4244-7394-6, DOI: 10.1109/SISY.2010.5647434, Subotica, Serbia, september 10-11, 2010. MTMT
- c4⁽¹⁰⁷⁾ Istvan Matijevics, Simon Janos, Control of Greenhouse's Microclimatic Condition Using Wireless Sensor Network , The IPSI BgDTransactions on Internet Research, Vol. 6, Number 2, pp. 35-38, Belgrade, Serbia, 2010. MTMT
- c5⁽¹⁰⁸⁾ Istvan Matijevics, Simon Janos, Autonomous Mobile Robot Measuring Station in Greenhouse Environment, Proceedings of the SIP 2010, 28th International Conference Science in Practice, pp. 167-170, ISBN 978-86-85409-53-0, Subotica, Serbia, , June 3-4, 2010. MTMT
- c6⁽¹⁰⁹⁾ Istvan Matijevics, Web Based Remote Control of Mobile Robot with Video Stream Feedback, Icist, pp. 28-31, ISSN: 2217-3269, 2011. MTMT
- c7⁽¹¹⁰⁾ Simon János, Gogolák László, Greenhouse microclimatic control strategy using WSN and mobile robot, Proceedings of the International Conference Science in Practice SIP 2013, pp 1-6, Bremen, Germany, Oct. 27-29, 2013. MTMT
- c8⁽¹¹¹⁾ Janos Simon, Optimal microclimatic control strategy using wireless sensor network and mobile measuring agent , Acta Agriculturae Serbica, Vol. XVIII, No. 36, pp. 111-121, ID: 203789324, 2013 "In a cluster, a wireless sensor node can transmit data to the base station and transmit instructions to the control system (Gyula Mester, 2009)." MTMT
- c9⁽¹¹²⁾ Janos Simon, Višekriterijsko neizrazito upravljanje mikroklimom plastenika pomoću autonomne mobilne mjerne stanice, PhD Dissertation, 162 pages, Sveučilište Josipa Jurja Strossmayera u Osijeku, Elektrotehnički Fakultet Osijek, mentor: Goran Martinović, 2013. MTMT

D14. **GooSch** Gyula Mester, "Sensor Based Control of Autonomous Wheeled Mobile Robots", The Ipsi BgD Transactions on Internet Research, TIR, Volume 6, Number 2, pp. 29-34, ISSN 1820-4503, New York, Frankfurt, Tokio, Belgrade, <http://internetjournals.net/journals/tir/2010/July/Paper%2004.pdf>, 2010. MTMT/0.4

- c1⁽¹¹³⁾ Dragan Z. Saletic, Milica Savic, Andrej Zurovac, "Improvement in Implementation of Fuzzy

- Decision Making in Determining the Severity of Respiratory Distress", Proceedings of the SISY 2010 • 2010 IEEE 8th International Symposium on Intelligent Systems and Informatics, pp. 47-52, ISBN: 978-1-4244-7394-6, DOI: 10.1109/SISY.2010.5647101, Subotica, Serbia, September 10-11, 2010. **MTMT**
- c2⁽¹¹⁴⁾ Sandor Csikos, Robot Remote Control Over the Internet, Proceedings of the SIP 2010, 28th International Conference Science in Practice, pp. 41-43, Subotica, Serbia, June 3-4, 2010. **MTMT**
- c3⁽¹¹⁵⁾ Dragan Z. Saletic, Uros Popovic, "Design of fuzzy controllers based on automatic selection of membership functions shapes ", Proceedings of the 10th Symposium on Neural Network Applications in Electrical Engineering Neurel 2010, pp. 131-136, ISBN: 978-1-4244-8821-6, DOI: 10.1109/NEUREL.2010.5644090, Belgrade, Serbia, September 23-25, 2010. **MTMT**
- c4⁽¹¹⁶⁾ Janos Simon, Istvan Matijevics, "Simulation and Implementation of Mobile Measuring Robot Navigation Algorithms in Controlled Microclimatic Environment Using WSN", Proceedings of the SISY 2011, 9th IEEE International Symposium on Intelligent Systems and Informatics, pp 275-279, ISBN: 978-1-4577-1973-8, Subotica, Serbia, September 8-10, 2011. **MTMT**
- c5⁽¹¹⁷⁾ Dusko Katic, Cooperative Multi Robot Systems for Contemporary Shopping Malls, Volume 8, Number 2, pp. 10-17, Intelligent Service Robotic Systems, Ipsi Journal, Transactions on Internet Research, TIR, ISSN 1820 - 4503, New York, Frankfurt, Tokyo, Belgrade, <http://internetjournals.net>, 2012.... The main concept of multi-robot systems for shopping malls is based on the representation of a multi-purpose robotic system for service applications with advanced perception and action capabilities [20-23]. **MTMT**
- c6⁽¹¹⁸⁾ Annamária R. Várkonyi-Kóczy, A Complexity Reduced Hybrid Autonomous Navigation Method for Indoor Robots, Intelligent Service Robotic Systems, Ipsi Journal, Transactions on Internet Research, TIR, Volume 8, Number 2, pp. 32-39, ISSN 1820 - 4503, New York, Frankfurt, Tokyo, Belgrade, <http://internetjournals.net>, 2012....In case of global navigation (see e.g. [3], [4]), only presupplied data are accessible while in case of local navigation (see e.g. [5], [6], [7]), only the sensory measurements are taken into account. **MTMT**
- c7⁽¹¹⁹⁾ Mester G., Intelligent Mobile Robot Motion Control in Unstructured Environments, Acta Polytechnica Hungarica, Vol. 7, No. 4, pp. 153-165, 2010, link.
- c8⁽¹²⁰⁾ Liang Janus, Chao Kuo-Ming, Ivey Paul, Intelligent VR-based wheeled mobile robot in application of remote real-time assembly, International Journal of Advanced Manufacturing Technology, Springer London, ISSN: 0268-3768, DOI: 10.1007/s00170-012-4140-1, pp. 1765-1779, 63 Volumes, 363 Issues, 2012, **WoS** link. **MTMT**
- c9⁽¹²¹⁾ Simon Janos, Istvan Matijevics, Remote Control of Anthropomorphic Robotic Platform for Socially Acceptable and Adequate Interaction in Human's Working Environment, Proceedings of the SIP 2012, 30th International Conference Science in Practice, pp. 103-107, ISBN 978-963-7298-53-0, Pécs, Hungary, October 29-30, 2012. **MTMT**
- c10⁽¹²²⁾ Rajnai Zoltán, Elektronikus adatkezelő rendszerek kockázati módszerek bemutatása, VMTT Konferencia, Konferenciakiadvány, pp. 1-14, Újvidék, Szerbia, November 15, 2014.
- D15. D. Saletic, B. Selic, G. Mester, „Are we Ready for Nanotechnology“, e-RAF Journal on Computing, Vol. 1, pp. 38-48, Beograd, <http://joc.raf.edu.rs/index.php?lang=en>, 2009. **MTMT/0.133**
- D16. **GooSch** Gyula Mester, Szilveszter Pletl: „Rugalmas robotok hibrid irányítása”. Gép, LV. évf. pp. 37-38, ISSN 0016-8572, Budapest, Hungary, 2004. **MTMT/0.075**
- c1⁽¹²³⁾ Istvan Matijevics, Real and Remote Laboratories in Education, Proceedings of the International Symposium on Advanced Engineering & Applied Management 40th Anniversary in Higher Education, pp. 199-202, Hunedoara, Romania, 2010. **MTMT**
- c2⁽¹²⁴⁾ Istvan Matijevics, Real and Remote Laboratories in Education, Annals of Faculty Engineering Hunedoara – International Journal of Engineering, Tome IX, Fascicule 2, pp. 73-78, ISSN 1584 – 2665 , pp. 129-132, Hunedoara, Romania, 2011. **MTMT**
- D17. Gyula Mester, Tibor Mester, "Building Applications of XML Web Services", Annals of the Faculty of Engineering Hunedoara, Tome 2, pp. 5-8, ISSN 1584-2665, Timisoara, Romania, 2004. **MTMT/0.2**
- D18. **GooSch** Gyula Mester, Pletl Szilveszter, Lehel Szarapka: "Fuzzy Control of RL-FJ Robots with Neural Membership Functions". Bulletins for Applied Mathematics, 1063/94, pp. 231-238, ISSN 0133-3526, Budapest, Hungary, 1994. **MTMT/0.1**
- c1⁽¹²⁵⁾ Szilveszter Pletl, Korszerű adaptív, fuzzy és neurális elvű robotirányítási algoritmusok, Budapest University of Technology and Economics, Ph.D. Thesis, pages 102, Budapest, Hungary, 2001. **MTMT**
- D19. Gyula Mester, Pletl Szilveszter, Gizella Pajor: "Adaptive Motion Control of Rigid-Link Flexible Joints Scara Robots". Bulletins for Applied Mathematics, 966/94, pp. 63-72, ISSN 0133-3526, Budapest, Hungary, 1994. **MTM/0.1**
- c1⁽¹²⁶⁾ Szilveszter Pletl, Korszerű adaptív, fuzzy és neurális elvű robotirányítási algoritmusok, Budapest University of Technology and Economics, Ph.D. Thesis, pages 102, Budapest, Hungary, 2001. **MTMT**

- D20. J. Rudas, A. L. Bencsik, J. F. Bitó, Á. Szeghegyi, Gy. Mester: Inverse Entropy Based New Fuzzy Logic Control Formalism. Bulletins for Applied Mathematics, BAM, pp. 181-186, ISSN 0133-3526, Budapest, Hungary, 1995./0.06
- D21. Gyula Mester, Szilveszter Pletl, Gizella Pajor: "Csuklórugalmasság kihatása a robotmanipulátorok adaptív irányítására". Bulletins for Applied Mathematics, BAM 877, pp. 167-172, ISSN 0133-3526, Budapest, Hungary, 1993. **MTM/0.1**
- c1⁽¹²⁷⁾ Pletl Szilveszter, Korszerű adaptív, fuzzy és neurális elvű robotirányítási algoritmusok, Budapest University of Technology and Economics, Ph.D. Thesis, pages 102, Budapest, Hungary, 2001. **MTMT**
- D22. Gyula Mester, Zoltan Jeges, Szilveszter Pletl, Pajor Gizella: "Rugalmas csuklóval rendelkező robotmanipulátorok dinamikai modellezése". Bulletins for Applied Mathematics, BAM 731/91, ISSN 0133-3526, pp. 137-143, Budapest, Hungary, 1991. **MTM/0.075**
- c1⁽¹²⁸⁾ Pletl Szilveszter: Korszerű adaptív, fuzzy és neurális elvű robotirányítási algoritmusok, Budapest University of Technology and Economics, Ph.D. Thesis, pages 102, Budapest, Hungary, 2001. **MTMT**
- D23. Zoltan Jeges, Gyula Mester, Branko Zuzic: „Robotsteurung mit Elastischen Gliedern unter Verwendung von Modellen”. Bulletins for Applied Mathematics, BAM 712/91, pp. 123-130, ISSN 0133-3526, Budapest, Hungary, 1991. **MTM/0.1**
- D24. Gyula Mester, Vytautas Turla: "Dynamik von Maschinenantrieben mit Dreistufigen ZahnradGetriebe". Bulletins for Applied Mathematics, BAM 583/88, pp. 319-324, ISSN 0133-3526, Budapest, Hungaria, 1988. **MTM/0.15**
- D25. Gajin Slobodan, Gyula Mester: "Prilog resavanju problema dinamicke stabilnosti nelinearnih parametarskih torzionih vibracija vratila elektromehanickih prenosnika". Zbornik radova Gradjevinskog fakulteta, No. 3, pp. 112-120, ISBN 86-80297-04-6, Subotica, Yugoslavia, 1986. **MTM/0.2**
- D26. Pavlović Miroljub, Gajin Slobodan, Gyula Mester: "Prilog dinamici krutog plocastog temelja na elasticnom sloju Vlasova – Leontijeva. Zbornik radova Gradjevinskog fakulteta, No. 3, pp. 70-78, ISBN 86-80297-04-6, Subotica, Yugoslavia, 1986. **MTM/0.2**
- D27. Kuzmanovic Sinisa, Gyula Mester, Kovacević D., Maravic D.: "Motoros hajtóművek tengelyvégének megengedett terhelés kimutatása katalógus segítségével". Bulletins for Applied Mathematics, BAM 335/85, ISSN 0133-3526, pp. 181-186, Budapest, Hungary, 1985. **MTM/0.075**
- D28. Lajos Kutri, Gyula Mester, Gajin Slobodan, Zoltan Jeges: "Motoros hajtóművek nemlineáris gerjesztett térbeli rezgései". Bulletins for Applied Mathematics, BAM 325/85, ISSN 0133-3526, pp. 51-60, Budapest, Hungary, 1985. **MTM/0.075**
- D29. Gajin Slobodan, Folić R., Gyula Mester: "Mathematical Modeling of the Optimum Vibroisolation of a Discrete Mass Supported by a Plate on Elastic Base" Bulletins for Applied Mathematics, BAM 321/85 ISSN 0133-3526, pp. 7-16, Budapest, Hungary, 1985. **MTM/0.1**
- D30. Gyula Mester, Lajos Kutri, Gajin Slobodan: "A munkagép változó tehetetlenségi nyomatékának és az áttétel változásának kihatása motoros hajtóművek csavarórezgéseire". Bulletins for Applied Mathematics, BAM 251/84, pp. 80-89, ISSN 0133-3526, Budapest, Hungary, 1984. **MTM/0.1**
- D31. Gajin Slobodan, Pavlović Miroljub, Gyula Mester: "Rugalmas talalon fekvő prizmatikus test állandósult csillapítatlan gerjesztett rezgései". KAMM füzetek, BAM 224/84, ISSN 0209-9489, pp. 133-141, Budapest, Hungary, 1984. **MTM/0.1**
- D32. Gajin Slobodan, Pavlović Miroljub, Gyula Mester: "A talaj geometriai nemlinearitásának kihatása tömbalapok rezgésére". Bulletins for Applied Mathematics, BAM 254/84, ISSN 0133-3526, pp. 8-21, Budapest, Hungary, 1984. **MTM/0.1**
- D33. Orlov G. Vera, József Detki, Gajin Slobodan, Gyula Mester: "Beurteilung der Beschränktheit der Lösung für eine Gleichung der Oszillationstheorie". Bulletins for Applied Mathematics, BAM 216/84, ISSN 0133-3526, pp. 53-59, Budapest, Hungary, 1984. **MTM/0.075**
- D34. Gyula Mester, Dirner Aleksandar: "Izbor optimalne varijante hidraulicnog servo sistema". KAMM Füzetek (229), pp. 211-220, Budapest, 1983. **MTM/0.15**

- D35. Gajin Slobodan, Gyula Mester, Pavlovic Miroljub: "Eigenfrequencies of an Elastically Supported and with Mass Points Weighted Bar" Bulletins for Applied Mathematics, BAM 138/82, pp. 15-21, ISSN 0133-3526, Budapest, Hungary, 1982. **MTM/0.1**
- D36. Gyula Mester: "Prilog resenju problema slobodnih prigušenih poprecnih oscilacija prizmaticnog stapa pri nelinearnom zakonu elasticnosti". Tehnika, No. 5, pp. 751-753, ISSN 0040-2176, Beograd, Jugoslavija, 1978. **MTM/0.4**
- D37. Gyula Mester: "Prilog resenju problema nelinearnih torzionih oscilacija vratila", Tehnika, No. 9, pp. 8-9, ISSN 0040-2176, Beograd, Jugoslavija, 1977. **MTM/0.4**
- D38. Gyula Mester: "A Variational Approach to the Problem of free Damped Longitudinal Oscillations a Prismatic Beam with a Nonlinear Elastic Characteristik". Theoretical and Applied Mechanics, No.3, pp. 53-57, ISSN 0350-2708, Belgrade, Yugoslavia, 1977. **MTM/0.4**
- D39. Gyula Mester: "Slobodne poprecne oscilacije prizmaticnog stapa pri nelinearnom zakonu elasticnosti". Matematički Vesnik, Vol. 13 (28), No. 4, pp. 407-413, ISSN 0025-5165, Beograd, Jugoslavija, 1976. **MTM/0.4**

D. Konferenciakiadványban megjelent lektorált konferenciacikkek

- E1. Mester Gyula, Új tudományos eredmények mérése, Konferenciakiadvány XXX. Kandó konferencia, pp.1- , Budapest, 2014, november 20.
- E2. Josip Kasac, Vladimir Milic, Josip Stepanic, Gyula Mester, A Computational Approach to Parameter Identification of Spatially Distributed Nonlinear Systems with Unknown Initial Conditions, Proceedings of the IEEE Symposium on Robotic Intelligence in Informationally Structured Space (RiiSS 2014), pp. 1-7, 9-12 December 2014, Orlando, Florida, USA. <http://ieee-ssci.org/RiiSS.html>.
- E3. Gyula Mester, Introduction to Cloud Robotics, Proceedings of the SIP 2014, 32nd International Conference Science in Practice, pp.1-4, Osijek, Croatia, 15-17.10.2014.
- E4. L Cveticanin, I Biro, Gy Mester, Investigation of nonlinear oscillating system, In: ICoSTAF2014 Confrence. Konferencia helye, ideje: Szeged, Magyarország, 2014.04.25
- E5. Mester Gyula, Doktori iskola létesítése és működése, Létünk konferenciakiadvány, pp. 1-5, Újvidék, 2013. <http://www.letunk.rs/virtualis/mester.html>
- E6. Mester Gyula, Honlap szerkesztése Google Tudós alkalmazásával, VMTT Konferencia, Konferenciakiadvány, pp. 674-679, ISBN 978-86-88077-06-4, Újvidék, Szerbia, november 23, 2013.
- E7. **GooSch** Gyula Mester, Aleksandar Rodic, Simulation of Quad-rotor Flight Dynamics for the Analysis of Control, Spatial Navigation and Obstacle Avoidance, Proceedings of the 3rd International Workshop on Advanced Computational Intelligence and Intelligent Informatics (IWACIII 2013), pp. 1-4, ISSN2185-758X, Shanghai, China, October 18 to 21 in 2013.
- E8. **GooSch** Gyula Mester, Metode naučne metrike i rangiranja naučnih rezultata, Zbornik radova 57. konferencije ETRAN, str. RO3.5.1-3, Zlatibor, 3-6. juna 2013.
- E9. **GooSch** Josip Stepanic, Gyula Mester, Josip Kasac, Synthetic Inertial Navigation Systems: Case Study of Determining Direction, Proceedings of 57th ETRAN Conference, pp. RO 2.7., 1-3, Zlatibor, Serbia, June 3-6, 2013. **MTMT**
- c1⁽¹²⁹⁾ Josip Stepanić, Josip Kasać, Jelena Čosić Lesičar, What is Taken for Granted about Quadrotors: Remarks about drive and communication, Proceedings of the 3rd International Workshop on Advanced Computational Intelligence and Intelligent Informatics (IWACIII 2013), pp. 1-4, ISSN2185-758X, N. Kubota, Shanghai, China, October 18 to 21 in 2013. „Corresponding details are given elsewhere [8]. Here we present main elements of the approach aimed for operationalising previously described enhancement in quality of navigation of a swarm of quadrotors [8].” **MTMT**
- c2⁽¹³⁰⁾ Gyula Mester, Design of the Fuzzy Control Systems Based on Genetic Algorithm for Intelligent Robots, Interdisciplinary Description of Complex Systems 12 (3), pp. 245-254, 2014, ISSN 1334-4676, DOI: 10.7906/indecs.12.3.4 DOI: 10.7906/indecs.12.3.4
- E10. Gyula Mester, ARWU egyetemi világgranglista, Vajdasági Magyar Tudóstalálkozó, Szabadka, Szerbia, 2013, április 13, Tudományos Diszkurzusok konferenciakötet, pp. 274-279, ISBN 978-86-89095-04-3, szerkesztő: Berényi János, Vajdasági magyar Akadémiai Tanács, Újvidék, 2013. április 13.

- E11. **GooSch** Aleksandar Rodic, Gyula Mester, Control of a Quadrotor Flight, Proceedings of the ICIST Conference, pp. 61-66, ISBN: 978-86-85525-12-4, Kopaonik, Serbia, 03-06.03.2013.
- E12. **GooSch** Gyula Mester, Univerziteti regionalni rang listi univerziteta u svetu 2012, Proceedings of the XIX Skup Trendovi Razvoja: "Univerzitet na tržištu...", paper No. T1.1-1, pp. 1-5, Maribor, Pohorje, Slovenija, 18-21.02.2013.
- E13. **GooSch** Gyula Mester, Aleksandar Rodic, 'Navigation of an Autonomous Outdoor Quadrotor Helicopter', Proceedings of the 2nd International Conference on Internet Society Technologie and Management ICIST , ISBN: 978-86-85525-10-0, pp. 259-262, 1-3.03.2012. **MTMT/0.2**
- E14. Gyula Mester, "Development of Anthropomorphic Robotic Platform", Proceedings of the IBC 2012, 1st International Internet & Business Conference, pp. 198-203, ISSN 1848-5278, June 27-28, Rovinj, Croatia, 2012. **MTMT/0.2**
- E15. Aleksandar Rodic, Gyula Mester, Ivan Stojkovic, " Navigation and Control of Indoor Mobile Robot in Unknown Environments", Proceedings of the 56th ETRAN Conference, RO3.6-1-4, pp. 1-5, ISBN 978-86-80509-67-9, Zlatibor, Serbia, June 11-14, 2012. **MTMT/0.066**
- E16. Gyula Mester, "Najnovije svetske rang liste univerziteta", XVIII Skup Trendovi Razvoja "Internacionalizacija Univerziteta" - Proceedings of the TREND 2012, pp. 144-151, ISBN 978 86 7892 388 3, Kopaonik, Serbia, 27.02. - 01.03. 2012. **MTMT/0.2**
- E17. Gyula Mester, „Személyi robotikai platformok fejlesztése és alkalmazása”, VMTT Konferencia, Konferenciakiadvány, pp. 572-579, ISBN 978-86-88077-03-3, Újvidék, Szerbia, november 12, 2011. **MTMT/0.1**
- E18. Aleksandar Rodic, Gyula Mester, "Ambientally Aware Bi-Functional Ground-Aerial Robot-Sensor Networked System for Remote Environmental Surveillance and Monitoring Tasks", Proceedings of the 55th ETRAN Conference, Section Robotics, Volume RO2.5, pp 1-4, ISBN 978-86-80509-66-2, Banja Vrućica, Bosnia and Herzegovina, Jun 6-9, 2011. **MTMT/0.1**
- E19. Gyula Mester, „Szerviz robotok”, VMTT Konferencia, Konferenciakiadvány, pp. 470-482, ISBN 978-86-88077-02-6, Újvidék, Szerbia, 2010. **MTMT/0.1**
- E20. **GooSch** Aleksandar Rodic, Gyula Mester, "Modeling and Simulation of Quad-Rotor Dynamics and Spatial Navigation", Proceedings of the SISY 2011, 9th IEEE International Symposium on Intelligent Systems and Informatics, pp 23-28, ISBN: 978-1-4577-1973-8, DOI: 10.1109/SISY.2011.6034325, Subotica, Serbia, 8–10 September, <http://conf.uni-obuda.hu/sisy2011>, 2011. **MTMT/0.1**
- c1⁽¹³¹⁾ Aleksandar Rodic, Gyula Mester, The Modeling and Simulation of an Autonomous Quad-Rotor Microcopter in a Virtual Outdoor Scenario, Acta Polytechnica Hungarica, Journal of Applied Sciences, Vol. 8, Issue No. 4, pp. 107-122, ISSN 1785-8860, Budapest, Hungary, 2011, **Wos** link. **MTMT**
- c2⁽¹³²⁾ Aleksandar Rodic, Ivan R. Stojkovic 'Dynamic Inversion Control of Quadrotor with Complementary Fuzzy Logic Compensator', Proceedings of the 2012 11th Symposium on Neural Network Applications in Electrical Engineering (NEUREL), Belgrade, Print ISBN: 978-1-4673-1569-2, INSPEC Accession Number: 13266444, DOI: 10.1109/NEUREL.2012.6419963, pp. 53-58, 20-22 Sept. 2012, 'The Fig. 1. shows the structure model [9] [10] in hovering condition, where all the propellers have the same speed of rotation. For the purpose of testing proposed integrated flight controller the following quadrotor parameters are assumed Table II [9] [10].' **MTMT**
- c3⁽¹³³⁾ Noda Shohei, Hiroyuki Masuta, Hun-ok Lim, The fuzzy position control for the four rotor flying robot, Proceedings of the Soft Computing and Intelligent Systems (SCIS) and 13th International Symposium on Advanced Intelligent Systems (ISIS), 2012 Joint 6th International Conference on Date of Conference, pp.1238-1243, ISBN: 978-1-4673-2742-8, DOI: 10.1109/SCIS-ISIS.2012.6505159, Kobe, Japan, 20-24 Nov. 2012. "As we consider hovering flight, we can assume that the thrust and the drag are proportional to the square of the propellers rotation speed [10]." **MTMT**
- c4⁽¹³⁴⁾ Yibo Li, Gang Wang, Quad-Rotor Airship Modeling and Simulation Based on Backstepping Control, International Journal of Control and Automation, Vol.6, No.5, pp.369-384, ISSN: 2005-4297 IJCA, 2013, <http://dx.doi.org/10.14257/ijca.2013.6.5.32>. "The following is the traditional dynamic model of the Quad-Rotor helicopter [5, 6]: „ **MTMT**
- c5⁽¹³⁵⁾ Yibo Li, Gang Wang, Quad-Rotor Airship Modeling and Simulation, Sensors & Transducers, Vol. 157, Issue 10, pp. 306-316, ISSN 1726- 5479, Article number: P_1431, <http://www.sensorsportal.com/>, October 2013. "The following is the traditional dynamic model of the Quad-Rotor helicopter [5, 6]: „ **MTMT**
- c6⁽¹³⁶⁾ 基于模糊自整定 PID 四旋翼无人机悬停控制李一波, 宋述锡 - 控制工程, 2013 -

- 万方数据资源系统摘要：四旋翼无人直升机是一种多输入，强耦合，多变量，欠驱动的系统，其可以应用到航拍，考古，边境巡逻，反恐侦查等多个领域，具有广阔的前景。根据欧拉定理以及牛顿定律建立四旋翼无人直升机的动力学模型，并且考虑了空气阻力，转动力矩对于桨叶的影响，而后基于经典PID算法 ...
- c7⁽¹³⁷⁾ Yibo Li, Gang Wang, Quad-Rotor Airship Modeling and Simulation, Sensors & Transducers, Vol. 157, Issue 10, pp. 306-316, ISSN 1726- 5479, Article number: P_1431, <http://www.sensorsportal.com/>, October 2013. "The following is the traditional dynamic model of the Quad-Rotor helicopter [5, 6]: „
- c8⁽¹³⁸⁾ Gyula Mester, Aleksandar Rodic, Navigation of an Autonomous Outdoor Quadrotor Helicopter, Proceedings of the 2nd International Conference on Internet Society Technologie and Management ICIST , ISBN: 978-86-85525-10-0, pp. 259-262, 1-3.03.2012.
- c9⁽¹³⁹⁾ Aleksandar Rodic, Gyula Mester, Ivan Stojković, Qualitative Evaluation of Flight Controller Performances for Autonomous Quadrotors, pp. 115-134, Intelligent Systems: Models and Applications, Endre Pap (Ed.), Topics in Intelligent Engineering and Informatics, Vol. 3, Part. 2, TIEI 3, ISSN 2193-9411, e-ISSN 2193-942X, ISBN 978-3-642-33958-5, e-ISBN 978-3-642-33959-2, DOI 10.1007/978-3-642-33959-2_7, Springer-Verlag Berlin Heidelberg, http://link.springer.com/chapter/10.1007/978-3-642-33959-2_7, 2013.
- c10⁽¹⁴⁰⁾ Aleksandar Rodic, Gyula Mester, Control of a Quadrotor Flight, Proceedings of the ICIST Conference, pp. 61-66, ISBN: 978-86-85525-12-4, Kopaonik, Serbia, 03-06.03.2013.
- c11⁽¹⁴¹⁾ Gyula Mester, Aleksandar Rodic, Simulation of Quad-rotor Flight Dynamics for the Analysis of Control, Spatial Navigation and Obstacle Avoidance, Proceedings of the 3rd International Workshop on Advanced Computational Intelligence and Intelligent Informatics (IWACIII 2013), pp. 1-4, ISSN2185-758X, Shanghai, China, October 18 to 21 in 2013, webmanage.ecust.edu.cn.
- c12⁽¹⁴²⁾ Gyula Mester, Aleksandar Rodic, Modeling and Navigation of an Autonomous Quad-Rotor Helicopter, E-society Journal: Research and Applications, Vol. 3, No. 1, pp. 45-53, ISSN 2217-3269, COBISS.SR-ID 255833863, July 2012.
- c13⁽¹⁴³⁾ Josip Kasac, Vladimir Milic, Josip Stepanic, Gyula Mester, A Computational Approach to Parameter Identification of Spatially Distributed Nonlinear Systems with Unknown Initial Conditions, Proceedings of the IEEE Symposium on Robotic Intelligence in Informationally Structured Space (RiiSS 2014), pp. 1-7, 9-12 December 2014, Orlando, Florida, USA. <http://ieee-ssci.org/RiiSS.html>.

E21. **GooSch, Scopus** link, Aleksandar Rodic, Milos Jovanovic, Svetmir Popic, Gyula Mester, "Scalable Experimental Platform for Research, Development and Testing of Networked Robotic Systems in Informationally Structured Environments", Proceedings of the IEEE SSCI2011, Symposium Series on Computational Intelligence, Workshop on Robotic Intelligence in Informationally Structured Space, pp. 136-143, ISBN: 978-1-4244-9885-7, DOI: 10.1109/RIISS.2011.5945779, Paris, France, 2011. **MTMT/0.05**

- c1⁽¹⁴⁴⁾ Mirjana Filipovic, Ljubinko Kevac, Branimir Reljin, Comparative Analysis of Two Configurations of a Aerial Robot, Proceedings of the SISY 2012 IEEE 10th Jubilee International Symposium on Intelligent Systems and Informatics, pp. 211-216, ISBN: 978-1-4673-4750-1, Subotica, Serbia, September 20-22, 2012. **MTMT**
- c2⁽¹⁴⁵⁾ Mirjana Filipovic, Ana Djuric, Ljubinko Kevac, Contribution to the modeling of cable-suspended parallel robot hanged on the four points, Proceedings of the International Conference on Intelligent Robots and Systems IROS, IEEE/RSJ, pp. 3526-3531, ISBN: 978-1-4673-1737-5, DOI 10.1109/IROS.2012.6385507, Vilamoura-Algarve, Portugal, Oct. 7-12, 2012, "The CPR-A system is in a process of developing at the Mihajlo Pupin Institute, which is a part of a more complex system. See Fig. 10 and paper [10]". **MTMT**
- c3⁽¹⁴⁶⁾ Mirjana Filipovic, Ana Djuric, Ljubinko Kevac, The mathematical model of aerial robot in purpose increasing of its autonomy, Proceedings of the 20th Telecommunications Forum TELFOR, pp. 1575 - 1578 , ISBN 978-1-4673-2983-5, DOI 10.1109/TELFOR.2012.6419523, Belgrade, Serbia, 20-22 Nov. 2012. **MTMT**
- c4⁽¹⁴⁷⁾ Mirjana Filipovic, Ljubinko Kevac, Ana Djuric, Future directions for implementation of aerial robot, Proceedings of the 10th International Symposium on Electronics and Telecommunications ISETC, pp. 91-94 , ISBN 978-1-4673-1177-9, DOI 10.1109/ISETC.2012.6408108, Timisiora, Romania, 15-16 Nov. 2012. **MTMT**
- c5⁽¹⁴⁸⁾ Fernandez German Carro, Gil Manuel Castro, Perez Francisco Mur, Remote robotic laboratory as nexus between students and real engineering, Proceedings of the 15th International Conference on Interactive Collaborative Learning ICL, pp. 1-4 , ISBN 978-1-4673-2425-0, DOI 10.1109/ICL.2012.6402136, Villach, Austria, 26-28 Sept. 2012. **MTMT**
- c6⁽¹⁴⁹⁾ Mirjana Filipovic, Cable-suspended Parallel Robot hanged on the four points and powered by four motors – reference frame, Proceedings of the Conference Infoteh-Jahorina, Vol. 12, pp. 514 -519, March 2013. »The CPR system is in a process of developing at the Mihajlo Pupin Institute. See Fig. 6 and paper [10].« **MTMT**
- c7⁽¹⁵⁰⁾ Mirjana Filipovic, The dynamic response of the Cable-suspended Parallel Robot hanged on the four points and powered by four motors, Proceedings of the Conference Infoteh-Jahorina, Vol. 12, pp. 520 - 525, March 2013. » The CPR device is developed in the Mihajlo Pupin Institute and is used to observe space. It is a part of more complex system presented in [10] Simulation Results « **MTMT**

- c8⁽¹⁵¹⁾ Rodić, A. and Stojković, I., 15, Building of Open-Structure Wheel-Based Mobile Robotic Platform, in Interdisciplinary Mechatronics (eds M. K. Habib and J. P. Davim), John Wiley & Sons, Inc., Hoboken, ISBN: 9781848214187, DOI: 10.1002/9781118577516.ch15, NJ, USA, 2013. **MTMT**
- c9⁽¹⁵²⁾ German Carro Fernandez, Modeling of a Telematic Control System for Robotic Equipment (Sicter), 09-10-2012, Unesco Code: 120314, 331115, work end of master, Department Of Electrical And Electronics Engineering And Control, School Of Industrial Engineers National University For Distance Education, http://ohm.ieec.uned.es/portal/wpcontent/uploads/2013/10/tfm_sicter_German_Carro_v_1_1_en.pdf, 2012. "Existing Communications: in the same way be defined existing communication systems in the work environment, benefits and disadvantages of the use of wireless systems, [9], [10], or cabled and the possible implications for interference, remote control decisions for physical cable through internet access, within the same corporate network, locally or via mobile devices or desktops, [11]." **MTMT**
- c10⁽¹⁵³⁾ Ljubinko Kevac, Mirjana Filipović, Ana Đurić, Ivana Kršenović, Analiza uticaja izbora motora na efikasnost praćenja trajektorija kablovski vođenog robota, Proceedings of 57th ETRAN Conference, Zlatibor, Serbia, June 3-6, 2013, pp. RO2.5.1-4. » U ovom radu je predstavljen jedan sistem sa kablovski vođenom kamerom. Trenutno je u planu relizacija jednog ovakvog sistema u Institutu Mihajlo Pupin u Beogradu [7] i veliki uticaj na realizaciju sistema će imati izbor motora za kontrolisanje kretanja kamere u prostoru. Iz tog razloga su ovom radu analizi ». **MTMT**
- c11⁽¹⁵⁴⁾ Mirjana Filipović, Ljubinko Kevac, Ana Đurić, Sinteza i analiza dve konfiguracije kablovski vođenog sistema, Proceedings of 57th ETRAN Conference, Zlatibor, Serbia, June 3-6, 2013, pp. RO2.4.1-6. » CPR system se razvija u Institutu Mihajlo Pupin [13].« **MTMT**
- c12⁽¹⁵⁵⁾ German Carro Fernandez, Manuel Castro Gil, Elio Sancristobal Ruiz, Miguel Latorre, Gabriel Diaz, Sergio Martin, Pablo Losada, Scaffolding online laboratory experiences as inclusive and motivational tools for students and teachers, Proceedings of the Frontiers in Education Conference, 2013 IEEE, pp. 1921 - 1927, ISSN 0190-5848, DOI 10.1109/FIE.2013.6685170, Oklahoma City, OK, USA, 23-26 Oct. 2013. "That's one of the keys to the modularity and scalability of a system, [14], and it allows its use becomes widespread as quickly as possible." **MTMT**
- c13⁽¹⁵⁶⁾ Mirjana Filipović, Technical solution Program system AIRCAMA, pp. 1-10, Mihailo Pupin Institute, www.institutepupin.com, University of Belgrade, Belgrade, Serbia, 08.03.2014. "The CPR-A system is in a process of developing at the Mihajlo Pupin Institute [7]." **MTMT**

E22. **GooSch**, Gyula Mester, "The valuation of the Impact Factor of the Journal Acta Polytechnica Hungarica", Proceedings of the TREND 2011, pp. 70-73, ISBN 978-86-7892-323-4, Kopaonik, Serbia, 2011. **MTMT/0.2**

E23. **GooSch, Scopus** link, Aleksandar Rodic, Gyula Mester, "Virtual WRSN – Modeling and Simulation of Wireless Robot-Sensor Networked Systems". Proceedings of the 8th IEEE International Symposium on Intelligent Systems and Informatics, SISY 2010, pp. 115-120, DOI: 10.1109/SISY.2010.5647245, ISBN: 978-1-4244-7394-6, Subotica, Serbia, 2010. **MTMT/0.1**

c1⁽¹⁵⁷⁾ Aleksandar Rodic, Khalid Addi, Mirko Jezdimirovic: Sensor-Based Intelligent Navigation and Control of Autonomous Mobile Robots for Advanced Terrain Missions, Scientific Technical Review, Vol.60, No.2, pp.7-15, 2010. **MTMT**

c2⁽¹⁵⁸⁾ Marko Šušić, Aleksandar Čosić, Aleksandar Ribić and Duško Katić, "An Approach for Intelligent Mobile Robot Motion Planning and Trajectory Tracking in Structured Static Environments", Proceedings of the SISY 2011, 9th IEEE International Symposium on Intelligent Systems and Informatics, pp 17-22, ISBN: 978-1-4577-1973-8, Subotica, Serbia, september 8-10, 2011, „Proposed algorithm for motion planning of mobile robot is implemented in MATLAB package, using Virtual WRSN software for mobile robot navigation, given in [12] and [13]“. **MTMT**

c3⁽¹⁵⁹⁾ Aleksandar Rodic, Navigation, Motion Planning and Control of Autonomous Wheeled Mobile Robots in Labyrinth Type Scenarios, Volume 8, Number 2, pp. 2-9, Intelligent Service Robotic Systems, Ipsi Journal, Transactions on Internet Research, TIR, ISSN 1820 - 4503, New York, Frankfurt, Tokyo, Belgrade, <http://internetjournals.net>, 2012, „To verify the proposed control approach, one characteristic labyrinth scenario with several wheeled robots moving around is simulated by use of the Virtual WRSP software toolbox“. **MTMT**

c4⁽¹⁶⁰⁾ Aleksandar Rodic, Milos Jovanovic, Svetmir Popic, Gyula Mester, "Scalable Experimental Platform for Research, Development and Testing of Networked Robotic Systems in Informationally Structured Environments", Proceedings of the IEEE SSCI2011, Symposium Series on Computational Intelligence, Workshop on Robotic Intelligence in Informationally Structured Space, pp. 136-143, ISBN: 978-1-4244-9885-7, DOI: 10.1109/RIISS.2011.5945779, Paris, France, 2011, „For an experimental verification of the navigation and control algorithms designed for guidance of mobile robots operating in the informationally structured space with presence of obstacles, corresponding experimental test bed station (presented in Fig. 8) [14] as well as complementary simulation software Virtual WRSN [13] are developed.“ **MTMT**

c5⁽¹⁶¹⁾ Gyula Mester, Intelligent Mobile Robot Motion Control in Unstructured Environments, Acta Polytechnica Hungarica, Journal of Applied Sciences, Vol. 7, Issue No. 4, ISSN 1785-8860, pp. 153-165, 2010, **WoS** link. **MTMT**

- c6⁽¹⁶²⁾ Gyula Mester, Aleksandar Rodic, "Sensor-Based Intelligent Mobile Robot Navigation in Unknown Environments", International Journal of Electrical and Computer Engineering Systems, Volume 1, Number 2, pp. 55-62, ISSN: 1847-7003, 2010. **MTMT**
- c7⁽¹⁶³⁾ Rodić, A. and Stojković, I., 15, Building of Open-Structure Wheel-Based Mobile Robotic Platform, in Interdisciplinary Mechatronics (eds M. K. Habib and J. P. Davim), John Wiley & Sons, Inc., Hoboken, ISBN: 9781848214187, DOI: 10.1002/9781118577516.ch15, NJ, USA, 2013. **MTMT**
- c8⁽¹⁶⁴⁾ Aleksandar Rodic, Gyula Mester, Sensor-based Navigation and Integrated Control of Ambient Intelligent Wheeled Robots with Tire-Ground Interaction Uncertainties, Acta Polytechnica Hungarica, Journal of Applied Sciences, Vol. 10, No. 3, pp. 113-133, http://www.uni-obuda.hu/journal/Rodic_Mester_41.pdf, (impakt faktor: 0.588), ISSN 1785-8860, DOI: 10.12700/APH.10.03.2013.3.9, Budapest, Hungary, 2013, **WoS link. MTMT**
- c9⁽¹⁶⁵⁾ A Čosić, M Šušić, D Katić, Advanced algorithms for mobile robot motion planning and tracking in structured static environments using particle swarm optimization, Serbian Journal of Electrical Engineering , Vol. 9, No. 1, pp. 9-28, DOI 10.2298/SJEE1201009C, scindeks.ceon.rs, Serbia, 2012. **MTMT**
- c10⁽¹⁶⁶⁾ Rudra Anil Kumar, G.Murali Krishna, S.Chandra Sekhar , An Efficient Navigation Test Based Remote Control Strategy, International Journal of Reviews on Recent Electronics and Computer Science, pp. 908-912, IJRRECS/October 2013/Volume-1/Issue-6/908-912, ISSN 2321-5461, www.ijrreecs.com , 2013. "In this paper a method is designed with a well efficient framework oriented strategy in which it is accurate in terms of the performance based strategy followed by the accurate outcome in a well oriented aspect towards the entire system respectively [4][7]."
"Here there is a huge challenge for the present method in which it is accurately designed in a well effective fashion followed by the accurate implementation by the control oriented strategy of the degraded performance in a well efficient fashion where there is an improvement in the performance in a well respective fashion [5][6]." **MTMT**
- E24. **GooSch** Gyula Mester, Contribution to the Simulation of Biped Robot Using 19-DOF, Proceedings of the International Symposium on Advanced Engineering & Applied Management 40th Anniversary in Higher Education, ISBN: 978-973-0-09340-7, pp. 225-230, Hunedoara, Romania, November 4-5, 2010. **MTMT/0.2**
- E25. **GooSch** Gyula Mester, "Predlog poboljsanja statusa visokih strukovnih skola Srbije u Bolonjskom sistemu studija", XVI Skup Trendovi Razvoja: Bolonja 2010, pp. 58-61, ISBN 978 86 7892 236 7, Kopaonik, 2010. **MTMT/0.2**
- E26. Ilija Cosic, Ilija Kovacevic, Goran Andjelic, Vladimir Katic, Miodrag Temerinac, Vladimir Todorovic, Milan Radosevic, Zeljko Tekic, Vladimir Djakovic, Gyula Mester, "Harmonizacija strukovnih i akademskih studija u obrazovnom sistemu Republike Srbije", Proceedings of the XVI Skup Trendovi Razvoja: Bolonja 2010, pp. 100-102, Kopaonik, 2010.
- E27. Gyula Mester, Introduction of Intelligent Vehicles and Smart Traffic Monitoring, Proceedings of the SIP 2010, 28th International Conference Science in Practice, pp. 89-92, ISBN 978-86-85409-53-0, Subotica, Serbia, June 3-4, 2010. **MTMT/0.2**
- E28. **GooSch, WoS, Scopus link**, Aleksandar Rodic, Dusko Katic, Gyula Mester, "Ambient Intelligent Robot-Sensor Networks for Environmental Surveillance and Remote Sensing", Proceedings of the IEEE SISY 2009, pp. 28-33, IEEE Catalog Number: CFP0984C-CDR, ISBN: 978-1-4244-5349-8, Library of Congress: 2009909575, DOI 10.1109/SISY.2009.5291141, Subotica, Serbia, Sept. 25-26, 2009. **MTMT/0.066**
- c1⁽¹⁶⁷⁾ Aleksandar Rodic, Khalid Addi, Mirko Jezdimirovic: Sensor-Based Intelligent Navigation and Control of Autonomous Mobile Robots for Advanced Terrain Missions, Scientific Technical Review, Vol. 60, No. 2, pp. 7-15, 2010. **MTMT**
- c2⁽¹⁶⁸⁾ Dusko Katic, Cooperative Multi Robot Systems for Contemporary Shopping Malls, Volume 8, Number 2, pp. 10-17, Intelligent Service Robotic Systems, Ipsi Journal, Transactions on Internet Research, TIR, ISSN 1820 - 4503, New York, Frankfurt, Tokyo, Belgrade, <http://internetjournals.net>, 2012.... "The main concept of multi-robot systems for shopping malls is based on the representation of a multi-purpose robotic system for service applications with advanced perception and action capabilities [20-23]". **MTMT**
- c3⁽¹⁶⁹⁾ Gyula Mester, Intelligent Mobile Robot Motion Control in Unstructured Environments, Acta Polytechnica Hungarica, , Journal of Applied Sciences, Vol. 7, Issue No. 4, ISSN 1785-8860, pp. 153-165, 2010, **WoS link. MTMT**
- c4⁽¹⁷⁰⁾ Gyula Mester, "Modelling of the Humanoid Robot Motion", Ipsi Journal, Transactions on Advanced Research, TAR, New York, Frankfurt, Tokio, Belgrade, Volume 7, Number 1, pp. 21-25 , ISSN 1820 - 4511, 2011.
- c5⁽¹⁷¹⁾ Gyula Mester, Aleksandar Rodic, "Sensor-Based Intelligent Mobile Robot Navigation in Unknown Environments", International Journal of Electrical and Computer Engineering Systems, Volume 1, Number 2, pp. 55-62, ISSN: 1847-7003, 2010.
- c6⁽¹⁷²⁾ Evy Troubleyn, Ingrid Moerman, Piet Demeester, QoS Challenges in Wireless Sensor Networked Robotics, Wireless Personal Communications, Vol. 70, Issue 3, pp. 1059-1075, DOI 10.1007/s11277-013-1103-2, Print ISSN 0929-6212, Online ISSN 1572-834X, journal No. 11277, Springer Science + Business

- Media, New York, 2013. Science Citation Index Expanded (SciSearch), Journal Citation Reports/Science Edition, SCOPUS, 2011 Impact Factor: 0.458. **WoS** link. **MTMT**
- c7⁽¹⁷³⁾ Sabrina De Capitani di Vimercati, Angelo Genovese, Giovanni Livraga, Vincenzo Piuri, Fabio Scotti, Privacy and security in environmental monitoring systems, Date of Conference: 2-5 Oct. 2012 Satellite Telecommunications (ESTEL), 2012 IEEE First AESS European Conference on, Page(s): 1 – 6, E-ISBN : 978-1-4673-4686-3, Print ISBN: 978-1-4673-4687-0, Rome, DOI: 10.1109/ESTEL.2012.6400161, "Sensing nodes are deployed in a fixed position or may be mobile on board of robots to explore the environment [3]. „, **MTMT**
- c8⁽¹⁷⁴⁾ Alessandro Brawerman, Mauricio Perretto, Felipe Augusto Przysiada, Remote Controlled Terrestrial Robotic Module, Computer Engineering Department, University of Positivo, Curitiba, Parana, Brazil, 2012, pp. 1-3, <http://world-comp.org/p2012/ESA4525.pdf>, "The work in [3] presents the development of robots using an approach to sensor network and multi-agent systems for movement." **MTMT**
- c9⁽¹⁷⁵⁾ Zhang, Guo Peng; Wang, Bo, "Research and Application of Robotics Remote Sensing", Mechatronics and Materials Processing I, PTS 1-3, Book Series: Advanced Materials Research, Vol.: 328-330, ISBN 978-3-03785-238-5, Editors: Liangchi Zhang, Chunliang Zhang and Zichen Chen, Trans Tech Publications, pp. 2074-2078, DOI: 10.4028/www.scientific.net/AMR.328-330.2074, Guangzhou, China, 2011. **MTMT**
- c10⁽¹⁷⁶⁾ Guo, Fuqin; Wang, Yuanqing, "Study of Remote Sensing and Remote Sensing Robot Technology", Green Power, Materials and Manufacturing Technology and Applications II, ISBN 978-3-03785-496-9, Editors Shaobo Zhong and Zhigang Liu, Book Series: Applied Mechanics and Materials, Trans Tech Publications, Vol. 214, pp. 914-918, DOI: 10.4028/www.scientific.net/AMM.214.914, 2012, . **WoS** link. **MTMT**
- c11⁽¹⁷⁷⁾ Marc Böhlen, Brian Clark, Jordan Dalton, Joe Atkinson, Dave Blersch, Luge Yang, Another Day at the Beach combining sensor data with human perception and intuition for the monitoring and care of public recreational water resources, Proceedings of the 2013 9th IEEE International Conference on Intelligent Environments, pp. 37-44, DOI 10.1109/IE.2013.21, 16-17 July 2013, Athens, Greece. "Related questions have been investigated in ambient systems and environment surveillance [15] as well as ambient intelligence for water management [13]." **MTMT**
- c12⁽¹⁷⁸⁾ Rudra Anil Kumar, G.Murali Krishna, S.Chandra Sekhar , An Efficient Navigation Test Based Remote Control Strategy, International Journal of Reviews on Recent Electronics and Computer Science, Editor: M.Venkat, pp. 908-912, IJRRECS/October 2013/Volume-1/Issue-6/908-912 ISSN 2321-5461, www.ijrreecs.com , 2013. "In this paper a method is designed with a well efficient framework oriented strategy in which it is accurate in terms of the performance based strategy followed by the accurate outcome in a well oriented aspect towards the entire system respectively [4][7]." **MTMT**
- c13⁽¹⁷⁹⁾ Istvan Biro, Synthesis of Some Mechanisms Using Natural Coordinates, Interdisciplinary Description of Complex Systems 12(3), 255-262, DOI: 10.7906/indecs.12.3.5, 2014, „The position of a rigid body can be determined by three coordinates of one point and three Euler-angles which are the reference point coordinates [7, 8]."
- c14⁽¹⁸⁰⁾ Gyula Mester, Design of the Fuzzy Control Systems Based on Genetic Algorithm for Intelligent Robots, Interdisciplinary Description of Complex Systems 12 (3), pp. 245-254, 2014, DOI: 10.7906/indecs.12.3.4

E29. **GooSch**, **WOS** link, **Scopus** link, Gyula Mester, "Wireless Sensor-based Control of Mobile Robots Motion", Proceedings of the IEEE SISY 2009, pp. 67-70, IEEE Catalog Number: CFP0984C-CDR, ISBN: 978-1-4244-5349-8, Library of Congress: 2009909575, DOI 10.1109/SISY.2009.52911190, Subotica, Serbia, Sept. 25-26, 2009. **MTMT/0.2**

- c1⁽¹⁸¹⁾ Istvan Matijevics, Simon Janos, Control of Greenhouse's Microclimatic Condition Using Wireless Sensor Network , Proceedings of the PROSENSE 3rd Seminar Ljubljana, Institute Joze Stefan, pp. 25-26, Slovenia, November, 17-21, 2009. **MTMT**
- c2⁽¹⁸²⁾ Istvan Matijevics, Simon Janos, Autonomni mobilni robot kao merna stanica u okruzenju staklenika, Proceedings of the Conference YUINFO 2010, pp. 1-4, ISBN 978-86-85525-05-6, Kopaonik, Serbia, 2010. **MTMT**
- c3⁽¹⁸³⁾ Istvan Matijevics, Janos Simon : Implementation of a Mobile Measuring Station Fort he Purpose of Measuring and Controlling the Greenhouse Application, Proceedings of the 10th International Symposium of Hungarian Researchers on Computational Intelligence and Informatics, Budapest, pp. 723-731, ISBN 978-963-7154-96-6, November 12-14, 2009. **MTMT**
- c4⁽¹⁸⁴⁾ Simon Janos, Goran Martinovic, Matijevics Istvan, "WSN Implementation in the Greenhouse Environment Using Mobile Measuring Station" International Journal of Electrical and Computer Engineering Systems, Vol. 1, No. 1, pp. 37-44, ISSN 1847-6996, Osijek, Croatia, 2010. **MTMT**
- c5⁽¹⁸⁵⁾ Janos Simon, Istvan Matijevics, "Implementation of Potential Field Method for Mobile Robot Navigation in Greenhouse Environment with WSN Support", Proceedings of the SISY 2010 IEEE 8th International Symposium on Intelligent Systems and Informatics, pp. 319-323, ISBN: 978-1-4244-7394-6, DOI: 10.1109/SISY.2010.5647434 Subotica, Serbia, September 10-11, 2010. **MTMT**
- c6⁽¹⁸⁶⁾ Istvan Matijevics, Simon Janos, Control of Greenhouse's Microclimatic Condition Using Wireless Sensor Network , The IPSI BgDTransactions on Internet Research Vol. 6 Number 2, pp. 35-38, Belgrade, Serbia, 2010. **MTMT**
- c7⁽¹⁸⁷⁾ Sandor Csikos, Robot Remote Control Over the Internet, Proceedings of the SIP 2010, 28th International Conference Science in Practice, pp. 41-43, ISBN 978-86-85409-53-0,Subotica, Serbia, June 3-4, 2010. **MTMT**

- c8⁽¹⁸⁸⁾ Istvan Matijevics, Simon Janos, Autonomous Mobile Robot Measuring Station in Greenhouse Environment, Proceedings of the SIP 2010, 28th International Conference Science in Practice, pp. 167-170, Subotica, Serbia, June 3-4, 2010. **MTMT**
- c9⁽¹⁸⁹⁾ Istvan Matijevics, Web Based Remote Control of Mobile Robot with Video Stream Feedback, Icist, pp. 28-31, 6-9.03.2011. **MTMT**
- c10⁽¹⁹⁰⁾ Janos Simon, Istvan Matijevics, "Simulation and Implementation of Mobile Measuring Robot Navigation Algorithms in Controlled Microclimatic Environment Using WSN", Proceedings of the SISY 2011 IEEE 9th International Symposium on Intelligent Systems and Informatics, pp 275-279, ISBN: 978-1-4577-1973-8, Subotica, Serbia, september 8-10, 2011. **MTMT**
- c11⁽¹⁹¹⁾ Simon Janos, Matijevics Istvan, "Autonomous Mobile Robot as a Measuring Station in Controlled Microclimatic Environment", Proceedings of the XXVI. International Kandó Conference 2011, Science in Practice, pp. 1-9, ISBN 978-615-5018-19-0, Budapest, Hungary, 17-18 November, 2011. "Using automation in microclimatic environment is possible to expand the production cycle of the crops inside the greenhouse but the energy usage factor must be taken into consideration". "This main problem has been addressed by many different techniques that try to solve or at least minimize its impact." **MTMT**
- c12⁽¹⁹²⁾ Simon János, Mobil merőállomás navigációja kontrollált mikroklimatikus környezetben, VMTT Konferencia, Konferenciakiadvány, pp. 10-20, ISBN &, Újvidék, Szerbia, november 12, 2011. „A makett előállításához célszerű könnyű, tartós és erős anyagokat használni. A vas váz valamint a borításhoz használt „lexan” jó megoldás. A 4.2m x 3.65m (15.33m²) alapterület elegendő a kísérleti nővények fejlődéséhez és megfigyeléséhez [4].” **MTMT**
- c13⁽¹⁹³⁾ Gyula Mester, Intelligent Mobile Robot Motion Control in Unstructured Environments, Acta Polytechnica Hungarica, Journal of Applied Sciences, Vol. 7, No. 4, ISSN 1785-8860, pp. 153-165, 2010, http://bmf.hu/journal/Mester_25.pdf, (impakt faktor: 0.284), Budapest, Hungary, 2010. **WoS** link. **MTMT**
- c14⁽¹⁹⁴⁾ Saliyah Kahar, Riza Sulaiman, Suziyanti Marjudi, Development on Mobile Robot Controller by using High Level Language Programming: a Review, International Journal of Computer Applications (0975 – 8887), Volume 45– No.10, pp. 29-33, May 2012. “During navigation, all the sensor readings are viewed in real time on the screen of the PC. Java programming language, with the Java VM run on the hardware itself is used to write a program for Sun SPOTs technology [17].” **MTMT**
- c15⁽¹⁹⁵⁾ Jonathan P. Baker, Gabriela Garcia, BOE-Bot – Programmable Robot using the BASIC Stamp 2 Microcontroller, pp. 1-3, 2011. **MTMT**
- c16⁽¹⁹⁶⁾ Yatin Wadhawan and Sajal Gupta, Tele-Operation of Web Enabled Wireless Robot for Old Age Surveillance, Advances in Computer Science and Information Technology. Computer Science and Engineering, Volume 85, Part 1, 355-365, DOI: 10.1007/978-3-642-27308-7_39, 2012. **MTMT**
- c17⁽¹⁹⁷⁾ C. Ulaş, H. S. Efendioglu, O. Toker, H. Gümüşkaya, Delay Sensitive Wireless Protocols for Telerobotics Applications, Journal of Networking Technology, Volume 1 Number 3, September 2010, pp. 118-125, ISSN: 0976-898X. **MTMT**
- c18⁽¹⁹⁸⁾ O Toker, H Gümüşkaya, C Ulaş, BT Yilmaz, Lightweight wireless protocol based on IEEE 802.11 for delay sensitive telerobotic systems, pp. 1-33, „In [11], [12], design and implementation of a Bluetooth enabled robots are discussed, where wireless communication was done by using the Bluetooth protocol. In [13], IEEE 802.15.4.” **MTMT**
- c19⁽¹⁹⁹⁾ Janos Simon, Goran Martinovic, Navigation of Mobile Robots Using WSN's RSSI Parameter and Potential Field Method, Acta Polytechnica Hungarica, Journal of Applied Sciences, pp. 107-118, Vol. 10, No. 4, 2013., ISSN 1785-8860, DOI: 10.12700/APH.10.04.2013.4.6, „ The relationship between measured RSSI values and distances is shown in the figure below [4, 10].” **MTMT**
- c20⁽²⁰⁰⁾ Zhenxing Luo, Paul S. Min, and Shu-Jun Liu, Target Localization in Wireless Sensor Networks for Industrial Control with Selected Sensors, International Journal of Distributed Sensor Networks, Volume 2013 (2013), Article ID 304631, 9 pages, doi:10.1155/2013/304631, <http://dx.doi.org/10.1155/2013/304631>. „ In many ICSs, a wireless sensor network (WSN) is laid out to control the robotics [4–6] or to track human motion [7].” **WoS** link. **MTMT**
- c21⁽²⁰¹⁾ Simon János, Mobil robotok az oktatásban, A Magyar Tudomány Napja a Délvidéken 2012, VMTT, pp. 477-487, ISBN 978-86-88077-04-0, Újvidék, Szerbia, 2013.11.24. „ A fűnyírók és a porszívók elektromos kerítések és terelőfalak által határolt, az akadályoktól általában megtisztított térbén, összességében felettebb steril, előre kiszámítható körülmények között működnek [4].” **MTMT**
- c22⁽²⁰²⁾ István Matijevics and Janos Simon (2010). Improving Greenhouse's Automation and Data Acquisition with Mobile Robot Controlled System via Wireless Sensor Network, Chapter 6 of book 'Wireless Sensor Networks: Application-Centric Design', Geoff V Merrett and Yen Kheng Tan (Ed.), pp. 1-24, ISBN: 978-953-307-321-7, Publisher InTech, December 2010, “Any of these activities has its own control algorithm (Gy. Mester, 2009)”. **MTMT**
- c23⁽²⁰³⁾ Ismail, A.H. Ayob, M.N. ; Kaihao, T. ; Hassrizal, H.B. ; Hashim, M.S.M. ; Rahim, N.A. ; Azmi, M.S.M. ; Aziz, M.A. ; Shahriman, A.B. ; Wan, K., Investigation of homogeneous multi robots communication via Bluetooth, IEEE Symposium on Computer Applications and Industrial Electronics (ISCAIE), ISBN: 978-1-4673-3032-9, DOI :10.1109/ISCAIE.2012.6482082, pp. 124-129, Kota Kinabalu, Malaysia, 3-4 Dec. 2012. **MTMT**
- c24⁽²⁰⁴⁾ Simon János, Gogolák László, Greenhouse microclimatic control strategy using WSN and mobile robot, Proceedings of the Conference SIP 2013, pp 1-6, Bremen, Germany, Oct. 27-29, 2013. **MTMT**

- c25⁽²⁰⁵⁾ Dhanashree Pannase, To analyze hand gesture recognition for electronic device control: Review, International Journal of Advance Research in Computer Science and Management Studies, IJARCSMS, Volume 2, Issue 1, pp. 462-467, ISSN: 2321-7782 , January 2014. **MTMT**
- c26⁽²⁰⁶⁾ Janos Simon, Optimal microclimatic control strategy using wireless sensor network and mobile measuring agent , Acta Agriculturae Serbica, Vol. XVIII, 36 (2013) , pp. 111-121, ID: 203789324 " In a cluster, a wireless sensor node can transmit data to the base station and transmit instructions to the control system (Gyula Mester, 2009)." **MTMT**
- c27⁽²⁰⁷⁾ Janos Simon, Višekriterijsko neizrazito upravljanje mikroklimom platenika pomoću autonomne mobilne mjerne stanice, PhD Dissertation, 162 pages, Sveučilište Josipa Jurja Strossmayera u Osijeku, Elektrotehnički Fakultet Osijek, mentor: Goran Martinović, 2013. **MTMT**
- c28⁽²⁰⁸⁾ Goran Martinovic, Janos Simon, Greenhouse microclimatic environment controlled by a mobile measuring station, NJAS - Wageningen Journal of Life Sciences, Elsevier, pp. ?, ISSN: 1573-5214, DOI: 10.1016/j.njas. 2014.05.007, 7 June 2014. **MTMT**
- c29⁽²⁰⁹⁾ Gyula Mester, Aleksandar Rodic, "Sensor-Based Intelligent Mobile Robot Navigation in Unknown Environments", International Journal of Electrical and Computer Engineering Systems, Volume 1, Number 2, pp. 55-62, ISSN: 1847-7003, <http://www.etfos.hr/ijeces/index.php/ijeces/article/view/22>, 2010.
- E30. Gyula Mester, "Introduction of Micro- and Nanorobotics Engineering", Proceedings of the SIP, 27th International Conference Science in Practice, pp.25-28, Pécs, Hungary, 2009. **MTMT/0.2**
- E31. **GooSch** Dragan Saletic, Gyula Mester, "Nanorobots - State of the Art", Proceedings of the YuINFO 2009, pp. 1-5, ISBN: 978-86-85525-04-9, <http://www.e-drustvo.org/proceedings/YuInfo2009/html/pdf/143.pdf>, Kopaonik, Serbia, 2009. **MTMT/0.1**
- E32. Dragan Saletic, Gyula Mester, "Nanoroboti – cime raspolazemo, a sta nam jos treba da bismo ih realizovali?", Zbornik radova 12. Međunarodne konferencije ICDQM - 2009, str. 859-866, Beograd, Srbija, 2009. **MTMT/0.1**
- E33. **GooSch** Gyula Mester, "Web Based Remote Control of Mobile Robots Motion", Proceedings of the YUINFO'2009, pp. 1-3, ISBN: 978-86-85525-04-9, Kopaonik, Serbia, 2009. **MTMT/0.2**
- c1⁽²¹⁰⁾ Mester G Intelligent Mobile Robot Motion Control in Unstructured Environments, Acta Polytechnica Hungarica, , Journal of Applied Sciences, Vol. 7, No. 4, pp. 153-165, ISSN 1785-8860, 2010. **WoS** link. **MTMT**
- E34. **GooSch** Gyula Mester, "Doktorske studije na Univerzitetu u Segedinu", Proceedings of the TREND 2009, pp. 32-36, ISBN 978-86-7892-157-5, Kopaonik, Serbia, 2009. **MTMT/0.2**
- c1⁽²¹¹⁾ Norbert Sabic, Kriticni osvrt na binarni sistem visokog obrazovanja i mogucnosti za razvoj strukovnih master i doktorskih studija u Srbiji. Proceedings of the TREND 2010, pp. 312-316, ISBN, 978-86-7892-236-7, Kopaonik, Serbia, 2010. **MTMT**
- E35. Gyula Mester, "Nano- és mikrorobotok", VMTT Konferencia, Konferenciakiadvány, pp. 517-526, ISBN 978-86-88077-00-2, Újvidék, Szerbia, 2009. **MTMT/0.1**
- E36. **GooSch, WoS, Scopus** link, Gyula Mester, "Obstacle - Slope Avoidance and Velocity Control of Wheeled Mobile Robots using Fuzzy Reasoning", Proceedings of the IEEE 13th International Conference on Intelligent Engineering Systems, INES 2009, Barbados, pp. 226-230, ISBN: 978-1-4244-4113-6, Library of Congress: 2009901330, DOI: 10.1109/INES.2009.4924770, April 16-18, 2009. **MTMT/0.2**
- c1⁽²¹²⁾ Gyula Mester, Intelligent Mobile Robot Motion Control in Unstructured Environments, Acta Polytechnica Hungarica, Journal of Applied Sciences, Vol. 7, No. 4, pp. 153-165, ISSN 1785-8860, 2010, "The paper actually is a continuation of a conference paper [1]." http://bmf.hu/journal/Mester_25.pdf **WoS** link. **MTMT**
- c2⁽²¹³⁾ Victor Ayala-Ramirez, Jose A. Gasca-Martinez, Rigoberto Lopez-Padilla and Raul E. Sanchez-Yanez, An Artificial Protection Field Approach For Reactive Obstacle Avoidance in Mobile Robots, Mobile Robots Navigation, InTEch, 2010 No. 17, pp. 355-366, ISBN: 978-953-307-076-6, 2010." Some other methods have also been proposed recently for reactive navigation. Some of them use fuzzy logic to control the reactive motion of the robot. Some examples of this approach are the works by (Mester, 2008) and (Larson et al., 2005)." **MTMT**
- c3⁽²¹⁴⁾ Nicușor Minculete, Claudiu Pozna and Radu-Emil Precup,, A refinement of Sándor-Tóth's inequality, Journal of Inequalities and Applications, Springer Open Journal, 2012, Vol. 2012, No. 1, pp. 1-11, DOI:10.1186/1029-242X-2012-4. "Such applications include solutions to optimal control problems [15], stability analysis [16,17], robotics [18], fuzzy logic [19,20], difference inequalities [21] or differential equations [22], as far as positive integers are concerned." **WoS** link. **MTMT**

- c4⁽²¹⁵⁾ Gyula Mester, Aleksandar Rodic, "Sensor-Based Intelligent Mobile Robot Navigation in Unknown Environments", International Journal of Electrical and Computer Engineering Systems, Volume 1, Number 2, pp. 55-62, ISSN: 1847-7003, 2010.
- c5⁽²¹⁶⁾ Gyula Mester, " Wireless Sensor-based Control of Mobile Robots Motion ", Proceedings of the 7th International Symposium on Intelligent Systems and Informatics, pp. 67-70, Subotica, Serbia, Sept. 25-26, 2009.
- E37. **GooSch, WOS, Scopus** link, Gyula Mester, "Obstacle Avoidance and Velocity Control of Mobile Robots", Proceedings of the 6th International Symposium on Intelligent Systems and Informatics SISY2008, pp. 97-101, IEEE Catalog Number: CFP0884C-CDR, ISBN 978-1-4244-2406-1, Library of Congress: 2008903275, DOI 10.1109/SISY.2008.4664918, Subotica, Serbia, Sept. 26-27, 2008. **MTMT/0.2**
- c1⁽²¹⁷⁾ Dragan Saletic, Andrej Zurovac: Development of a Fuzzy Sets Based Prototype Expert System for Financial Applications, Proceedings of the 7th International Symposium on Intelligent Systems and Informatics, 2009. SISY '09, pp. 132-137, ISBN: 978-1-4244-5348-1, DOI 10.1109/SISY.2009.5291174, Subotica, Serbia, 25-26 September 2009. **WoS** link. **MTMT**
- c2⁽²¹⁸⁾ Piroska Molcer Stantic, Vlado Delic; Web-Based Exercises for Educating Basis of Fuzzy Logic, Proceedings of the 7th International Symposium on Intelligent Systems and Informatics, SISY'09, DOI: 10.1109/SISY.2009.5291187, pp. 103-107, Subotica, Serbia, 25-26 Sept. 2009. **WoS** link **MTMT**
- c3⁽²¹⁹⁾ Joshi, M.M.; Zaveri, M.A.; Fuzzy Based Autonomous Robot Navigation System. Proceedings of the India Conference (INDICON), 2009 Annual IEEE, ISBN: 978-1-4244-4858-6, DOI: 10.1109/INDCON.2009.5409419, pp. 1-4, Gujarat, India, 18-20 Dec. 2009. **MTMT**
- c4⁽²²⁰⁾ M. M. Joshi , M. A. Zaveri: Reactive Navigation of Autonomous Mobile Robot using NeuroFuzzy System, International Journal of Robotics and Automation (IJRA), Volume (2): Issue (3), pp. 128-145, Ed. Nabeel Tahir, ISSN : 2180-1312, http://scholar.google.com/scholar?cites=14065819296326265883&as_sdt=2005&sciodt=0,5&hl=en&num=100, 2011. „Fuzzy velocity control of mobile robot has been discussed by Mester [14]. However, only 10 heuristic fuzzy rules were used in their experiments. These approaches have inherent drawback that much efforts are needed to adjust tuning parameters and firing in advance.” **WoS** link. **MTMT**
- c5⁽²²¹⁾ M. M. Joshi; M. A. Zaveri, Neuro-fuzzy based autonomous mobile robot navigation system, This paper appears in: Control Automation Robotics & Vision (ICARCV), 2010, 11th International Conference on, Issue Date: 7-10 Dec. 2010 On page(s): 384 - 389 Location: Singapore Print ISBN: 978-1-4244-7814-9 References Cited: 13 INSPEC Accession Number: 11805705 Digital Object Identifier: 10.1109/ICARCV.2010.5707354, http://ieeexplore.ieee.org/xpl/freeabs_all.jsp?arnumber=5707354, **WoS** link. **MTMT**
- c6⁽²²²⁾ M. M. Joshi; M. A. Zaveri, Optimally Learnt, Neural Network Based Autonomous Mobile Robot Navigation System, Proc. of Int. Conf. on Advances in Electrical & Electronics 2010, pp. 56-60, 2010 ACEEE, DOI: 02.AEE.2010.01.65, „Several other methods exploiting neural-fuzzy network schemes ([6]-[14]), have been proposed for avoiding unexpected obstacles”. **MTMT**
- c7⁽²²³⁾ Gyula Mester, Intelligent Mobile Robot Motion Control in Unstructured Environments, Acta Polytechnica Hungarica, Journal of Applied Sciences, Vol. 7, No. 4, pp. 153-165, ISSN 1785-8860, 2010, http://bmf.hu/journal/Mester_25.pdf , WoS link. **MTMT**
- c8⁽²²⁴⁾ Istvan Biro, Synthesis of Some Mechanisms Using Natural Coordinates, Interdisciplinary Description of Complex Systems 12(3), 255-262, DOI: 10.7906/indecs.12.3.5
2014, „The position of a rigid body can be determined by three coordinates of one point and three Euler-angles which are the reference point coordinates [7, 8].”
- c9⁽²²⁵⁾ Josip Kasac, Vladimir Milic, Josip Stepanic, Gyula Mester, A Computational Approach to Parameter Identification of Spatially Distributed Nonlinear Systems with Unknown Initial Conditions, Proceedings of the IEEE Symposium on Robotic Intelligence in Informationally Structured Space (RiiSS 2014), pp. 1-7, 9-12 December 2014, Orlando, Florida, USA. http://ieee-ssci.org/RiiSS.html.
- E38. **GooSch**, Gyula Mester, " Designing of the Intelligent Mobile Robot Control in the Matlab Environment", Proceedings of the YUINFO'2008, pp. 1-5, ISBN: 978-86-85525-03-2, http://www.e-drustvo.org/proceedings/YuInfo2008/html/pdf/016.pdf, Kopaonik, Serbia, 9-12.03.2008. **MTMT/0.2**
- c1⁽²²⁶⁾ Gyula Mester, Intelligent Mobile Robot Motion Control in Unstructured Environments, Acta Polytechnica Hungarica, Journal of Applied Sciences, Vol. 7, No. 4, pp. 153-165, ISSN 1785-8860, 2010, http://bmf.hu/journal/Mester_25.pdf , WoS link **MTMT**
- E39. **GooSch**, Gyula Mester, "Kriticki osvrt na nedostatke i predlog izmena zakona o visokom obrazovanju", Proceedings of the TREND 2008, pp. 115-117, ISBN 978-86-7892-123-0, Kopaonik, Serbia, 2008.
- c1⁽²²⁷⁾ Norbert Sabic, Kritični osvrt na binarni sistem visokog obrazovanja i mogućnosti za razvoj strukovnih master i doktorskih studija u Srbiji. Proceedings of the TREND 2010, paper No. T2.2-3, pp. 312-316, ISBN, 978-86-7892-236-7, Kopaonik, Serbia, 2010. **MTMT**
- c2⁽²²⁸⁾ Gyula Mester, "Predlog poboljsanja statusa visokih strukovnih škola Srbije u Bolonjskom sistemu studija", XVI Skup Trendovi Razvoja: Bolonja 2010, pp. 58-61, ISBN 978 86 7892 236 7, www.trend.uns.ac.rs, Kopaonik, Serbia, 01-04.03.2010. **MTMT**

- E40. Gyula Mester, "Dynamic Modeling for a Walking Robot", Proceedings of the SIP 2008, 26th International Conference Science in Practice, pp.87-89, ISBN 978-953-6032-62-4, Osijek, Croatia, 5-7.05.2008. **MTMT**
- E41. Mester Gyula, "Kétlábon járó robot modellezése", Informatika a felsőoktatásban 2008, Konferencia kiadvány, pp. 1-8, ISBN 978-963-473-129-0, Debrecen, 2008. **MTMT/0.1**
- E42. **GooSch**, Gyula Mester, "Simulation of Humanoid Robot Motion", Proceedings of The KANDÓ Conference, pp. 1-8, ISBN 978-963-7154-74-4, Budapest, 2008. **MTMT/0.2**
- c1⁽²²⁹⁾ Gyula Mester, "Modelling of the Humanoid Robot Motion", Ipsi Journal, Transactions on Advanced Research, TAR, New York, Frankfurt, Tokio, Belgrade, Volume 7, Number 1, pp. 21-25 , ISSN 1820 - 4511, 2011. **MTMT**
 - c2⁽²³⁰⁾ Gyula Mester, Intelligent Mobile Robot Motion Control in Unstructured Environments, Acta Polytechnica Hungarica, Journal of Applied Sciences, Vol. 7, No. 4, pp. 153-165, ISSN 1785-8860, 2010, http://bmf.hu/journal/Mester_25.pdf , WoS link. **MTMT**
 - c3⁽²³¹⁾ Gyula Mester, Obstacle - Slope Avoidance and Velocity Control of Wheeled Mobile Robots using Fuzzy Reasoning, Proceedings of the IEEE 13th International Conference on Intelligent Engineering Systems, INES 2009, Barbados, pp. 245-249, ISBN: 978-1-4244-4113-6, Library of Congress: 2009901330, DOI: 10.1109/INES.2009.4924770, April 16-18, 2009, WoS link.
 - c4⁽²³²⁾ Joshi, Maulin M.; Zaveri, Mukesh A., Neuro-Fuzzy Based Autonomous Mobile Robot Navigation System, Proceedings of the 11th International Conference on Control, Automation, Robotics and Vision (ICARCV 2010), pp. 384-389, Singapore, Dec. 07-10, 2010, WoS link. **MTMT**
 - c5⁽²³³⁾ Joshi, Maulin M.; Zaveri, Mukesh A., Fuzzy Based Autonomous Robot Navigation System, Proceedings of the 2009 Annual IEEE India Conference Location: Ahmedabad, India, pp. 189-192, Dec. 18-20, 2009, WoS link. **MTMT**
- E43. Gyula Mester, "Robotizált intelligens otthonok", VMTT Konferencia, konferenciakiadvány, pp. 390-399, ISBN 978-86-83581-46-7, Újvidék, Szerbia, 2008. **MTMT/0.1**
- E44. Gyula Mester, "Robotics in Agriculture", Proceedings of the International Conference on Science and Technique in the Agri-Food Business, pp. 241, ISBN 978-963-482-908-9, University of Szeged, Faculty of Engineering, Szeged, Hungary, 5-6.11.2008. **MTMT/0.2**
- E45. **GooSch**, Gyula Mester, "Improving the Mobile Robot Control in Unknown Environments", Proceedings of the YUINFO'2007, pp. 1-5, ISBN 978-86-85525-02-5, <http://www.e-drustvo.org/proceedings/YuInfo2007/html/pdf/168.pdf>, Kopaonik, Serbia, 11-14.03.2007. **MTMT/0.2**
- c1⁽²³⁴⁾ Dragan Saletic, Milica Savic: A Fuzzy Decision-Making Agent, Research Application in Medicine and Possible Other Applications, Proceedings of the Conference YUINFO'2008, pp. 1-6, Kopaonik, Serbia, 2008. **MTMT**
 - c2⁽²³⁵⁾ Dragan Saletic, Uros Popovic: A Fuzzy Controller Parameters Optimization Using Genetic Algorithm, on an Example of Inverse Pendulum, Proceedings of the Conference YUINFO'2010, pp. 1-4, Kopaonik, Serbia, 2010. **MTMT**
 - c3⁽²³⁶⁾ Dragan Saletic, Milica Savic: Software implementation of fuzzy decision making in determining the severity of respiratory distress, Proceedings of the SISY 2008, 6th International Symposium on Intelligent Systems and Informatics, pp. 1-5, ISBN: 978-1-4244-2406-1, DOI: 10.1109/SISY.2008.4664925, Subotica, Serbia, September 26-27, 2008. WoS link. **MTMT**
 - c4⁽²³⁷⁾ Dragan Z. Saletic, Branislav V. Selic, Gyula Mester, Are We Ready for Nanotechnologi?, e-RAF Journal on Computing, Vol. 1, pp. 38-48, Beograd, 2009. <http://joc.raf.edu.rs/index.php?lang=en>. **MTMT**
 - c5⁽²³⁸⁾ Gyula Mester, Intelligent Mobile Robot Motion Control in Unstructured Environments, Acta Polytechnica Hungarica, Journal of Applied Sciences, Vol. 7, No. 4, pp. 153-165, ISSN 1785-8860, 2010, http://bmf.hu/journal/Mester_25.pdf , WoS link **MTMT**
 - c6⁽²³⁹⁾ Mester Gyula, Wireless Sensor-based Control of Mobile Robots Motion, Proceedings of the IEEE SISY 2009, pp. 67-70, IEEE Catalog Number: CFP0984C-CDR, ISBN: 978-1-4244-5349-8, Library of Congress: 2009909575, DOI 10.1109/SISY.2009.52911190, Subotica, Serbia, 2009. WoS link.
- E46. Gyula Mester, Dusan Bobera, "O potrebi brzeg ukljucivanja visokog obrazovanja Srbije u Evropski prostor Kopaonik, Serbia, 5-8.03.2007. **MTMT/0.1**
- c1⁽²⁴⁰⁾ Gyula Mester, "Doktorske studije na Univerzitetu u Segedinu", Proceedings of the TREND 2009, pp. 32-36, ISBN 978-86-7892-157-5, Kopaonik, Serbia, 02-05.03.2009, www.trend.uns.ac.rs. **MTMT**
 - c2⁽²⁴¹⁾ Gyula Mester, "Predlog poboljsanja statusa visokih strukovnih skola Srbije u Bolonjskom sistemu studija", XVI Skup Trendovi Razvoja: Bolonja 2010, pp. 58-61, ISBN 978 86 7892 236 7, www.trend.uns.ac.rs, Kopaonik, Serbia, 01-04.03.2010. "Predloženo rešenje pospešuje integraciju našeg sistema visokog obrazovanja u Evropski prostor visokog obrazovanja, a samim tim i u Evropski prostor naučnog rada i u globalni obrazovno-naučni sistem [3]." **MTMT**

c3⁽²⁴²⁾ Gyula Mester, "Academic Ranking of World Universities 2009/2010", Invited Paper, Volume 7, Number 1, pp. 44-47, Ipsi Journal, Transactions on Internet Research, TIR, ISSN 1820 - 4503, New York, Frankfurt, Tokyo, Belgrade, 2011. **MTMT**

E47. **GooSch, Scopus** link, Gyula Mester, Obstacle Avoidance of Mobile Robots in Unknown Environments," Proceedings of the 5th International Symposium on Intelligent Systems and Informatics, SISY2007, pp. 123-127, ISBN 978-1-4244-1442-0, DOI 10.1109/SISY.2007.4342637, Subotica, Serbia, August 24-25, 2007. **MTMT/0.2**

c1⁽²⁴³⁾ Wen-Yo Lee, Jhu-Syuan Guo, Chi-Pin Chenp, „Motion Control Components' Algorithms on a Chip for driving module”, Proceedings of the International Conference on Power Electronics and Drive Systems, PEDS2009, Vol. 1 and 2, pp. 385-390, ISBN: 978-1-4244-4166-2, DOI: 10.1109/PEDS.2009.5385713, 2009, „From day after day cycling testing of the mobile robot obstacle avoiding algorithms [4-5], it shows that the motion driving module has high reliabilities and excellent stabilities.“ Taipei, Taiwan, 2-5 November 2009. **WoS** link. **MTMT**

c2⁽²⁴⁴⁾ Lai, L.-C. , Wu, C.-J, Jeng, J.-T., Ko, C.-N., Fu, Y.-Y., „PSO-based potential field method for a mobile robot motion planning in an unknown environment”, Proceedings of the 14th International Symposium on Artificial Life and Robotics, AROB 14th'09 , Oita, Japan, February 5 - 7, 2009, pp. 255-258. **MTMT**

c3⁽²⁴⁵⁾ Ahmet Kizilhan, Zafer Bingül, „Üç Boyutlu Yeraltı Görüntüleme Amaçlı Gezgin Robotun Konum ve Yörünge Kontrolü”, pp. 514-519, Otomatik Kontrol Ulusal Toplantısı, 21-23 Eylül 2010, Gebze Kocaeli, .09.23. Gebze KOCAELİ: &, (2010) pp. 514-519. http://akademikpersonel.kocaeli.edu.tr/zaferb/bildiri/zaferb27.09.2010_15.30.10bildiri.pdf „Modelleme yapılrken robotun nonholonomik yapısından kaynaklanan bazı sınırlırmalar ve kabuller mevcuttur[7][8].” **MTMT**

c4⁽²⁴⁶⁾ Li-Chun Lai, Chun-Feng Lu, Yen-Ching Chang and Tsong-Li Lee, „Parameter Estimation of Potential Field Method with Fuzzy Control for Motion Planning of Soccer Robot”, Next Wave in Robotics, Communications in Computer and Information Science, 2011, Volume 212, pp. 186-192, ISBN 978-3-642-23146-9, ISSN 1865-0929, DOI: 10.1007/978-3-642-23147-6_23, T.-HS Li et al. (Eds.): FIRA 2011, CCIS 212, Springer-Verlag Berlin Heidelberg , 2011, **WoS** link. **MTMT**

c5⁽²⁴⁷⁾ Mester G., Intelligent Mobile Robot Motion Control in Unstructured Environments, Acta Polytechnica Hungarica, Journal of Applied Sciences, Vol. 7, No. 4, pp. 153-165, ISSN 1785-8860, 2010, http://bmf.hu/journal/Mester_25.pdf, WoS link **WoS** link. **MTMT**

c6⁽²⁴⁸⁾ Turki Y. Abdalla, Abdulkareem. A. A, PSO-based Optimum Design of PID Controller for Mobile Robot Trajectory Tracking, International Journal of Computer Applications (0975 – 8887), Volume 47, No.23, pp. 30-35, June 2012, “The position of the mobile robot in the plane is shown in Figure 1, the inertial-based frame (Oxy) is fixed in the plane of motion and the moving frame is attached to the mobile robot. The mobile robots are rigid cart equipped, with non-deformable conventional wheels, and it is moving on a non-deformable horizontal plane. During the motion: the contact between the wheel and the horizontal plane is reduced to a single point, the wheels are fixed, the plane of each wheel remains vertical, the wheel rotates about its horizontal axle and the orientation of the horizontal axle with respect to the cart can be fixed [9]. This means that the velocity of the contact point between each wheel and the horizontal plane is equal to zero. The rotation angle of the wheel about its horizontal axle is denoted by $\varphi(t)$ and the radius of the wheel by r . Hence, the position of the wheel is characterized by two constants: b and r and its motion by: $\varphi_r(t)$ – the rotation angle of the right wheel and $\varphi_l(t)$ – the rotation angle of the left wheel. The configuration of the mobile robot can be described by five generalized coordinates (q) such as [9, 10]: where: x_c and y_c are the two coordinates of the origin C of the moving frame (the geometric center of the mobile robot), θ is the orientation angle of the mobile robot (of the moving frame). **MTMT**

c7⁽²⁴⁹⁾ Chia-yu Shih, Intelligent Navigation and Micro - Spectrometer Content Detection System for Home Care Mobile Robot, Master's Thesis, pp. 1-77, 2012. **MTMT**

c8⁽²⁵⁰⁾ Coelho, Vivien; Liew, Stanley; Stol, Karl; et al., Development of a Mobile Two-Wheel Balancing Platform for Autonomous Applications, Proceedings of the 15th International Conference on Mechatronics and Machine Vision in Practice, IEEE, pp. 552-557, Auckland, New Zealand, Dec. 02-04, 2008. **WoS** link. **MTMT**

c9⁽²⁵¹⁾ Gyula Mester, Obstacle - Slope Avoidance and Velocity Control of Wheeled Mobile Robots using Fuzzy Reasoning, Proceedins of the International Conference on Intelligent Engineering Systems, pp. 226-230 Barbados, Apr. 16-18, 2009, **WoS** link.

c10⁽²⁵²⁾ Mester Gyula, Obstacle Avoidance and Velocity Control of Mobile Robots, Proceedings of the 6th International Symposium on Intelligent Systems and Informatics, pp. 97-101, Subotica, Serbia, Sept. 26-27, 2008, **WoS** link.

c11⁽²⁵³⁾ J Prakash, K Udhayakumar, Vision based AGV (mobile robot) using multiprocessor controller with RTOS, Advanced Engineering Informatics, Elixir Adv. Engg. Info., elixirpublishers.com, No. 31, pp. 1893-1896, 2011. **MTMT**

c12⁽²⁵⁴⁾ 基于多传感器的移动机器人避障, Obstacle Avoidance of Mobile Robot Based on Multi-Sensors, 310023, Applied Technique, pp 164-166, 2009, <http://www.c-s-a.org.cn>. **MTMT**

E48. Gyula Mester, "Bipedal Walking in Robots", Proceedings of the Európai Kihívások IV. Nemzetközi

- E49. **GooSch**, Gyula Mester, "Obstacle and Slope Avoidance of Mobile Robots in Unknown Environments". Proceedings of the XXV. Science in Practice, pp. 27-33, Schweinfurt, Oct. 15-16, 2007, Germany. **MTMT**
- c1⁽²⁵⁵⁾ Istvan Matijevics: Development of e-Laboratory for Embedded Systems, Proceedings of the YUINFO'2008, pp. 1-3, Kopaonik, Serbia, 2008. **MTMT/0.2**
- c2⁽²⁵⁶⁾ Mester G Intelligent Mobile Robot Motion Control in Unstructured Environments, Acta Polytechnica Hungarica, Vol. 7, No. 4, pp. 153-165, 2010. **WoS** link. **MTMT**
- E50. Gyula Mester, "Lépegető humanoid robotok mozgástervezése", VMTT Konferencia 10.11.2007, Konferenciakiadvány pp. 267-273, ISBN 978-86-83581-44-3, Novi Sad, Serbia, 2007. **MTMT/0.1**
- E51. **GooSch** Gyula Mester, "Modeling of the Control Strategies of Wheeled Mobile Robots", Proceedings of The Kandó Conference 2006, pp. 1-3, ISBN 963-7154-42-6, Budapest, Hungary, 2006. **MTMT**
- c1⁽²⁵⁷⁾ Istvan Matijevics: Infrared Sensors Microcontroller Interface System for Mobile Robots, Proceedings of the 5th Serbian-Hungarian Joint Symposium on Intelligent Systems and Informatics SISY 2007, ISBN 978-1-4244-1442-0, pp. 177-181, Subotica, Serbia, Aug. 24-25, 2007. **MTMT**
- c2⁽²⁵⁸⁾ Istvan Matijevics: Remote Control Laboratory for Embedded Systems via the Internet, Proceedings of the XXV. Science in Practice, pp. 59-63, Schweinfurt, Germany, Oct. 15-16, 2007. **MTMT**
- c3⁽²⁵⁹⁾ Peter Kucsera: Modular Industrial Mobile Robot Systems Mobile Robot Docking, Proceedings of the XXV. Science in Practice, pp. 13-25, Schweinfurt, Germany, Oct. 15-16, 2007. **MTMT**
- c4⁽²⁶⁰⁾ Peter Kucsera: Experimental Mobile Robot System Built Up from Industrial Components, pp. 417-428, Proceedings of the 8th International Symposium of Hungarian Researchers on Computational Intelligence and Informatics, ISBN 9789637154652, Budapest, Nov. 15-17, 2007. **MTMT**
- c5⁽²⁶¹⁾ Peter Kucsera, Industrial Component-based Sample Mobile Robot System, Acta Polytechnica Hungarica, pp. 69-81, Volume 4, Issue Number 4, ISSN 1785-8860, 2007, Budapest. **MTMT**
- c6⁽²⁶²⁾ Peter Kucsera: Autonomous Advertising Mobile Robot for Exhibitions, Developed at BMF, Studies in Computational Intelligence, Imre J. Rudas at al. Eds., ISBN 978-3-642-03736-8, DOI 10.1007/978-3-642-03737-5-21, Volume 243, pp. 295-303, Springer, 2009. **MTMT**
- c7⁽²⁶³⁾ E. Horvath, Peter Kucsera: „Autonomous Advertising Mobile Robot Development”, Proceedings of the IEEE Conference INES 2010 • 14th International Conference on Intelligent Engineering Systems, pp. 281-284, ISBN:978-1-4244-7651-0, DOI:10.1109/INES.2010.5483831, Las Palmas of Gran Canaria, Spain, May 5-7, 2010. **MTMT**
- c8⁽²⁶⁴⁾ Istvan Matijevics: „Local and Remote Laboratories in the Education of Robot Architectures”, Intelligent Engineering Systems and Computational Cybernetics, J. A. Tenreiro Machado, Béla Pátkai, Imre J. Rudas editors, pp. 27-36, ISBN 978-1-4020-8677-9, DOI: 10.1007/978-1-4020-8678-6_3, Springer, 2009. „The navigation of mobile robots [7,8] is solved with microcontrollers and microprocessors together with numerous of sensors and actuators”. **MTMT**
- c9⁽²⁶⁵⁾ Salomão Gonçalves de Oliveira, Desenvolvimento de um Robô COM Rodas Autônomo, Dissertação - Universidade Federal do Rio de Janeiro, COPPE, 122p., Rio de Janeiro, RJ – BRASIL, Abril de 2008. **MTMT**
- c10⁽²⁶⁶⁾ Simon János, Mobil merőállomás navigációja kontrollált mikroklimatikus környezetben, VMTT Konferencia, Konferenciakiadvány, pp. 580-589, ISBN 978-86-88077-03-3, Újvidék, Serbia, november 12, 2011. „A nagyobb üvegházaknál célszerű saját vízforrás létesítése, mivel ez ekkora mennyiségű vízszükséglet a vízhálózatról (központi hálózat, ivóvíz) táplálni nem lehetséges [17].” **MTMT**
- c11⁽²⁶⁷⁾ Gyula Mester, Wireless Sensor-based Control of Mobile Robots Motion, Proceedings of the 7th International Symposium on Intelligent Systems and Informatics SISY 2009, pp. 67-70, Subotica, Serbia, Sept. 25-26, 2008. **WoS** link.
- c12⁽²⁶⁸⁾ Simon János, Mobil robotok az oktatásban, A Magyar Tudomány Napja a Délvidéken, 2012.11.24, VMTT, pp. 477-487, ISBN 978-86-88077-04-0, Újvidék, Serbia, 2013. „Az autónóm robotok külső irányítótól függetlenül is képesek cselekedni. Programozásukat az a cél vezérli, hogy a külső hatásokra valamelyen módon reagáljanak. A fejlettebbek sztereó látórendszerét használnak: a térbeli érzékelést két kamera, a tárgyak lokalizálását és osztályozását képfelismerő szoftverek biztosítják [15].” **MTMT**
- E52. **GooSch** Gyula Mester, "Introduction to Control of Mobile Robots", Proceedings of the YUINFO'2006, pp. 1-4, ISBN 86-85525-01-2, <http://www.e-drustvo.org/proceedings/YuInfo2006/html/pdf/188.pdf>, Kopaonik, Serbia & Montenegro, 2006. **MTMT/0.2**
- c1⁽²⁶⁹⁾ Istvan Matijevics: Education of Mobile Robot Architecture, Proceedings of the IEEE 10th International Conference on Intelligent Engineering Systems INES 2006, pp.: 180-183, ISBN 1-4244-9708-8, London, June 26-28, 2006. **MTMT**
- c2⁽²⁷⁰⁾ Istvan Matijevics: Mobil robotok architektúrája, Szegedi Tudományegyetem, Szegedi Élelmiszeripari Főiskolai Kar, VII. Nemzetközi élelmisztudományi konferencia, pp. 83, Szeged, 2006. **MTMT**
- c3⁽²⁷¹⁾ Dragan Z. Saletic : On Further Development of Soft Computing, Some Trends in Computational Intelligence, Proceedings of the SISY 2006, pp. 319-328, Subotica, Serbia, September 29-30, 2006. **MTMT**

- c4⁽²⁷²⁾ Istvan Matijevics: Microcontrollers, Actuators and Sensors in Mobile Robots, Proceedings of the Symposium on Intelligent Systems SISY 2006, pp. 155-166, Subotica, Serbia, September 29-30, 2006. **MTMT**
- c5⁽²⁷³⁾ Janos Simon, Tibor Szakal, Zlatko Covic.: Programming Mobile Robots in ANSI C Language for PIC MCUs, Proceedings of the Symposium on Intelligent Systems SISY 2006, pp. 131-137, Subotica, Serbia, September 29-30, 2006. **MTMT**
- c6⁽²⁷⁴⁾ Gyula Mester, Obstacle Avoidance and Velocity Control of Mobile Robots, Proceedings of the IEEE 6th International Conference on Intelligent Engineering Systems and Informatics, pp. 97-101, Subotica, Serbia, September 26-27, 2008. **WoS** link.
- c7⁽²⁷⁵⁾ Gyula Mester, Obstacle Avoidance and Velocity Control of Mobile Robots, Proceedings of the IEEE 5th International Conference on Intelligent Engineering Systems and Informatics, pp.: 107-111, Subotica, Serbia, Aug. 24-25, 2007. **WoS** link.
- c8⁽²⁷⁶⁾ Istvan Matijevics, Infrared sensors microcontroller interface system for mobile robots, Proceedings of the IEEE 5th International Conference on Intelligent Engineering Systems and Informatics, pp.: 157-161, Subotica, Serbia, Aug. 24-25, 2007. **WoS** link. **MTMT**
- c9⁽²⁷⁷⁾ Janos Simon, Tibor Szakal, Zlatko Covic, Okruzenje za implementaciju i razvoj algoritama za kretanje mobilnih roboata na tockovima, Proceedings of the JISA 11 Congress SEFICT, South East Europe Forum for Informacion and Communication Technologies, pp. 1-3, Belgrade, Serbia, 22-24 May, 2006. **MTMT**

E53. Gyula Mester, "Kratak prikaz Madjarskog Zakona o visokom obrazovanju i komparacija sa našim Zakonom", Proceedings of the TREND 2006, pp. 24-27, ISBN 86-85211-77-8, Kopaonik, Serbia & Montenegro, 2006. **MTMT/0.2**

- c1⁽²⁷⁸⁾ Gyula Mester, "Predlog poboljsanja statusa visokih strukovnih skola Srbije u Bolonjskom sistemu studija", XVI Skup Trendovi Razvoja: Bolonja 2010, pp. 58-61, ISBN 978 86 7892 236 7, www.trend.uns.ac.rs, Kopaonik, Serbia, 01-04.03.2010. **MTMT**
- c2⁽²⁷⁹⁾ Gyula Mester, "Kriticki osvrt na nedostatke i predlog izmena zakona o visokom obrazovanju", Proceedings of the TREND 2008, pp. 115-117, ISBN 978-86-7892-123-0, Kopaonik, Serbia, 03-06.03.2008. **MTMT**
- c3⁽²⁸⁰⁾ Gyula Mester, "Doktorske studije na Univerzitetu u Segedinu", Proceedings of the TREND 2009, pp. 32-36, ISBN 978-86-7892-157-5, Kopaonik, Serbia, 02-05.03.2009, www.trend.uns.ac.rs. **MTMT**
- c4⁽²⁸¹⁾ Ilija Cosic, Ilija Kovacevic, Goran Andjelic, Vladimir Katic, Miodrag Temerinac, Vladimir Todorovic, Milan Radosevic, Zeljko Tekic, Vladimir Djakovic, Gyula Mester, "Harmonizacija strukovnih i akademskih studija u obrazovnom sistemu Republike Srbije", Proceedings of the XVI Skup Trendovi Razvoja: Bolonja 2010, pp. 100-102, ISBN 978-86-7892-236-7, Kopaonik, 01-04.03.2010. **MTMT**

E54. Gyula Mester, "Applications of Mobile Robots", Proceedings of the 7th International Conference of Food Science, Szeged, pp. 1-5, Hungary, 2006. **MTMT/0.2**

E55. **GooSch** Gyula Mester, "Distance Learning in Robotics", Proceedings of The Third International Conference on Informatics, Educational Technology and New Media in Education, pp. 239-245, ISBN 86-83097-51-X, Sombor, Serbia 2006. **MTMT/0.2**

- c1⁽²⁸²⁾ Istvan Matijevics, The Realization of a Web Based Control Laboratory for Distant Learning, Proceedings of the 6th International Symposium on Intelligent Systems and Informatics SISY 2008, pp. 287-289, IEEE Catalog Number: CFP0884C-CDR, ISBN: 978-1-4244-2407-8 Library of Congress: 2008903275, Subotica, Serbia, Sept. 26-27, 2008. **WoS** link. **MTMT**
- c2⁽²⁸³⁾ Istvan Matijevics : A mérnökképzés új kihívásai – internettel összeköttött távoli laboratóriumok, A Magyar tudomány napja a Délvidéken, Vajdasági Magyar Tudományos Társaság, 2008.11.08. Újvidék, pp. 380-389, ISBN 978-86-83581-46-7, COBISS.SR-ID 236453383, 2008. **MTMT**
- c3⁽²⁸⁴⁾ Istvan Matijevics, Web Based Laboratory: Stepper Motor, XXIVth International Kandó Conference 2008, 110 years on duty of education and researche, Nov. 6-7, 2008, Budapest, pp.29, ISBN 978-963-7154-74-4. **MTMT**
- c4⁽²⁸⁵⁾ Istvan Matijevics, Janos Simon : Advantages of the Remote Greenhouse Laboratory for Distant Learning, Proceedings of the International Conference on Scince and Technique in the Agri-Food Buisness, ICoSTAF2008, Szeged, Nov. 5-6, 2008, pp. 376-379. **MTMT**
- c5⁽²⁸⁶⁾ Istvan Matijevics: Internettel összeköttött laboratóriumok szerepe a mérnökinformatikus képzésben (The Role of Internet-Connected Distant Laboratories in the Engineers of Informatics' Education), Informatika a felsőoktatásban 2008, , ISBN 978-963-473-129-0, pp. 1-8, Debrecen, augusztus 27-29, 2008. **MTMT**
- c6⁽²⁸⁷⁾ Istvan Matijevics: Remote Accessing Control Laboratory on the Internet, Proceedings of the XXVI. „Science in Practice”, pp. 91-94, Osijek, Croatia, 15-16 April, 2008. **MTMT**
- c7⁽²⁸⁸⁾ Istvan Matijevics, Real and Remote Laboratories in Education, Proceedings of the International Symposium on Advanced Engineering &Applied Management 40th Anniversary in Higher Education, pp. 199-202, ISBN: 978-973-0-09340-7, Hunedoara, Romania, Nov. 4-5, 2010. **MTMT**
- c8⁽²⁸⁹⁾ Emil Matijevics, KNX Controlled Lighting Over the DALI Network, Acta Technica Corviniensis, Bulletin of Engineering, Tome IV, ISSN 2067-3809, pp. 65-69, Romania, 2011. **MTMT**

- c9⁽²⁹⁰⁾ Simon Janos, Matijevics Istvan, "Autonomous Mobile Robot as a Measuring Station in Controlled Microclimatic Environment", Proceedings of the XXVI. International Kandó Conference 2011, Science in Practice, pp. 1-9, ISBN 978-615-5018-19-0, Budapest, Hungary, 17-18 November, 2011.. ." The parameters of the data presentation, such as colors, font size, and graph types can be reconfigured, as well as dynamically rotate, zoom, and pan these graphs without programming." **MTMT**
- c10⁽²⁹¹⁾ Simon János, Mobil merőállomás navigációja kontrollált mikroklimatikus környezetben, VMTT Konferencia, Konferenciakiadvány, pp. 580-589, ISBN 978-86-88077-03-3, Újvidék, Szerbia, november 12, 2011. „A hűést könnyebb kivitelezni, mint a fűtést, akár a locsoló rendszer aktiválása (szellőztetés) vagy az árnyékolás nagy hatékonyságot ér el [16].” **MTMT**
- c11⁽²⁹²⁾ Istvan Matijevics, Real and Remote Laboratories in Education, Annals of Faculty Engineering Hunedoara – International Journal of Engineering, Tome IX, Fascicule 2, pp. 73-78, ISSN 1584 – 2665, Hunedoara, Romania, 2011. **MTMT**
- c12⁽²⁹³⁾ Gyula Mester, Wireless Sensor-based Control of Mobile Robots Motion, Proceedings of the 7th International Symposium on Intelligent Systems and Informatics SISY 2009, pp. 67-70, IEEE Catalog Number: CFP0984C-CDR, ISBN: 978-1-4244-5349-8, Library of Congress: 2009909575, DOI 10.1109/SISY.2009.52911190, Subotica, Serbia, Sept. 25-26, 2009. **WoS link**, **Scopus link**, **MTMT**
- c13⁽²⁹⁴⁾ Simon János, Mobil robotok az oktatásban, A Magyar Tudomány Napja a Délvidéken 2012, VMTT, pp. 477-487, ISBN 978-86-88077-04-0, Újvidék, Szerbia, 2013. „ Ehhez nyújt alternatívát a Kalman szűrőkre alapozó algoritmusok, amelyek egy priori rendszer modell alapján megpróbálják a becslési hibát minimálisra csökkenteni. Ugyanakkor a felhasználásukkal a több forrásból beérkező információt is egyszerre lehet hasznosítani [14].” **MTMT**
- E56. **GooSch** Gyula Mester, Intelligent Mobile Robot Controller Design, Proceedings of the Intelligent Engineering Systems, INES 2006, pp. 282-286, ISBN: 0-7803-9708-8, DOI: 10.1109/INES.2006. 1689384 London, United Kingdom, 2006. **MTMT/0.2**
- c1⁽²⁹⁵⁾ Dragan Z. Saletic : On Further Development of Soft Computing, Some Trends in Computational Intelligence, Proceedings of the 4th Serbian-Hungarian Joint Symposium on Intelligent Systems SISY 2006, pp. 319-328, Subotica, Serbia, September 29-30, 2006. **MTMT**
- c2⁽²⁹⁶⁾ Istvan Matijevics, Microcontrollers, Actuators and Sensors in Mobile Robots, Proceedings of the 4th Serbian-Hungarian Joint Symposium on Intelligent Systems SISY 2006, pp. 155-166, Subotica, Serbia, September 29-30, 2006. **MTMT**
- c3⁽²⁹⁷⁾ Dragan Z. Saletic : Fuzzy Controllers Design from their Stability Point of View, Proceedings of the YUINFO'2007, pp. 1-6, ISBN 978-86-85525-02-5, Kopaonik, Serbia, 2007. **MTMT**
- c4⁽²⁹⁸⁾ Dragan Z. Saletić : Design of Stable Fuzzy Controllers, Proceedings of the 5th Serbian-Hungarian Joint Symposium on Intelligent Systems and Informatics SISY 2007, ISBN 978-1-4244-1442-0, pp. 151-156, Subotica, Serbia, Aug. 24-25, 2007. **WoS link**. **MTMT**
- c5⁽²⁹⁹⁾ Dragan Saletić, N Mastorakis, Nikos E., A contribution to the design of stable fuzzy controllers, S Greece - Proceedings of the 9th WSEAS ..., May 2-4, 2008 - wseas.us, 9th WSEAS International Conference on Fuzzy Systems (FS'08) which was held in Sofia, Bulgaria, ISBN: 978-960-6766-57-2. pp 206-211, May 2-4, 2008. „In the paper considered results are of interest for industrial, military system, or, in general, in embedded computer systems, and especially , in intelligent robot systems, [9], [10], [11], [12].” **WoS link**. **MTMT**
- c6⁽³⁰⁰⁾ Sándor Csikós, Robot Remote Control Over the Internet, Proceedings of the SIP 2010, 28th International Conference Science in Practice, ISBN 978-86-85409-53-0, pp. 41-43, Subotica, Serbia, June 3-4, 2010. **MTMT**
- c7⁽³⁰¹⁾ Kang-Hun Lee, Chang-Jun Seo, Development of user-friendly intelligent home robot focused on safety and security, Proceedings of the Control Automation and Systems (ICCAS), 2010 International Conference on Control Automation and Systems, pp. 389-392, ISBN: 978-1-4244-7453-0, Gyeonggi-do, South Korea , 27-30 Oct.2010. **WoS link**. **MTMT**
- c8⁽³⁰²⁾ Aleksandar Rodic, Navigation, Motion Planning and Control of Autonomous Wheeled Mobile Robots in Labyrinth Type Scenarios, Volume 8, Number 2, pp. 2-9, Intelligent Service Robotic Systems, Ipsi Journal, Transactions on Internet Research, TIR, ISSN 1820 - 4503, New York, Frankfurt, Tokyo, Belgrade, <http://internetjournals.net>, 2012..... . For the case of spatial reasoning in unknown and unpredicted environments, appropriate fuzzy inference system (FIS) is commonly used [2]-[19], [22] to perform such kind of robot tasks. **MTMT**
- c9⁽³⁰³⁾ Simon Janos, Matijevics Istvan, "Autonomous Mobile Robot as a Measuring Station in Controlled Microclimatic Environment", Proceedings of the XXVI. International Kandó Conference 2011, Science in Practice, pp. 1-9, ISBN 978-615-5018-19-0, Budapest, Hungary, 17-18 November, 2011.. ." The parameters of the data presentation, such as colors, font size, and graph types can be reconfigured, as well as dynamically rotate, zoom, and pan these graphs without programming." **MTMT**
- c10⁽³⁰⁴⁾ Simon János, Mobil merőállomás navigációja kontrollált mikroklimatikus környezetben, VMTT Konferencia, Konferenciakiadvány, pp. 580-589, ISBN 9788688077033, Újvidék, Szerbia, november 12, 2011, „Némely üvegházi növénytermesztésben akár 10,000 m³ öntözővíz is elfogyhat éves szinten, egy hektáron [15].” **MTMT**

- c11⁽³⁰⁵⁾ Gyula Mester, Intelligent Mobile Robot Motion Control in Unstructured Environments, Acta Polytechnica Hungarica, , Journal of Applied Sciences, Vol. 7, No. 4, pp. 153-165, ISSN 1785-8860, 2010. **WoS** link. **MTMT**
- c12⁽³⁰⁶⁾ Gyula Mester, Aleksandar Rodic, "Sensor-Based Intelligent Mobile Robot Navigation in Unknown Environments", International Journal of Electrical and Computer Engineering Systems, Volume 1, Number 2, pp. 55-62, ISSN: 1847-7003, 2010. **MTMT**
- c13⁽³⁰⁷⁾ Simon Janos, Istvan Matijevics, Remote Control of Anthropomorphic Robotic Platform for Socially Acceptable and Adequate Interaction in Human's Working Environment, Proceedings of the SIP 2012, 30th International Conference Science in Practice, pp. 103-107 , ISBN 978-963-7298-53-0 ,Pécs, Hungary, October 29-30, 2012. **MTMT**
- c14⁽³⁰⁸⁾ Wang, Jong C.; Cheng, Hui Teng; Tsai, Ping Han; et al., Intelligent Motion Platform for Mobile Robot, IEEE Conference: 7th World Congress on Intelligent Control and Automation, pp. 3104-3109, DOI: 10.1109/WCICA.2008.4593417 Location: Chongqing, PEOPLES R CHINA, jun 25-27, 2008. **WoS** link **MTMT**
- c15⁽³⁰⁹⁾ Gyula Mester: Obstacle avoidance of mobile robots in unknown environments, Proceedings of the 5th Serbian-Hungarian Joint Symposium on Intelligent Systems and Informatics SISY 2007, ISBN 978-1-4244-1442-0, pp. 107-111, Subotica, Serbia, Aug. 24-25, 2007. **WoS** link
- c16⁽³¹⁰⁾ Gyula Mester: Wireless Sensor-based Control of Mobile Robots Motion, Proceedings of the 7th Serbian-Hungarian Joint Symposium on Intelligent Systems and Informatics SISY 2009, pp. 67-70, Subotica, Serbia, Sept. 25-26, 2009. **WoS** link
- c17⁽³¹¹⁾ Gyula Mester, "Obstacle - Slope Avoidance and Velocity Control of Wheeled Mobile Robots using Fuzzy Reasoning", Proceedings of the IEEE 13th International Conference on Intelligent Engineering Systems, INES 2009, Barbados, pp. 245-249, ISBN: 978-1-4244-4113-6, Library of Congress: 2009901330, DOI: 10.1109/INES.2009.4924770, April 16-18, 2009. **WoS** link
- c18⁽³¹²⁾ Gyula Mester: Obstacle Avoidance and Velocity Control of Mobile Robots, Proceedings of the 6th Serbian-Hungarian Joint Symposium on Intelligent Systems and Informatics SISY 2008, pp. 97-101, Subotica, Serbia, Sept. 26-27, 2008. **WoS** link
- c19⁽³¹³⁾ Simon János, Mobil robotok az oktatásban, A Magyar Tudomány Napja a Délvidéken 2012.11.24, VMTT, pp. 477-487, ISBN 978-86-88077-04-0, Újvidék, Szerbia, 2013. „Ezekre az alkalmazásokra jellemző, hogy egyidőben több típusú szenzor is információt ad a külvilágáról. Sajnos a mért információk legtöbb esetben olyan mértékben telítettek zajjal, hogy nem lehet teljes mértékben rájuk alapozni a pozíció becslést [13].” **MTMT**
- c20⁽³¹⁴⁾ Winai Chonnaparamutt, A Smart Locomotion Support Component, PhD thesis, pp. 1-140, International University Bremen, School of Engineering and Science, Bremen, Germany, 2007. “More recent examples of behavior-based control systems for dynamic environments that employs fuzzy logic can be found in[113][25][73].” **MTMT**
- c21⁽³¹⁵⁾ Rudra Anil Kumar, G.Murali Krishna, S.Chandra Sekhar , An Efficient Navigation Test Based Remote Control Strategy, International Journal of Reviews on Recent Electronics and Computer Science, pp. 908-912, IJRRECS/October 2013/Volume-1/Issue-6/908-912 ISSN 2321-5461, www.ijrreecs.com , 2013. „And the above operation takes place in the laboratory based aspect with the particular scenario in a well oriented fashion where the it is ready for the calibration aspect respectively [2][3].” **MTMT**

E57. **GooSch** Gyula Mester, "Motion Control of Wheeled Mobile Robots". Proceedings of the 4th International Symposium on Intelligent Systems, SISY 2006, pp. 119-130, ISBN 963 7154 50 7, Subotica, Serbia, 29-30.09.2006. **MTMT/0.2**

- c1⁽³¹⁶⁾ Claudiu Popirlan, Mihai Dupac, „An Optimal Path Algorithm for Autonomous Searching Robots”, Annals of University of Craiova, Math. Comp. Sci. Ser., Volume 36, No. 1, Pages 37–48, ISSN: 1223-6934, , Craiova, Romania, 2009, „Most of the research have been directed to the use of kinematic models of the mobile robots to achieve and accomplished the motion control [12, 11, 14].” **MTMT**
<http://www.inf.ucv.ro/~ami/index.php/ami/article/view/264/258..>
- c2⁽³¹⁷⁾ Claudiu Popirlan, „A Mobile Agents Architecture for Robots Control”, Annals of University of Craiova, Math. Comp. Sci. Ser. Volume 36(2), pp. 109-117, ISSN: 1223-6934, Craiova, Romania, 2009. <http://inf.ucv.ro/~ami2/index.php/ami/article/viewFile/292/283>, **MTMT**
- c3⁽³¹⁸⁾ Claudiu Popirlan, Mihai Dupac, „A Mobile Agent Virtual Reality Modeling of Searching Robots”, Annals of the University of Craiova, Math. Comp. Sci. Ser. Volume 35, pp. 139-148, ISSN: 1223-6934, Craiova, Romania, 2008. „Most of the research have been directed to the use of kinematic models of the mobile robots to achieve and accomplished the motion control [9, 8, 11].” **MTMT**
<http://www.inf.ucv.ro/~ami/index.php/ami/article/viewFile/254/249>
- c4⁽³¹⁹⁾ Ion Iancu, Michaela I. Colhon, Mihai Dupac, „A Takagi-Sugeno Type Controller for Mobile Robot Navigation”, Proceedings of the 4th WSEAS International Conference on Computational Intelligence, pp. 29-34 , ISBN: 978-960-474-179-3, Bucharest, Romania, 20-22 April 2010, „Research on robots has attracted attention in the last years [3] and was mainly directed to the use of kinematic models of the mobile robots to achieve and accomplished the motion control [7, 1, 2].” **MTMT**
<http://www.wseas.us/e-library/conferences/2010/Bucharest/CI/CI-04.pdf>

- c5⁽³²⁰⁾ Parhi, D R & Pothal, J K, "Analysis of Different Technique used for Mobile Robot Navigation", Int. J. of App. Artl. Int. Engg. Stm., Vol. 1, pp. 175-194, 2009. **MTMT**
- c6⁽³²¹⁾ **Scopus** link, Maryna P. Mukhina, „Control Algorithm for Four-Wheeled Robot Motion for Monitoring Problems”, Journal Solid State Phenomena (Volumes 147 - 149), Mechatronic Systems and Materials III, pp. 31-34, DOI 10.4028/www.scientific.net/SSP.147-149.31, January, 2009. **MTMT**
- c7⁽³²²⁾ **Scopus** link, Ion Iancu, Mihaela Colhon, Mihai Dupaca,“ Fuzzy Controller with Various T-norms Applied in Robot Navigation”, WSEAS Transactions on Systems and Control, Issue 11, Volume 5, pp. 882-891, ISSN: 1991-8763, November 2010, „Research on robots has attracted attention in the last years [1] and was mainly directed to the use of kinematic models of the mobile robots to achieve and accomplish the motion control [2 - 6].” **MTMT**
- c8⁽³²³⁾ Simon Janos, Matijevics Istvan, "Autonomous Mobile Robot as a Measuring Station in Controlled Microclimatic Environment", Proceedings of the XXVI. International Kandó Conference 2011, Science in Practice, pp. 1-9, ISBN 978-615-5018-19-0, Budapest, Hungary, 17-18 November, 2011. "LabVIEW includes a visualization features, including tools for charting and graphing and built-in 2D and 3D visualization Fig. 10, so that data can be presented on the user interface of the application". **MTMT**
- c9⁽³²⁴⁾ Simon János, Mobil mérőállomás navigációja kontrollált mikroklimatikus környezetben, VMTT Konferencia, Konferenciakiadvány, pp. 10-20, ISBN &, Újvidék, Szerbia, november 12, 2011.” A mobil mérőállomás több mérési funkciót lát el. Rendelkezik hőmérővel, páratartalom, gyorsulás érzékelőkkel [14].” **MTMT**
- c10⁽³²⁵⁾ Mester Gyula, Intelligent Mobile Robot Motion Control in Unstructured Environments, Acta Polytechnica Hungarica, Vol. 7, No. 4, pp. 153-165, ISSN 1785-88602010, **WoS** link. **MTMT**
- c11⁽³²⁶⁾ Simon Janos, Istvan Matijevics, Remote Control of Anthropomorphic Robotic Platform for Socially Acceptable and Adequate Interaction in Human’s Working Environment, Proceedings of the SIP 2012, 30th International Conference Science in Practice, pp.103-107, ISBN 9789637298530, Pécs, Hungary, October 29-30, 2012. **MTMT**
- c12⁽³²⁷⁾ Ales Obal, Izdelava in vodenje avtonomnega vozila na gošenicah, Proceedings of the AIG’ Conference, pp. 1-7, Maribor, Slovenia, April 4-5, 2012. **MTMT**
- c13⁽³²⁸⁾ M Awadalla, TF Lu, Z Tian, B Dally, Z Liu, "3D framework combining CFD and MATLAB techniques for plume source localization research", Building and Environment, pp. 10-19, ISSN 0360-13232013, DOI: 10.1016/j.builden.2013.07.021, Volume 70, December 2013 <http://www.sciencedirect.com/science/article/pii/S0360132313002205>, “The kinematics model [27] for the robot is given in (1)-(8).”, **WoS** link. **MTMT**
- c14⁽³²⁹⁾ Ng, K. H.; Yeong, C. F.; Su, E. L. M.; et al., " Implementation of Cascade Control for Wheeled Mobile Robot Straight Path Navigation ", 4th International Conference on Intelligent and Advanced Systems (ICIAS), Vol. 1-2, pp. 503-506, Kuala Lumpur, Malaysia, Jun 12-14, 2012. **WoS** link. **MTMT**
- c15⁽³³⁰⁾ Gyula Mester, Obstacle avoidance of mobile robots in unknown environments, Proceedings of the 5th International Symposium on Intelligent Systems and Informatics SISY 2007, pp. 107-111, Subotica, Serbia, Aug. 24-25, 2007. **WoS** link.
- c16⁽³³¹⁾ Simon János, Mobil robotok az oktatásban, A Magyar Tudomány Napja a Délnyugaton 2012 , VMTT, pp. 477-487, ISBN 978-86-88077-04-0, 2012.11.24, Újvidék, Szerbia, 2013. „ A navigációs applikációkban az egyik legfontosabb szerepet a helymeghatározás, a pozíció becslése jelenti [12].” **MTMT**
- c17⁽³³²⁾ Y Favaedi, Prediction of Tractive Response for Flexible Wheels with Application to Planetary Exploration Rovers, PhD thesis, pp. 1-163, University of Surrey, epubs.surrey.ac.uk, Guildford, Surrey, UK, 2010. **MTMT**
- c18⁽³³³⁾ R.B.Meshram, Tracking and Formation of Wheeled Mobile Robot Using Fuzzy Logic, International Journal of Inventive Engineering and Sciences (IJIES) ISSN: 2319–9598, Volume-2, Issue-2, pp. 18-22, January 2014. “The kinematic model for mobile robots which in our case is a car like model is quite commonly used as given in [1][2][3].” **MTMT**
- c19⁽³³⁴⁾ Carlos A. Vargas, Juan M. Salazar, Depth profile of the fractal dimension associated to earthquakes distribution in the NW South America, Proceedings of the 6th Chaotic Modeling and Simulation International Conference, 11 - 14 June 2013 Istanbul, Turkey. “For implementation of obstacles avoidance with this method, we need to **MTMT**
- c20⁽³³⁵⁾ Amevi Acakpovi, Salifu Osman, Oluferni O Fatonade, Design of a Fast and Autonomous Complex Line Tracker and Fully Controlled Robot by Limit Switches, International Journal of Computer Applications, Vol. 62, No. 5, pp. 35-42, DOI: 10.5120/10079-4693, 2013.
- c21⁽³³⁶⁾ Gyula Mester, Intelligent Mobil Robot Control in Unknown Environments, Intelligent Engineering Systems and Computational Cybernetics, Part I Intelligent Robotics, pp. 15-26, ISBN 978-1-4020-8677-9, Library of Congress: 2008934137, DOI 10.1007/978-1-4020-8678-6_2, Springer, 2009..
- c22⁽³³⁷⁾ Ingyu Lim , Kira L. Barton, Pareto Iterative Learning Control: Optimized Control for Multiple Performance Objectives, Control Engineering Practice, pp. 125-135, Vol. 26, DOI 10.1016/j.conengprac.2014.01.011, May 2014– Elsevier. **WoS** link.
- c23⁽³³⁸⁾ Rana Soltani-Zarrin, Suhada Jayasuriya, Constrained Directions as a Path Planning Algorithm for Mobile Robots Under Slip and Actuator Limitations, Intelligent Robots and Systems IROS 2014, 2014 IEEE/RSJ International Conference on Intelligent Robots and Systems, 978-1-4799-6934-0/14/\$31.00 ©2014 IEEE, DOI: 10.1109/IROS.2014.6942887,, pp. 2395 - 2400, September 14-18, 2014. „Consequently the

- simulation results from such models do not emulate the real behavior of 2WMRs. In [3] and [4] closedloop controllers are designed for the derived no-slip dynamic models.” **WoS** link.
- c24⁽³³⁹⁾ Gyula Mester, Aleksandar Rodic, "Sensor-Based Intelligent Mobile Robot Navigation in Unknown Environments", International Journal of Electrical and Computer Engineering Systems, Volume 1, Number 2, pp. 55-62, ISSN: 1847-7003, <http://www.etfos.hr/ijeces/index.php/ijeces/article/view/22>, 2010.
- c25⁽³⁴⁰⁾ A.S. Ali, R.V. Fedorenko, V.A. Krukhmalev, Autonomous Mobile Robot Skif-3 Control System for Nonformalized Environment, Известия ЮФУ. Технические науки Тема-тический выпуск, 132-143, УДК 681.511.4, Некоторые современные подходы конструированию систем управления автономных роботов, функционирующих в неформализованных средах, рассмотре-, Раздел III. Наземная робототехника ны в [1-5].'
- E58. Gyula Mester, „Development of XHTML CSS and PHP e-Learning Portal”, Proceedings of the YUINFO’2005, pp. 1-5, Kopaonik, Serbia and Montenegro, 2005. **MTMT/0.2**
- E59. Gyula Mester, „Kriticki osvrt na neka resenja u prednacrtu Zakona o visokom obrazovanju”, Proceedings of the TREND 2005, pp. 1-4, ISBN 86-85211-32-8, Kopaonik, Serbia and Montenegro, 2005. **MTMT/0.2**
- E60. **GooSch** Gyula Mester: „Intelligent e-Learning Portal Development”. Proceedings of the SISY 2004, pp. 137-143, ISBN-963 7154 32 9, Subotica, Serbia and Montenegro, 2004. **MTMT/0.2**
- c1⁽³⁴¹⁾ Zlatko Covic : Implementation and Administration of e-Learning System. Proceedings of the YUINFO’2005, pp. 1-5, Kopaonik, Serbia and Montenegro, 7-11.03.2005. **MTMT**
- c2⁽³⁴²⁾ SU Khalid, A Basharat, AA Shahid, S Hassan: „An adaptive E-learning Framework to supporting new ways of teaching and learning”, Proceedings of the International Conference on Information and Communication Technologies, IEEE ICICT '09, pp. 300-306, ISBN: 978-1-4244-4608-7, DOI: 10.1109/ICICT.2009.5267175, Karachi, Sept. 25, 2009, “The skill categories required to create an online E learning course as compiled by [8] and according to [10,13] are: ”, **WoS** link. **MTMT**
- c3⁽³⁴³⁾ Rasoul Zavaraqi, A View On Electronic Learning Portals, Iranian Information Sciences and Technology Journal, Vol. 24, No. 1, pp. 141-172, 2009. **MTMT**
- c4⁽³⁴⁴⁾ Stantic Molcer Piroska, Integrisana komponenta sistema ucenja digitalne obrade signala implementirana u mreznom okruzenju, doktorska disertacija, pp. 1-100, Univerzitet u Novom Sadu, Fakultet Tehnickih Nauka, 2011. **MTMT**
- E61. Gyula Mester: „Multimedia Presentation the Procedure Based on the D-H Convention”. Proceedings of the 21th International Scientific Conference Information Technology in Education of Informatics, Electrical and Mechanical Engineers, pp. 83-86, ISBN 86-85409-03-9, Subotica, Serbia and Montenegro, 6-7 May, 2004. **MTMT/0.2**
- E62. Gyula Mester: „Web alapú és nyit forráskódú edukációs rendszer fejlesztése”. Proceedings of the 6th International Conference of Food Science, pp. 100-110, ISBN 963 482 676 8, Eds: Hódur C; Kovács E.; Véha A., Szegedi Tudományegyetem, Élelmiszeripari Főiskolai Kar, Szeged, Hungary, 2004.05.20-21. **MTMT/0.2**
- E63. Gyula Mester: "Development and Application of Web-based Open Source Course Management System" Proceedings of the YUINFO’2004, pp. 1-5, Kopaonik, Serbia and Montenegro, 2004. **MTMT**
- c1⁽³⁴⁵⁾ Robert Pinter, e-Learning in Use. Proceedings of the YUINFO’2005, pp. 1-4, Kopaonik, Serbia and Montenegro, 2005. **MTMT/0.2**
- E64. Gyula Mester: "E-learning xHTML és CSS tananyagfejlesztés LAMP környezetben". Tudományos napok, Dunaujváros, Konferenciakiadvány, pp. 411-428, Hungary, 2004. **MTMT/0.1**
- E65. Gyula Mester: "Development of Web Applications Using .NET Technologies". YUINFO’2003, pp. 1-5, Kopaonik, Serbia and Montenegro, 2003. **MTMT/0.2**
- c1⁽³⁴⁶⁾ Robert Pinter, Livia Szedmina: Cognitive Flexibility Theory in Creating e-Learning Materials. Proceedings of the YUINFO’2004, pp. 1-4, Kopaonik, Serbia and Montenegro, 2004. **MTMT**
- E66. Gyula Mester: "XML web szolgáltatások fejlesztése és alkalmazása .NET környezetben", Tudományos Konferencia Európai Kihívások 2, konferenciakiadvány, pp. 40-44, ISBN 9632102363, SZTE, SZÉF, Szeged, 2003, Hungary. **MTMT/0.1**
- c1⁽³⁴⁷⁾ Robert Pinter, Livia Szedmina: Cognitive Flexibility Theory in Creating e-Learning Materials. Proceedings of the YUINFO’2004, pp. 1-4, Kopaonik, Serbia and Montenegro, 2004. **MTMT**
- E67. Szilveszter Pletl, Gyula Mester: "Learning-Expanded Genetic Algorithm in Robot Control". Proceedings of the SISY 2003, pp. 213-220, ISBN-963 7154 19 1, Szabadka, Serbia&Montenegro, 2003. **MTMT/0.1**

- E68. Gyula Mester, Tibor Mester: "Building Applications of XML Web Services". Proceedings of the ISIRR, pp. 435-439, Hunedoara, Romania, 2003.
- E69. **GooSch** Janos Gyeviki, Gyula Mester: "Dynamics of a Servopneumatic Positioning System", Proceedings of the Workshop on Mechatronics, pp. 1-5, Varna, Bulgaria, 28.08.-03.09.2003. **MTMT/0.1**
- c1⁽³⁴⁸⁾ L. Molnar, A. Czmerk: "A pneumatikus hajtás tulajdonságai, és dinamikai modellje" OGÉT 2004 konferencia, XII. Nemzetközi Gépész Találkozó, 208 oldal, Románia, Csíksomlyó, 2004.04.22-25. **MTMT**
 - c2⁽³⁴⁸⁾ L. Molnar, A. Czmerk: "Properties and dynamic behaviour of pneumatic drive" Gépészet 2004, Proceedings of the fourth Conference on Mechanical Engineering p. 701, Budapest, 2004.05.27-28. **MTMT**
 - c3⁽³⁵⁰⁾ A. Czmerk: "Dynamics of a servopneumatic drive" VII. International PhD Workshop, Gliwice, Poland, ISBN 83-922242-0-5, Conference issue: Vol. 343-346. Cracow, Poland, 17-20 July, 2005. **MTMT**
 - c4⁽³⁵¹⁾ L. Molnár, A. Czmerk : "Modellbildung und Simulation des pneumatischen Zylinders" 50. Internationales Wissenschaftliches Kolloquium, Ilmenau 19.-23. September 2005, Proceedings 415-416. **MTMT**
 - c5⁽³⁵²⁾ Molnár L., Czmerk A.: "Linearisation of a Servopneumatic System" Gépészet 2006, Proceedings of the fifth Conference on Mechanical Engineering, Budapest, 2006. 05.25-26. **MTMT**
 - c6⁽³⁵³⁾ Molnár L., Czmerk A.: "Szervopneumatikus hajtás szimulációvizsgálata módosított PID szabályzóval" OGÉT 2006 konferencia, XIV. Nemzetközi Gépész Találkozó, Románia, Marosvásárhely, 2006. 04. 27-30. **MTMT**
- E70. Gyula Mester: "Fuzzy Modeling of Automatic Focusing System for Compact Camera". Proceedings of the XVIII. Scientific Conference The 21st Century as Challenge for the Education and Work of Electro-engineers, pp. 1-8, Pécs, Hungary, 31.05-01.06-2002. **MTMT/0.2**
- E71. **GooSch** Gyula Mester: "Converting Traditional Courses to E-learning". Proceedings of the Informatika a Felsőoktatásban, pp. 1212-1216, Debrecen, Hungary, 2002. **MTMT/0.2**
- c1⁽³⁵⁴⁾ Livia Szedmina, Róbert Pinter: Interactive Multimedia English Course. Proceedings of the Symposium on Intelligent Systems SISY 2004, pp. 145-152, ISBN-963 7154 32 9, Szabadka, Serbia and Montenegro, October 1-2, 2004. **MTMT**
 - c2⁽³⁵⁵⁾ Robert Pinter, Livia Szedmina: Cognitive Flexibility Theory in Creating e-Learning Materials. Proceedings of the YUINFO'2004, pp. 1-4, Kopaonik, Serbia and Montenegro, 8-12.03.2004. **MTMT**
 - c3⁽³⁵⁶⁾ Livia Szedmina, Robert Pinter : Technical English – the e-Way. Proceedings of the YUINFO'2005, pp. 1-4, Kopaonik, Serbia and Montenegro, 7-11.03.2005. **MTMT**
 - c4⁽³⁵⁷⁾ Robert Pinter : Iskustva u primeni e-learning materijala na Višoj tehničkoj školi u Subotici, Proceedings of the Second International Conference on Informatics, Educational Technology and New Media in Education– Vol. 1, pp. 181-188, Sombor, Serbia and Montenegro, 2005. **MTMT**
 - c5⁽³⁵⁸⁾ Livia Szedmina, Robert Pinter : Technical English – The e-Way, Proceedings of the Second International Conference on Informatics, Educational Technology and New Media in Education– Vol. 2, pp. 173-179, Sombor, Serbia and Montenegro, 2005. **MTMT**
 - c6⁽³⁵⁹⁾ Emil Matijevics, KNX Controlled Lighting Over the DALI Network, Acta Technica Corvinienensis, Bulletin of Engineering, Tome IV, ISSN 2067-3809, pp. 65-69, Romania, 2011. **MTMT**
- E72. Gyula Mester: "Savremeni trend modeliranja inteligentnih upravljačkih sistema". Zbornik radova Simpozijuma o racunarskim naukama i informacionim tehnologijama YUINFO'2002, pp. 1-5, Kopaonik, Yugoslavia, 2002. **MTMT/0.2**
- E73. Gyula Mester: "Fuzzy-genetsko modeliranje buke u urbanoj sredini". Zbornik radova Simpozijuma o računarskim naukama i informacionim tehnologijama YUINFO'2000, pp.1-5, Kopaonik, Yugoslavia, 2000. **MTMT/0.2**
- E74. Gyula Mester, Attila Nemes, Szilveszter Pletl, Tibor Mester: "Soft Computing metoda za optimalno modeliranje buke". Zbornik radova Simpozijuma o računarskim naukama i informacionim tehnologijama YUINFO '99, pp. 1-5, Kopaonik, Yugoslavia, 1999. **MTMT/0.05**
- E75. **GooSch** Gyula Mester, Szilveszter Pletl, Attila Nemes, Tibor Mester, "Structure Optimization of Fuzzy Control Systems by Multi-Population Genetic Algorithm". Proceedings of the 6th European Congress on Intelligent Techniques and Soft Computing, EUFIT'98, Vol. 1, pp. 450-456, Aachen, Germany, 7.-10. September 1998. Verlag Mainz, Aachen, Germany. †CCA70918/99 ga98aGMester.
- c1⁽³⁶⁰⁾ Jarmo T. Alander, "An Indexed Bibliography of Genetic Algorithms in Control", Report Series No. 94-1- Control, Updated 2010, Department of Electrical Engineering and Automation, University of Vaasa P.O. Box 700, FIN-65101 Vaasa, ftp://ftp.uwasa.fi/cs/report94-1/gaControlbib.pdf, Finland, 2010. **MTMT**
 - c2⁽³⁶¹⁾ Pletl Szilveszter, Korszerű adaptív, fuzzy és neurális elvű robotirányítási algoritmusok, Budapest University of Technology and Economics, Ph. D. Thesis, pages 102, Budapest, Hungary, 2001. **MTMT**
 - c3⁽³⁶²⁾ Jarmo T. Alander, "An Indexed Bibliography of Genetic Algorithms with Fuzzy Systems", Report Series

- E76. **GooSch** Szilveszter Pletl, Gyula Mester: "A Soft Computing Method for Control of Flexible Joint Robotic Manipulator". Proceedings of the 4 ECPD International Conference on Advanced Robotics and Intelligent Automation", pp. 175-178, Moskva, 1998. **MTMT/0.1**
c1⁽³⁶³⁾ Pletl Szilveszter, Korszerű adaptív, fuzzy és neurális elvű robotirányítási algoritmusok, Budapest University of Technology and Economics, Ph.D. Thesis, pages 102, Budapest, Hungary, 2001. **MTMT**
- E77. Gyula Mester, Attila Nemes, Szilveszter Pletl, Jozsef Varga: "Optimization of Electric Motors by Multi-Population Genetic Algorithm". SYMOPIS, Zbornik radova Jugoslovenskog simpozijuma o operacionim istrazivanjima pp. 8-9, Herceg-Novi, Yugoslavia, 1998. **MTMT/0.05**
- E78. Gyula Mester, Szilveszter Pletl: "Genetic Algorithm Based Structural Optimization of the Fuzzy Control Systems". Proceedings of the 3 ECPD International Conference on Advanced Robotics and Intelligent Automation", pp. 209-214, ISBN 86-7236-008-7, Bremen, Germany, 1997. **MTMT/0.1**
c1⁽³⁶⁴⁾ Pletl Szilveszter, Korszerű adaptív, fuzzy és neurális elvű robotirányítási algoritmusok, Budapest University of Technology and Economics, Ph.D. Thesis, pages 102, Budapest, Hungary, 2001. **MTMT**
- E79. Gyula Mester: "Recent Trend of Intelligent Control System Using Neural Networks, Fuzzy Logic and Genetic Algorithms". Proceedings of the Soft and Intelligent Computing in Control Engineering, SICCE'97, pp. 1-5, ISBN 86-81083-01-5, Subotica, Yugoslavia, 1997.
- E80. Szilveszter Pletl, Bela Lantos, Gyula Mester: "A Method that Guarantees the Stability of Soft-computing Based Controller Robot System During its Adaptation". Proceedings of the Soft and Intelligent Computing in Control Engineering, SICCE'97, pp. 14-17, ISBN 86-81083-01-5, Subotica, Yugoslavia, 1997. **MTMT/0.66**
c1⁽³⁶⁵⁾ Pletl Szilveszter, Korszerű adaptív, fuzzy és neurális elvű robotirányítási algoritmusok, Budapest University of Technology and Economics, Ph.D. Thesis, pages 102, Budapest, Hungary, 2001. **MTMT**
- E81. Gyula Mester, Szilveszter Pletl: "Comparison Between Two Types of Membership Functions of Optimal Fuzzy-Genetic Control". Proceedings of the 13th ISPE/IEE International Conference on CAD/CAM Robotics & Factories of the Future, editor: Hrishi Bera, pp. 453-458, Pereira, Colombia, South America, 15-17 December, 1997. **MTMT/0.1**
c1⁽³⁶⁶⁾ Pletl Szilveszter, Korszerű adaptív, fuzzy és neurális elvű robotirányítási algoritmusok, Budapest University of Technology and Economics, Ph.D. Thesis, pages 102, Budapest, Hungary, 2001. **MTMT**
- E82. **GooSch** Gyula Mester, Szilveszter Pletl: "Application of Intelligent Control Algorithm for Robot Manipulators". Proceedings of the European Symposium on Intelligent Techniques, ERUDIT, pp. 121-125, Bari, Italy, 1997. **MTMT/0.1**
c1⁽³⁶⁷⁾ Dusko Katic: Some Recent Issues in Connectionist Robot Control, Proceedings of the 3rd ECPD International Conference on Advanced Robotics, Intelligent Automation and Acive Systems, Bremen Germany, September 15-17, 1997, pp.79-92. ...Some interesting neuro-fuzzy-genetic control methods have been proposed recently [...] **MTMT**
c2⁽³⁶⁸⁾ Marta Takacs: Investigation on a Special Group of Fuzzy Implication Operators and Fuzzy Inference Mechanisms Using a Simplified Rule Base System. Proceedings of the International Conference on Neural Information Processing and Intelligent Information Systems, Vol. 2, 793-796, Dunedin, New Zealand, 1997.'...A great number of studies on fuzzy implication operators and their influences on the inference mechanisms in fuzzy systems has been published [...]'. **WoS link**. **MTMT**
c3⁽³⁶⁹⁾ Pletl Szilveszter, Korszerű adaptív, fuzzy és neurális elvű robotirányítási algoritmusok, Budapest University of Technology and Economics, Ph.D. Thesis, pages 102, Budapest, Hungary, 2001. **MTMT**
- E83. Gyula Mester, Szilveszter Pletl: "Designing Fuzzy Control Systems in Matlab Environment". Proceedings of YUINFO'96, Simpozijum o računarskoim naukama i informacionim tehnologijama, Brezovica, pp. 209-210, Yugoslavia, 1996. **MTMT/0.1**
c1⁽³⁷⁰⁾ Pletl Szilveszter, Korszerű adaptív, fuzzy és neurális elvű robotirányítási algoritmusok, Budapest University of Technology and Economics, Ph.D. Thesis, pages 102, Budapest, Hungary, 2001. **MTMT**
- E84. Gyula Mester, Szilveszter Pletl: "Structure Optimization of the Adaptive-Neuro-Fuzzy Controller". Proceedings of the XL International Conference ETRAN, pp. 283-286, ISBN 86-80509-20-5, Budva, Yugoslavia, 1996. **MTMT/0.1**
c1⁽³⁷¹⁾ Pletl Szilveszter, Korszerű adaptív, fuzzy és neurális elvű robotirányítási algoritmusok, Budapest University of Technology and Economics, Ph.D. Thesis, pages 102, Budapest, Hungary, 2001. **MTMT**
- E85. Gyula Mester, Szilveszter Pletl: "Application of Optimal Fuzzy-Genetic Control for SCARA Type Robot Manipulators". Proceeding of the 5th International Workshop on Robotics in Alpe-Adria-Danube Region,

- RAAD'96, pp. 525-528, ISBN 963-420-482-1, Budapest, Hungary, 1996. **MTMT/0.1**
- c1⁽³⁷²⁾ Pletl Szilveszter, Korszerű adaptív, fuzzy és neurális elvű robotirányítási algoritmusok, Budapest University of Technology and Economics, Ph.D. Thesis, pages 102, Budapest, Hungary, 2001. **MTMT**
 - c2⁽³⁷³⁾ Pletl Szilveszter, A Lega megvalósításának módozatai, Informatika Korszerű technikái, IKT 2006 konferencia kiadvány, pp. 112-118, Dunaujváros, 17-18.11.2006. **MTMT**
 - c3⁽³⁷⁴⁾ Gyula Mester, Design of the Fuzzy Control Systems Based on Genetic Algorithm for Intelligent Robots, Interdisciplinary Description of Complex Systems 12 (3), pp. 245-254, ISSN 1334-4676, DOI: 10.79 06/indecs.12.3.4, 2014.
- E86. Gyula Mester, Szilveszter Pletl: "Ganfis Control Algorithm of Intelligent Robots". Proceedings of the Second International Conference on Advanced Robotics and Intelligent Automation, pp. 155-160, Vienna, Austria, 1996. **MTMT/0.1**
- c1⁽³⁷⁵⁾ Pletl Szilveszter, Korszerű adaptív, fuzzy és neurális elvű robotirányítási algoritmusok, Budapest University of Technology and Economics, Ph.D. Thesis, pages 102, Budapest, Hungary, 2001. **MTMT**
 - c2⁽³⁷⁶⁾ Pletl Szilveszter, A Lega megvalósításának módozatai, Informatika Korszerű technikái, IKT 2006 konferencia kiadvány, pp. 112-118, Dunaujváros, 17-18.11.2006. **MTMT**
- E87. Gyula Mester: "Design of a Neuro-Fuzzy-Genetic Control Algorithm of Intelligent Robots", Proceedings of the World Automation Congress WAC '96, May 28-30, 1996, Montpellier, France, Soft Computing with Industrial Applications, Recent Trends and Development, Vol. 5, pp. 755-760, ISBN 1-889335-02-9, TSI Press Series, Albuquerque, NM, USA, 1996. **MTMT/0.1**
- E88. J. K. Tar, O. M. Kaynak, J. F. Bitó, I. J. Rudas, D. Mester: "A New Method for Modelling the Dynamic Robot-Environment Interaction Based on the Generalization of the Canonical Formalism of Classical Mechanics". Proceedings of the First International ECPD Conference, pp. 687-692, Athens, Greece, 1995. **MTMT/0.04**
- c1⁽³⁷⁷⁾ Tar, JK; Rudas, IJ; Bitó, JF, Group theoretical approach in using canonical transformations and symplectic geometry in the control of approximately modelled mechanical systems interacting with an unmodelled environment, Robotica, Vol: 15, pp. 163-179, DOI: 10.1017/S0263574797000192, part 2, 1997, WoS link. **MTMT**
 - c2⁽³⁷⁸⁾ Tar, J.K., Rudas, I.J., Bitó, J.F., Kaynak, M.O., Adaptive robot control gained by partial identification using the advantages of symplectic geometry, Proceedings of the 1995 IEEE IECON 21st International Conference on Industrial Electronics, Control, and Instrumentation, Vol.: 1, pp. 75-80, DOI: 10.1109/IECON.1995.483336, ISBN: 0-7803-3026-9, Publisher: IEEE, 06-10 Nov. 1995, Orlando, Florida, WoS link), Tar, J.K., Rudas, I.J., Bitó, J.F., Kaynak, M.O., On the tuning of the free parameters of a new adaptive robot control based on geometric principles of Hamiltonian mechanics, Proceedings, 1997 IEEE International Symposium on Computational Intelligence in Robotics and Automation, CIRA'97., pp. 326-331, DOI: 10.1109/CIRA.1997.613876, ISBN: 0-8186-8138-1, Publisher: IEEE, 10-11 Jul 1997, Monterey, CA, WoS link ?.
 - c3⁽³⁷⁹⁾ Utku Senol, Design by Incorporating Intelligence: Adaptive Structures. Proceedings of the 1996 3rd Biennial Joint Conference on Engineering Systems Design and Analysis, ESDA. Part 2 (of 9); Montpellier; France, 01-04 July 1996. pp. 195-213. 1996.
- E89. Gyula Mester, Pletl Szilveszter, Gizella Pajor, "Fuzzy Rules Set Optimization Using Genetic Algorithm for Robot Manipulator Control with Gear", Proceedings of the V. Simpozijum o elektromehanickim prenosnicima, pp. 231-236, Subotica, Yugoslavia, 1995. **MTM/0.066**
- c1⁽³⁸⁰⁾ Szilveszter Pletl, Korszerű adaptív, fuzzy és neurális elvű robotirányítási algoritmusok, Budapest University of Technology and Economics, Ph.D. Thesis, pages 102, Budapest, Hungary, 2001. **MTMT**
- E90. **GooSch** Gyula Mester, Szilveszter Pletl: "Fuzzy-Neuro Control and its implementation for a Robot Manipulator". Proceedings of the Teaching Fuzzy Systems Joint Tempus Workshop, pp.1-4, ISBN 963-420-464-3, Budapest, Hungary, 14-16 May, 1995. **MTM/0.1**
- c1⁽³⁸¹⁾ Szilveszter Pletl: Fuzzy Logic Based Neural Network Control for SCARA-Type Manipulators. Proceedings of the I International Conference on Advanced Robotics and Intelligent Automation", pp. 99-104, Athens, Greece, 1995. **MTMT**
 - c2⁽³⁸²⁾ Szilveszter Pletl, Neuro-fuzzy control of rigid and flexible-joint robotic manipulator, Proceedings of the 1995 IEEE IECON 21st International Conference on Industrial Electronics, Control, and Instrumentation, Vol. 1, pp. 93-97, ISBN: 0-7803-3026-9, DOI: 10.1109/IECON.1995.483339, Orlando, Florida, USA, 06 - 10 Nov 1995. **MTMT**
 - c3⁽³⁸³⁾ Marta Takacs: Fuzzy Control of Dynamic Systems Based on Possibility and Necessity Measures. Proceedings of the 5TH International Workshop on Robotics in Alpe-Adria-Danube Region RAAD'96, pp. 515-519, Budapest, Hungary, June 10-13, 1996. **MTMT**
 - c4⁽³⁸⁴⁾ I.J. Rudas, J.F. Bitó, J.K. Tar, M.O. Kaynak: A Multiple-Purpose Uniform Structure for Use in Dynamic Control of Mechanical Devices. Proceedings of the 1996 ASME Engineering Systems Design and Analysis Conference ESDA'96, July 1-4, 1996, Montpellier, France. Vol. 2. pp. 215-220. **MTMT**

c5⁽³⁸⁵⁾ Szilveszter Pletl, Korszerű adaptív, fuzzy és neurális elvű robotirányítási algoritmusok, Budapest University of Technology and Economics, Ph.D. Thesis, pages 102, Budapest, Hungary, 2001. **MTMT**

E91. Gyula Mester, Szilveszter Pletl: "Fuzzy Control of Robot Manipulators with joint Flexibility". Zbornik radova XXI Jugoslovenskog kongresa teorijske i primenjene mehanike, pp. 127-132, Niš, Yugoslavia, 1995. **MTMT/0.1**

c1⁽³⁸⁶⁾ Szilveszter Pletl, Korszerű adaptív, fuzzy és neurális elvű robotirányítási algoritmusok, Budapest University of Technology and Economics, Ph.D. Thesis, pages 102, Budapest, Hungary, 2001. **MTMT**

E92. **GooSch** Gyula Mester, Szilveszter Pletl, Gizella Pajor: "Fuzzy Adaptive Control of Robot Manipulators". Proceedings of the International Conference ETRAN, pp. 252-255, ISBN 86-80509-16-7, Zlatibor, Yugoslavia, June 6-9, 1995. **MTM/0.066**

c1⁽³⁸⁷⁾ Szilveszter Pletl, Zoltan Jeges, "Hierarchical Fuzzy-Adaptive Control Algorithm", Proceedings SISY 2004, pp.241-246, Subotica October 1-2, 2004. „This paper introduces a fuzzy supervisor for the coordination of the free parameters of the adaptive controller. In the technical literature several works deal with the similar application of fuzzy theory [1,3]”. **MTMT**

c2⁽³⁸⁸⁾ Pletl Szilveszter, Korszerű adaptív, fuzzy és neurális elvű robotirányítási algoritmusok, Budapest University of Technology and Economics, Ph.D. Thesis, pages 102, Budapest, Hungary, 2001. **MTMT**

E93. Gyula Mester, Szilveszter Pletl, Gizella Pajor: "Neuro-Fuzzy Control of Robot Manipulator with Joint Flexibility", Proceedings of the International Conference Automation'95, pp.423-432, ISBN 963-420-464-3, Budapest, Hungary, 1995. **MTMT/0.066**

c1⁽³⁸⁹⁾ Pletl Szilveszter, Korszerű adaptív, fuzzy és neurális elvű robotirányítási algoritmusok, Budapest University of Technology and Economics, Ph.D. Thesis, pages 102, Budapest, Hungary, 2001. **MTMT**

E94. **GooSch** Gyula Mester: "Neuro-Fuzzy-Genetic Trajectory Tracking Control of Flexible Joint robots". Proceedings of the I International Conference on Advanced Robotics and Intelligent Automation", pp. 93-98, Athens, Greece, 1995. **MTMT/0.2**

c1⁽³⁹⁰⁾ Marta Takacs: Fuzzy Control of Dynamic Systems Based on Possibility and Necessity Measures. Proceedings of the 5TH International Workshop on Robotics in Alpe-Adria-Danube Region RAAD'96, pp. 515-519, Budapest, Hungary, June 10-13, 1996. **MTMT**

c2⁽³⁹¹⁾ Szilveszter Pletl: Korszerű adaptív, Fuzzy és Neurális elvű Robotirányítási algoritmusok, PhD értekezés, Budapest, Budapesti Műszaki és Gazdaságtudományi Egyetem, 2001. **MTMT**

c3⁽³⁹²⁾ Janos Gyeviki, Kalman Rozsahegyi: Sliding Mode Control of a servopneumatic Positioning System University of Szeged, College Faculty of Food Engineering Szegedi Tudományegyetem Szegedi Élelmiszeripari Főiskolai Kar, Tudományos Közlemények 24, pp.65-69, Szeged, 2003. **MTMT**

c4⁽³⁹³⁾ Janos Gyeviki, Kalman Rozsahegyi: DSP-based Control of a servopneumatic Positioning System. University of Szeged College Faculty of Food Engineering, Szegedi Tudományegyetem, Szegedi Élelmiszeripari Főiskolai Kar, Tudományos Közlemények 24, pp.60-64, Szeged, 2003. **MTMT**

c5⁽³⁹⁴⁾ Janos Gyeviki: Nemlíneáris holtidős szabályozási körök vizsgálata. Proceedings of the SZTE, SZÉF, pp. 11-15, Szeged, Hungary, 2003. **MTMT**

c6⁽³⁹⁵⁾ Janos Gyeviki, Zoltan Fabulya, Pneumatic Positioning with Intelligent Control, Proceeding of the 3rd International Scientific Days of Land Management in the Great Hungarian Plan 2002, Vol. IV, pp. 21-25, Mezőtúr, Hungary, 2002. **MTMT**

c7⁽³⁹⁶⁾ Janos Gyeviki, Istvan Tibor, Kalman Rozsahegyi: Sliding Mode Control and its Application on a Servopneumatic Positioning System, Scientific Bulletin of Politehnica Universiti of Timisoara, Vol. 49 (63), No. 1, pp. 99-104, Timisoara, Romania, 2004. **MTMT**

c8⁽³⁹⁷⁾ Janos Gyeviki: Pneumatikus rendszerek pozícionálási pontosságának a növelése, Proceeding of the XI. International Conference and Exhibition on Pneumatics and Hydraulics, pp. 141-146, Miskolc, Hungary, 2004. ... Napjainkban az intelligens (soft computing) rendszerek alkalmazása is terjed [...] **MTMT**

c9⁽³⁹⁸⁾ Janos Gyeviki: Improving Positioning Accuracy of Pneumatic Systems, Gép, LV évfolyam, 9 szám, pp.: 7-11, 2004. ... Another solution is to employ the advanced nonlinear control startegies developed in recent years (soft computing) [...] **MTMT**

c10⁽³⁹⁹⁾ Janos Gyeviki and Attila Csizar: DSP Based Positioning in Practice, Proceeding of the 6thInternational Carpathian Control Conference, ICCC'2005, Vol. I, pp. 407-412, Miskolc- Lillafüred, Hungary, 2005...Another solution is to employ the advanced nonlinear control strategies developed in recent years (soft computing)[...] **MTMT**

c11⁽⁴⁰⁰⁾ Janos Gyeviki, Kalman Rozsahegyi and Attila Csizar: Chattering Reduction in Sliding Mode Control of Pneumatic Actuator, Proceeding of the 6thInternational Carpathian Control Conference, ICCC'2005, Vol. II, pp. 421-426, Miskolc- Lillafüred, Hungary, 2005...Another solution is to employ the advanced nonlinear control strategies developed in recent years (soft computing)[...] **MTMT**

c12⁽⁴⁰¹⁾ Janos Gyeviki, Attila Csizar „DSP-k gyakorlati alkalmazása a folyamatirányításban” Acta Agria Kaposváriensis, Vol 10, No 1, pp. 166-176 ISSN 1418-1789, Kaposvár, Hungary, 2006. **MTMT**

c13⁽⁴⁰²⁾ Janos Gyeviki, Zoltan Csiszmadia, Antal Veha: “Experimental Investigation of On-Off Valves Controlled Pneumatic Positioning System” XII. Nemzetközi Pneumatika - Hidraulika Konferencia és Kiállítás Miskolc/Eger 2007. szept. 17-19. **MTMT**

- c14⁽⁴⁰³⁾ Janos Gyeviki, Sarosi J., Endrody T., Forgacs E., Toman P.: LabVIEW based position control for a pneumatic cylinder, Annals of Faculty of Engineering, International Journal of Engineering, Vol. 8, No. 1, pp. 25-32, ISSN 1584-2665, Hunedoara, Romania, „Another solution is to employ the advanced nonlinear control strategies developed in recent years(soft computing)” [5], 2010. **MTMT**
- c15⁽⁴⁰⁴⁾ Patricia Grof, Janos Gyeviki, Antal Veha, Zoltan Petres, Peter Korondi, Tensor Product Model Transformation Based Control of a Pneumatic Cylinder, Proceedings of the CINTI 2008, Vol. 3, pp. 21-26, 2008. **MTMT**
- c16⁽⁴⁰⁵⁾ Janos Gyeviki, Szervopneumatikus pozícionálás pontosságának növelése DSP alapú csúszómód szabályozással, doktori disszertáció, Debreceni Egyetem, 115, 2007. **MTMT**
- c17⁽⁴⁰⁶⁾ P. Toman, Janos Gyeviki, Antal Veha, Position Control of Pneumatic Actuators with PLC, Review of Faculty of Engineering, Analecta Technica Szegedinensia, pp. 97-106, 2012/1-2, ISSN 1788-6392, “Another solution is to employ the advanced nonlinear control strategies developed inrecent years (soft computing)[4][5].”, 2012. **MTMT**
- c18⁽⁴⁰⁷⁾ Janos Gyeviki, Kalman Rozsahegyi and Attila Csiszar, Sliding modes application in pneumatic positioning, Proceedings of the IEEE International Conference on Mechatronics (ICM), pp. 964-969 Taipei, Taiwan, Jul 10-12, 2005, **WoS** link. **MTMT**

E95. Gyula Mester: "Neuro-Fuzzy-Genetic Algorithm of Intelligent Robots". Proceeding of the 3rd Seminar on Neural Network Applications in Electrotechnics Neurel-95, pp. 136-141, Beograd, Yugoslavia, 1995. **MTMT/0.2**

E96. **GooSch**, **WoS/Scopus** link, Gyula Mester, "Neuro-Fuzzy-Genetic Controller Design for Robot Manipulators", Proceedings of the IEEE IECON'95, International Conference on Industrial Electronics, Control and Instrumentation, Orlando, Vol. 1, pp. 87-92, DOI 10.1109/IECON.1995.483338, ISBN 0-7803-3026-9, Florida, USA, November 6-10, 1995, IEEE, New York, NY. †CCA28816/95 ga95bMester. **MTMT/0.2**

- c1⁽⁴⁰⁸⁾ Jarmo T. Alander, “An Indexed Bibliography of Genetic Algorithms with Fuzzy Logic”, Department of Electrical Engineering and Automation, University of Vaasa, Vaasa, Finland:
Book: Fuzzy evolutionary computation, Editor: Witold Pedrycz Univ. of Manitoba, Winnipeg, Man., Canada. Publication: Kluwer Academic Publishers Norwell, MA, USA ©1997, ISBN:0-7923-9942-0, Book Chapter: Jarmo T. Alander, “An indexed bibliography of genetic algorithms with fuzzy logic”, pp: 299 – 318, 1997. **MTMT**
- c2⁽⁴⁰⁹⁾ Alavandar, S.; Nigam, M.J.; “Genetic Fuzzy Based Tracking Control of 3 DOF Robot Arm”, Proceedings of the Emerging Trends in Engineering and Technology, 2008. ICETET '08. First International Conference on Emerging Trends in Engineering and Technology, pp. 547 – 552, ISBN: 978-0-7695-3267-7, DOI: 10.1109/ICETET.2008.75, Nagpur, Maharashtra India, 16 – 18 July 2008. **MTMT**
- c3⁽⁴¹⁰⁾ Srinivasan A., Intelligent Control of Robot Manipulators Using Soft Computing Techniques, PhD Thesis, Department of Electronics and Computer Engineering, Indian Institute of Technology Roorke, India, 2008. **MTMT**
- c4⁽⁴¹¹⁾ Jarmo T. Alander, “An Indexed Bibliography of Genetic Algorithms in Control”, Report Series No. 94-1-CONTROL, Updated 2010, Department of Electrical Engineering and Automation, University of Vaasa, Vaasa, ftp://ftp.uwasa.fi/cs/report94-1/gaControlLlib.pdf, Finland, 2010. **MTMT**
- c5⁽⁴¹²⁾ Chin-Shyurng Fahn; Kou-Torng Lan; Zen-Bang Chern, “Fuzzy Rules Generation Using New Evolutionary Algorithms Combined with Multilayer Perceptrons”, Industrial Electronics, IEEE Transactions on Finland, Vol. 46, Issue: 6, pp. 1103-1113, ISSN: 0278-0046, DOI: 10.1109/41.807995, 2002. **MTMT**
- c6⁽⁴¹³⁾ Andon Venelinov Topalova, Jong-Hwan Kim and Todor Philipov Proycheva, “Fuzzy-Net Control of Non-Holonomic Mobile Robot Using Evolutionary Feedback-Error-Learning”, Robotics and Autonomous Systems, Volume 23, Issue 3, Pages 187-200, 2 April 1998, **WoS** link. **MTMT**
- c7⁽⁴¹⁴⁾ Rameri Salama, “On Evolving Modular Neural Networks”, PhD thesis, Department of Computer Science, University of Western Australia, May 2000. **MTMT**
- c8⁽⁴¹⁵⁾ A. N. Poo, P. L. Tang, “Intelligent Control of Mashines”, pp. 245-288, Book: “Intelligent machines: myths and realities”, edited by Clarence W. de Silva, Published: Boca Raton, FL : CRC Press, ISBN: 0849303303, 2000. **MTMT**
- c9⁽⁴¹⁶⁾ H. Sayyaadi and A.A. Eftekharian, Modeling and Intelligent Control of a Robotic Gas Metal Arc Welding System, Scientia Iranica, Vol. 15, No. 1, pp 75-93, Sharif University of Technology, February, 2008, **WoS** link, „Mester, in [19], developed a neuro-fuzzy-genetic controller for robot manipulators; he applied the genetic algorithm for the fuzzy rules set optimization.”. **MTMT**
- c10⁽⁴¹⁷⁾ Janos Gyeviki, Kalman Rozsahegyi: Sliding Mode Control of a servopneumatic Positioning System University of Szeged College Faculty of Food Engineering Szegedi Tudományegyetem Szegedi Élelmiszeripari Főiskolai Kar, Tudományos Közlemények 24, pp.65-69, Szeged, Hungary, 2003. **MTMT**
- c11⁽⁴¹⁸⁾ Janos Gyeviki, Kalman Rozsahegyi: DSP-based Control of a Servopneumatic Positioning System. University of Szeged College Faculty of Food Engineering Szegedi Tudományegyetem Szegedi Élelmiszeripari Főiskolai Kar, Tudományos Közlemények 24, pp.60-64, Szeged, Hungary, 2003. **MTMT**
- c12⁽⁴¹⁹⁾ Janos Gyeviki: Nemlíneáris holtidős szabályozási körök vizsgálata. Proceedings of the SZTE, SZÉF, pp.

- 11-15, Szeged, Hungary, 2003. **MTMT**
- c13⁽⁴²⁰⁾ Janos Gyeviki, Zoltán Fabulya: Pneumatic Positioning with Intelligent Control, Proceedings of the 3rd International Scientific Days of Land Management in the Great Hungarian Plan, Vol. IV. pp. 21-25, Mezőtúr, Hungary 2002. **MTMT**
- c14⁽⁴²¹⁾ Janos Gyeviki, Istvan Tibor, Kalman Rozsahegyi: Sliding Mode Control and its Application on a Servopneumatic Positioning System, Scientific of Timisoara Bulletin of Politehnica Universiti, Volume 49 (63), No. 1. pp.:99-104, Timisioara, Romania, 2004. **MTMT**
- c15⁽⁴²²⁾ Janos Gyeviki: Pneumatikus rendszerek pozícionálási pontosságának a növelése, Proceedings of the XI. International Conference and Exhibition on Pneumatics and Hydraulics, pp. 141-146, Miskolc, 2004. „Napjainkban az intelligens (soft computing) rendszerek alkalmazása is terjed [].” **MTMT**
- c16⁽⁴²³⁾ Janos Gyeviki: Improving Positioning Accuracy of Pneumatic Systems, Gép, LV évfolyam, 9 szám, pp.: 7-11, 2004. ... Another solution is to employ the advanced nonlinear control startegies developed in recent years (soft computing) [...]... **MTMT**
- c17⁽⁴²⁴⁾ Janos Gyeviki and Attila Csiszar: DSP Based Positioning in Practice, Proceeding of the 6thInternational Carpathian Control Conference, ICCC'2005, Vol. I, pp. 407-412, Miskolc- Lillafüred, Hungary, 2005...Another solution is to employ the advanced nonlinear control strategies developed in recent years (soft computing)[...]... **MTMT**
- c18⁽⁴²⁵⁾ Janos Gyeviki, Kalman Rozsahegyi and Attila Csiszar: Chattering Reduction in Sliding Mode Control of Pneumatic Actuator, Proceeding of the 6thInternational Carpathian Control Conference, ICCC'2005, Vol. II, pp. 421-426, Miskolc- Lillafüred, Hungary, 2005... Another solution is to employ the advanced nonlinear control strategies developed in recent years (soft computing)[...]... **MTMT**
- c19⁽⁴²⁶⁾ Janos Gyeviki, Attila Csiszar, Kalman Rozsahegyi: Sliding modes application in pneumatic positioning, Proceedings of the 2005 IEEE International Conference on Mechatronics, ICM '05, pp. 964-969, ISBN: 0-7803-8998-0, DOI: 10.1109/ICMECH.2005.1529392, Taipei, Taiwan, July 10-12, 2005, **WoS** link. **MTMT**
- c20⁽⁴²⁷⁾ Janos Gyeviki, Zoltán Csizmazia and Antal Veha: Position Control of a Pneumatic Actuator Using High Speed On-Off Valves, Proceeding of the Európai Kihívások IV. Nemzetközi Tudományos Konferencia, pp. 661-666, ISBN 978-963-482-857-0, Szeged, Hungary, 2007... Another solution is to employ the advanced nonlinear control strategies developed in recent years (soft computing)[...]... **MTMT**
- c21⁽⁴²⁸⁾ J. Gyeviki; Z. Csizmazia; A. Veha; "Low-Cost, High Performance Pneumatic Positioning System with On-Off Valves" Proceedings of the 9th International Symposium Interdisciplinary Regional Research "ISIRR 2007" Hungary – Serbia – Romania, pp. 49, Novi Sad, 2007. **MTMT**
- c22⁽⁴²⁹⁾ J. Gyeviki J., Sarosi J., Endrody T., Forgacs E., Veha A., Szabo Z.: Sliding-mode control of pneumatic muscle for robot application. Review of Faculty of Engineering, Analecta Technica Szegedinensis, Faculty of Engineering, University of Szeged, Szeged, 2009, ISSN 1788-6392, pp. 28-35 **MTMT**
- c23⁽⁴³⁰⁾ Sarosi J., Gyeviki J., Szabo G., Szendro P.: Pneumatikus izmok pozícionálása csúszómód szabályozással, Gép, Vol. 60, No. 8, ISSN 0016-8572, pp. 45-48, 2009. **MTMT**
- c24⁽⁴³¹⁾ Toman P., Gyeviki J., Endrody T., Sarosi J., Veha A., Szabo Z.: Sliding-mode control of a robot arm driven by pneumatic muscle actuators, Annals of Faculty of Engineering Hunedoara, International Journal of Engineering, Vol. 7, No. 4, ISSN 1584-2665, pp. 95-100, „Another solution is to employ the advanced nonlinear control strategies developed in recent years (soft computing) [10] ”, 2009. **MTMT**
- c25⁽⁴³²⁾ Sarosi J., Gyeviki J., Veha A., Toman P.: Accurate position control of PAM Actuator in LabVIEW Environment, Proceedings of the IEEE 7th International Symposium on Intelligent Systems and Informatics, Subotica, Serbia, ISBN : 978-1-4244-5348-1, DOI: 10.1109/SISY.2009.5291145, pp. 272-276, September 25-26, 2009, **WoS** link. **MTMT**
- c26⁽⁴³³⁾ Janos Gyeviki, Sarosi J., Veha A., Toman P.: Sliding-mode Control of PAM Actuator in LabVIEW Environment, Jelenkorú Társadalmai és Gazdasági Folyamatok, Szegedi Tudományegyetem, Mérnöki Kar, Vol. 5, No. 1-2, ISSN 1788-7593, pp. 249-253, 2010. **MTMT**
- c27⁽⁴³⁴⁾ Janos Gyeviki, Sarosi J., Endrody T., Forgacs E., Toman P.: LabVIEW based position control for a pneumatic cylinder, Annals of Faculty of Engineering Hunedoara, International Journal of Engineering, Vol. 8, No. 1, ISSN 1584-2665, pp. 25-32, Hunedoara, Romania, 2010. **MTMT**
- c28⁽⁴³⁵⁾ Jarmo T. Alander, “Indexed Bibliography of Genetic Algorithms in Robotics”, Adaptive Behavior, Vol. 299, pages 437, University of Vaasa, Department of Information Technology and Production Economics, Vaasa, Finland, 1996. **MTMT**
- c29⁽⁴³⁶⁾ Janos Gyeviki J., Csiszar A.: DSP-k gyakorlati alkalmazása a folyamatirányításban, Acta Agrisa, Kaposváriensis, Vol. 10, No. 1, ISSN 1418-1789, pp. 166-176, Kaposvár, Hungary. **MTMT**
- c30⁽⁴³⁷⁾ Patricia Grof, Janos Gyeviki, Antal Veha, Zoltan Petres, Peter Korondi, Tensor Product Model Transformation Based Control of a Pneumatic Cylinder, Proceedings of the CINTI 2008, Vol. 3, pp. 21-26, 2008. **MTMT**
- c31⁽⁴³⁸⁾ Janos Gyeviki, Z. Csizmazia, Antal Veha, Experimental Investigation of On-Off Valves Controlled Pneumatic Positioning System, Proceedings of the XII. Nemzetközi Pneumatika-Hidraulika Konferencia és Kiállítás Miskolc/Eger, pp. 43-53, szept. 17-19, 2007. **MTMT**
- c32⁽⁴³⁹⁾ Janos Gyeviki, „Szervopneumatikus pozícionálás pontosságának növelése DSP alapú csúszómód szabályozással”, doktori disszertáció, Debreceni Egyetem, pp. 115, 2007. **MTMT**
- c33⁽⁴⁴⁰⁾ Srinivasan Alavandar, M. J. Nigam; “Tracking Control of 3-DOF Robot Manipulator Using Genetic Algorithm Tuned Fuzzy PID Controller”, Journal of Theoretical and Applied Information Technologie,

- Vol.3, No. 4, pp. 15-24, JATIT, 01-06-2007, „Mester in [15] developed a neuro- fuzzy-genetic controller for robot manipulators; he applied the genetic algorithm to optimize the fuzzy rule set.” **MTMT**
- c34⁽⁴⁴¹⁾ Ata Allah Eftekharian; Hassan Sayyadi; “ Design of Mixed Fuzzy-GA Controller For SCARA Type Robot”, IROS, International Conference on Intelligent Robots and Systems, 2006 IEEE/RSJ, Vols 1-12, pp. 2173 - 2178, ISBN: 1-4244-0259-X, 10.1109/IROS.2006.282556, DOI: 10.1109/IROS.2006.282556, Beijing, China, October 9-13, 2006. „Mester in [9] developed a neuro- fuzzy-genetic controller for robot manipulators; he applied the genetic algorithm to optimize the fuzzy rule set.” **WoS** link **MTMT**
- c35⁽⁴⁴²⁾ Leung RWK, Lau HCW, Kwong CK, “An Expert System to Support the Optimization of Ion Plating Process: an OLAP-Based Fuzzy-Cum-GA Approach”, Journal: Expert Systems with Applications, Volume: 25, Issue: 3, pages: 313-330, DOI: 10.1016/S0957-4174(03)00071-X., Hong Kong, Peoples R China, published: Oct, 2003, **WoS** link. **MTMT**
- c36⁽⁴⁴³⁾ A N Poo, P L Tang, “Intelligent Control of Mashines”, In: Clarence W de Silva: Intelligent Mashines. Published: Boca Raton, FL: CRC Press, 2000, pp. 245-288, 2000, **WoS** link. **MTMT**
- c37⁽⁴⁴⁴⁾ P. Toman, Janos Gyeviki, Antal Veha, Position Control of Pneumatic Actuators with PLC, Review of Faculty of Engineering, Analecta Technica Szegedinensis, pp. 97-106, 2012/1-2, ISSN 1788-6392, “Another solution is to employ the advanced nonlinear control strategies developed in recent years (soft computing)[4][5].”, 2012. **MTMT**
- c38⁽⁴⁴⁵⁾ Jarmo T. Alander, Indexed bibliography of genetic algorithms with fuzzy systems, Department of Electrical and Energy Engineering: Automation University of Vaasa, Finland. Report Series No. 94-1-Fuzzy, (Updated 2012/09/21), 2012.

E97. **GooSch** Gyula Mester, Szilveszter Pletl, Gizella Pajor, and Imre Rudas. Adaptive Control of Robot Manipulators with Fuzzy Supervisor Using Genetic Algorithms. Proceedings of International Conference on Recent Advances in Mechatronics, ICRAM'95, O. Kaynak (ed.), Volume 2, pages 661–666, Istanbul, Turkey, ISBN 975-518-063-X, 14.-16. August 1995. Bogazici University Bebek, Istanbul. †CCA72953/97ga95aGMester. **MTMT/0.05**

- c1⁽⁴⁴⁶⁾ Agnes Szeghegyi, Andrea Rudas, Jozsef K. Tar: On Construction of Generalized Non Monotone Fuzzy Operators. Proceedings of the IEEE International Conference on Intelligent Engineering Systems (INES 1997), Budapest, Hungary, September 15-17, 1997, ISBN 0-7803-3627-5, pp. 295-299, **WoS** link. **MTMT**
- c2⁽⁴⁴⁷⁾ Marta Takacs, „Fuzzy Control of Dynamic Systems Based on Possibility and Necessity Measures”, pp. 515-519, Proceedings of the 5th International Workshop on Robotics in Alpe-Adria-Danube Region RAAD'96, ISBN 9634204821, Hungarian Robotics Association, Budapest, Hungary, June 10-13, 1996. **MTMT**
- c3⁽⁴⁴⁸⁾ Szilveszter Pletl, Korszerű adaptív, fuzzy és neurális elvű robotirányítási algoritmusok, Budapest University of Technology and Economics, Ph.D. Thesis, pages 102, Budapest, Hungary, 2001. **MTMT**
- c4⁽⁴⁴⁹⁾ Szilveszter Pletl, Korszerű adaptív, fuzzy és neurális elvű robotirányítási algoritmusok, Budapest University of Technology and Economics, Ph.D. Thesis, pages 102, Budapest, Hungary, 2001.
- c5⁽⁴⁵⁰⁾ Jarmo T. Alander, Indexed bibliography of genetic algorithms papers of 1996, University of Vaasa, Department of Information Technology and Production Economics, 1996.
- c6⁽⁴⁵¹⁾ Jarmo T. Alander, Indexed bibliography of genetic algorithms in robotics, University of Vaasa, Department of Information Technology and Production Economics, Report Series No. 94-1-ROBOT, 1998.
- c7⁽⁴⁵²⁾ Jarmo T. Alander, “An Indexed Bibliography of Genetic Algorithms in Control”, Report Series No. 94-1-Control, Updated 2010, Department of Electrical Engineering and Automation, University of Vaasa P.O. Box 700, FIN-65101 Vaasa, <ftp://ftp.uwasa.fi/cs/report94-1/gaControlbib.pdf>, Finland, 2010. **MTMT**
- c8⁽⁴⁵³⁾ Jarmo T. Alander, Indexed bibliography of genetic algorithms with fuzzy systems, Department of Electrical and Energy Engineering: Automation University of Vaasa, Finland. Report Series No. 94-1-Fuzzy, (Updated 2012/09/21 13:56), 2012.

E98. J. Rudas, Á. Szeghegyi, F. N-Nagy, Gy. Mester: "A Theoretical Approach to Performance Improvement of Fuzzy Logic Controllers", Intelligent Manufacturing Systems, Proceedings of the 3nd IFAC/IFIP/IFORS Workshop, Vol. 2, pp.410-414, Bucharest, Romania, 1995.

E99. **GooSch** Gyula Mester, Pletl Szilveszter, Gizella Pajor, Djuro Basic: "Adaptive Control of Rigid-Link Flexible-Joint Robots". Proceedings of 3rd International Workshop of Advanced Motion Control, pp. 593-602, Berkeley, USA, 1994. **MTMT/0.05**

- c1⁽⁴⁵⁴⁾ Imre J. Rudas, Okyay Kaynak, Janos F. Bito, Agnes Szeghegyi: New Possibilities in Fuzzy Controllers Design Using Generalized Operators. 5th International Conference on Emerging Technologies and Factory Automation, ETFA'96, November 1996. Kauai, Hawaii, USA, pp. 513-517. **MTMT**
- c2⁽⁴⁵⁵⁾ Agnes Szeghegyi, Andrea Rudas, Jozsef K. Tar: On Construction of Generalized Non Monotone Fuzzy Operators. Proceedings of the IEEE International Conference on Intelligent Engineering Systems (INES 1997), Budapest, Hungary, September 15-17, 1997, ISBN 0-7803-3627-5, pp. 295-299. **MTMT**
- c3⁽⁴⁵⁶⁾ M. Bely, P. Hausel: Simulation Tool for Designing Simple Fuzzy Logic Controllers. Proceedings of the 5TH International Workshop on Robotics in Alpe-Adria-Danube Region RAAD'96, pp. 257-262,

- Budapest, Hungary, June 10-13, 1996, **MTMT**
c4⁽⁴⁵⁷⁾ Imre J. Rudas, Agnes Szeghegyi, Janos F. Bito, G. Geary: Non Monotone Generalized Fuzzy Operations for Fuzzy Logic Controllers. Proceedings of the 5TH International Workshop on Robotics in Alpe-Adria-Danube Region RAAD'96, Budapest, Hungary, June 10-13, 1996, pp. 529-533. **MTMT**
- c5⁽⁴⁵⁸⁾ Imre J. Rudas, Janos F. Bito, Jozsef K. Tar, Okyay Kaynak: A Multiple-Purpose Uniform Structure for Use in Dynamic Control of Mechanical Devices. Proceedings of the ASME Engineering Systems Design and Analysis Conference ESDA'96, Vol. 2., pp. 215-220, Montpellier, France, July 1-4, 1996. **MTMT**
- c6⁽⁴⁵⁹⁾ Imre J. Rudas, M. Dinev: New Types Of Generalized Operations. Teaching Fuzzy Systems Joint TEMPUS Workshop. Budapest, Hungary 1997. **MTMT**
- c7⁽⁴⁶⁰⁾ Imre J. Rudas, Agnes Szeghegyi, Janos F. Bito, Okyay Kaynak: Improvement of Fuzzy Logic Robot Controllers Using Inverse Entropy Based T-Operations. Proceedings of the International Conference on Robotics and Automation, pp. 2598-2604. Minneapolis, USA. April 22-29, 1996. The simulation package was developed by Mester, *et al.*, []... **MTMT**
- c8⁽⁴⁶¹⁾ Imre J. Rudas, Janos F. Bito, Agnes Szeghegyi, A. Asboth: On Design of Fuzzy Robot Controllers. Proceedingds of the International Conference on Power Electronics (ICPE'95), pp. 38-44. October, 1995, Seoul, Korea. „The simulation package was developed by Mester et al. []”. **MTMT**
- c9⁽⁴⁶²⁾ Istvan Matijevics, Mikrovezérlőt tartalmazó elektronikai berendezések megbízhatóságvizsgálata Markov módszerrel, Markov Models In Reliability Analysis Of Electronic Systems With Microcontrollers, Informatika a felsőoktatásban, augusztus 24-26, 2005, pp. 137-138, Debrecen, 2005. **MTMT**
- c10⁽⁴⁶³⁾ Marta Takacs, Zsolt Baky, Parametrized Program-interface for Simulation-based Operator Evaluation. Proceedingds of the 2nd Romanian-Hungarian Joint Symposium on Applied Computational Intelligence, Saci, Timisoara, Romania, May 12-14, 2005. **MTMT**
- c11⁽⁴⁶⁴⁾ Pletl Szilveszter, Korszerű adaptív, fuzzy és neurális elvű robotirányítási algoritmusok, Budapest University of Technology and Economics, Ph.D. Thesis, pages 102, Budapest, Hungary, 2001. **MTMT**
- c12⁽⁴⁶⁵⁾ Marta Takacs, System Behavior Change in FLC by Parameter Sliding Using Distance Based Operators, Proceedings of the ICCC 2005. IEEE 3rd International Conference on Computational Cybernetics, pp. 99-103, Mauritius, 13-16 April, 2005. **WoS** link. **MTMT**
- c13⁽⁴⁶⁶⁾ Utku Senol, Design by Incorporating Intelligence: Adaptive Structures. Proceedings of the 1996 3rd Biennial Joint Conference on Engineering Systems Design and Analysis, ESDA. Part 2 (of 9); Montpellier; France, 01-04 July 1996. pp. 195-213. 1996. **MTMT**

E100. Gyula Mester, Pletl Szilveszter, Gizella Pajor: "Neural Network Applications for Rigid-Link Flexible Joints SCARA Robot Motion Control". Proceedings of the International Conference ETRAN, pp. 93-94, ISBN 86-80509-10-8, Nis, Jugoslávia, Juni 7-9, 1994. **MTMT/0.066**
c1⁽⁴⁶⁷⁾ Szilveszter Pletl, Korszerű adaptív, fuzzy és neurális elvű robotirányítási algoritmusok, Budapest University of Technology and Economics, Ph.D. Thesis, pages 102, Budapest, Hungary, 2001. **MTMT**

E101. **GooSch, WoS** Gyula Mester: "Adaptive Force and Position Control of Rigid Link Flexible- Joint Scara Robots". Proceedings of the 20th Annual Conference of the IEEE Industrial Electronics Society IECON'94, Vol. 3, pp. 1639-1644, DOI: 10.1109/IECON.1994.398059, Bologna, Italy, September 1994. **MTMT/0.2**

- c1⁽⁴⁶⁸⁾ Imre J. Rudas, Janos F. Bito, Jozsef K. Tar, Okyay Kaynak: A Multiple-Purpose Uniform Structure for Use in Dynamic Control of Mechanical Devices. Proceedings of the ASME Engineering Systems Design and Analysis Conference ESDA'96, Vol. 2., pp. 215-220, Montpellier, France, July 1-4, 1996. **MTMT**
- c2⁽⁴⁶⁹⁾ Imre J. Rudas, Janos F. Bito, Agnes Szeghegyi, A. Asboth: On Design of Fuzzy Robot Controllers. Proceedingds of the International Conference on Power Electronics (ICPE'95), pp. 38-44, October, 1995, Seoul, Korea. „The simulation package was developed by Mester et al. []”. **MTMT**
- c3⁽⁴⁷⁰⁾ Istvan Matijevics, Mikrovezérlőt tartalmazó elektronikai berendezések megbízhatóságvizsgálata Markov módszerrel, Markov Models In Reliability Analysis Of Electronic Systems With Microcontrollers, Informatika a felsőoktatásban 2005, Debrecen, 2005. augusztus 24-26, pp. 137-138. **MTMT**
- c4⁽⁴⁷¹⁾ Sean G. McSweeney, William M. D. Wright, Software Interface and Vision System for a SCARA Robot, IEEE Transactions on Robotics and Automation, Vol. 20, No. 3, June 2004, **WoS** link. „Significant advances have been made in recent years in the area of understanding the kinematics [3-5] and jacobians [6-8] of complex and simple linked structures and this work makes use of many of these advances.” **MTMT**
- c5⁽⁴⁷²⁾ Federico Morabito, Andrew R. Teel, *Fellow, IEEE*, and Luca Zaccarian, Nonlinear Antiwindup Applied to Euler-Lagrange Systems, IEEE Transactions on Robotics and Automation, Vol. 20, Issue. 3, pp. 526-537, DOI: 10.1109/TRA.2004.824933, June 2004, **WoS** link. **MTMT**
- c6⁽⁴⁷³⁾ Federico Morabito, Andrew R. Teel and Luca Zaccarian, High Performance Anti-Windup for Robot Manipulators, Proceedings of the European Control Conference, ECC' 2003, Cambridge, United Kingdom, 1-4 September, 2003, **WoS** link. **MTMT**
- c7⁽⁴⁷⁴⁾ Federico Morabito, Salvatore Nicosia, Andrew R. Teel and Luca Zaccarian, „Measuring and Improving Performance in Anti-Windup Laws for Robot Manipulators”, pp 61-85, Advances in Control of Articulated and Mobile Robots, Springer Tracts in Advanced Robotics, Eds. B. Siciliano et al., Volume 10,

- ISBN 978-3-540-20783-2, ISSN 1610-7438, DOI: 10.1007/978-3-540-44410-7_3, 2004. Springer Berlin Heidelberg, **MTMT**
- c8⁽⁴⁷⁵⁾ Sean G. McSweeney, William M. D. Wright, Software Interface and Vision System for a SCARA Robot, Proceedings of the 24th International Manufacturing Conference, IMC 24, 2007, **WoS** link. „Significant advances have been made in recent years in the area of understanding the kinematics [3-5] and jacobians [6-8] of complex and simple linked structures and this work makes use of many of these advances.” **MTMT**
- c9⁽⁴⁷⁶⁾ Leung RWK, Lau HCW, Kwong CK, An expert system to support the optimization of ion plating process: an OLAP-based fuzzy-cum-GA approach, Expert Systems with Applications, Volume 25, Number 3, pp. 313-330, DOI: 10.1016/S0957-4174(03)00071-X, 2003, **WoS** link. **MTMT**
- c10⁽⁴⁷⁷⁾ Topalov AV, Kim JH, Proychev TP, Fuzzy-net control of non-holonomic mobile robot using evolutionary feedback-error-learning, Robotics and Autonomous Sistems, Volume 23, Number 3, pp. 187-200, 1998, **WoS** link. **MTMT**
- c11⁽⁴⁷⁸⁾ Utku Senol, Design by Incorporating Intelligence: Adaptive Structures. The 1996 3rd Biennial Joint Conference on Engineering Systems Design and Analysis, ESDA. Part 2 (of 9); pp. 195-213, Montpellier; France, 01-04 July 1996. **MTMT**
- c12⁽⁴⁷⁹⁾ Morabito, F; Teel, AR; Zaccarian, L, Results on Anti-Windup Design for Euler-Lagrange Systems, Proceedings of the 19th IEEE International Conference on Robotics and Automation (ICRA), pp. 3442-3447, Washington DC, Vol. 4, ISBN 0-7803-7272-7, DOI: 10.1109/ROBOT.2002.1014243, May 11-15, 2002, „Based on the physical parameters of the robot, which have been selected as shown in Table 1 on the basis of [15], we can write a quantitative Euler-Lagrange model of the form (1) for the SCARA robot.”, **WoS** link. **MTMT**
- c13⁽⁴⁸⁰⁾ Rossi Roberto, Bascetta Luca, Rocco Paolo, Implicit force control for an industrial robot with flexible joints and flexible links. Proceedings of the International Conference on Intelligent Robots and Systems (IROS 2014), 2014 IEEE/RSJ, pp. 4742 – 4749, DOI: 10.1109/IROS.2014.6943237, Chicago, IL, USA, 14-18 Sept. 2014, „A number of flexible joint rigid link robot models have been then proposed, aiming at parameter identification and force control [6], [7], [8], especially on the basis of the conservative congruence transformation [9].”.
- E102. Gyula Mester, Pletl Szilveszter, Gizella Pajor: "Neuronski kontroler SCARA robota". Zbornik radova "Simpozijum iz opste mehanike", pp. 83-90, Novi Sad, Yugoslavia, 1994. **MTMT/0.066**
- c1⁽⁴⁸¹⁾ Pletl Szilveszter, Korszerű adaptiv, fuzzy és neurális elvű robotirányítási algoritmusok, Budapest University of Technology and Economics, Ph.D. Thesis, pages 102, Budapest, Hungary, 2001. **MTMT**
- E103. Gyula Mester, Szilveszter Pletl, Gizella Pajor: "Adaptivno dinamicko hibridno upravljanje industrijskih roboata sa elasticnim zglobovima". Proceedings of the XXth Yugoslavien Congress in Theoretical and Applied Mechanics, Vol. 1, pp. 94-97, Kragujevac, Yugoslavia, 1993. **MTMT/0.066**
- c1⁽⁴⁸²⁾ Pletl Szilveszter, Korszerű adaptiv, fuzzy és neurális elvű robotirányítási algoritmusok, Budapest University of Technology and Economics, Ph.D. Thesis, pages 102, Budapest, Hungary, 2001. **MTMT**
- C104. Gyula Mester, Szilveszter Pletl, Gizella Pajor: "Sinteza adaptivnog upravljanja robota sa elastičnim zglobovima". Proceedings of the XXXVIIth Conference of Electronics, Telecommunications, Automation and Nuklear Engineering, ETAN, Part XII, pp. 87-92, ISBN 86-80509-06-X, Beograd, Jugoslavija, 1993. **MTMT/0.066**
- c1⁽⁴⁸³⁾ Pletl Szilveszter, Korszerű adaptiv, fuzzy és neurális elvű robotirányítási algoritmusok, Budapest University of Technology and Economics, Ph. D. Thesis, pages 102, Budapest, Hungary, 2001. **MTMT**
- E105. Gyula Mester, Szilveszter Pletl, Gizella Pajor: "Prikaz softverskog paketa ADAPTSIM za simulaciju adaptivnog upravljanja robota sa elastičnim zglobovima". Zbornik radova IV Simpozijuma o mehaničkim prenosnicima, 8.1, pp. 1-6, Subotica, Jugoslavija, 1993. **MTMT/0.066**
- c1⁽⁴⁸⁴⁾ Pletl Szilveszter, Korszerű adaptiv, fuzzy és neurális elvű robotirányítási algoritmusok, Budapest University of Technology and Economics, Ph.D. Thesis, pages 102, Budapest, Hungary, 2001. **MTMT**
- E106. Gyula Mester, Zoltan Jeges, Szilveszter Pletl, Gizella Pajor: "Dinamika i upravljanje osnovne konfiguracije industrijskog robota sa elastičnim zglobovima". Proceedings of the 37th International Conference Annual Gathering KoREMA, Part 1, pp. 644-647, ISBN 86-81571-11-7, Zagreb, Hrvatska, 26-29.04.1992. **MTMT/0.05**
- c1⁽⁴⁸⁵⁾ Pletl Szilveszter, Korszerű adaptiv, fuzzy és neurális elvű robotirányítási algoritmusok, Budapest University of Technology and Economics, Ph. D. Thesis, pages 102, Budapest, Hungary, 2001. **MTMT**
- E107. **GooSch** Gyula Mester, Szilveszter Pletl, Imre J. Rudas: Dynamic Modeling of Robot Joints. Proceedings of the IEEE International Workshop on Emerging Technologies and Factory Automation, ETFA'92, pp. 561-565, ISBN 0-646-10323-7, Melbourne, Australia, 08/1992. **MTMT/0.066**
- c1⁽⁴⁸⁶⁾ Pletl Szilveszter, Korszerű adaptiv, fuzzy és neurális elvű robotirányítási algoritmusok, Budapest University of Technology and Economics, Ph.D. Thesis, pages 102, Budapest, Hungary, 2001. **MTMT**

c2⁽⁴⁸⁷⁾ Josip Kasac, Vladimir Milic, Josip Stepanic, Gyula Mester, A Computational Approach to Parameter Identification of Spatially Distributed Nonlinear Systems with Unknown Initial Conditions, Proceedings of the IEEE Symposium on Robotic Intelligence in Informationally Structured Space (RiiSS 2014), pp. 1-7, 9-12 December 2014, Orlando, Florida, USA. <http://ieee-ssci.org/RiiSS.html>.

E108. **GooSch** Gyula Mester, Szilveszter Pletl, Gizella Pajor, Zoltan Jeges: "Flexible Planetary Gear Drives in Robotics". Proceedings of the 1992 International Conference on Industrial Electronics, Control, Instrumentation and Automation - Robotics, CIM and Automation, Emerging Technologies, IEEE IECON '92, Vol. 2, p.p 646-649, ISBN 0-7803-0582-5, DOI: 10.1109/IECON.1992.254556, San Diego, California, USA, November 9-13, 1992. **MTMT/0.05**

c1⁽⁴⁸⁸⁾ Imre J. Rudas, O. Kaynak, Janos F. Bito, J.K. Tar: Robustness Analysis of a Paradigm for Non-Linear Robot Controllers Based on Soft Computing Techniques. Proceedings of the IECON'94 20th International Conference on Industrial Electronics Control and Instrumentation, pp. 1633-1638, Bologna, Italy, September 5-9, 1994. **MTMT**

c2⁽⁴⁸⁹⁾ Attila L. Bencsik, V. Garai: A Mechatronic System with Force Feeling to Increase the Activity of Manipulator Control. Proceedings of the IECON'94 20th International Conference on Industrial Electronics Control and Instrumentation, Bologna, Italy, September 5-9, 1994, pp. 1650-1654. **MTMT**

c3⁽⁴⁹⁰⁾ Pletl Szilveszter, Korszerű adaptív, fuzzy és neurális elvű robotirányítási algoritmusok, Budapest University of Technology and Economics, Ph.D. Thesis, pages 102, Budapest, Hungary, 2001. **MTMT**

E109. Gyula Mester, Zoltan Jeges, Szilveszter Pletl, Pajor Gizella: "Dinamicko modeliranje osnovne konfiguracije SCARA robota sa elasticnim zglobovima". Zbornik radova VII simpozija o sistemima automatskog upravljanja, JUREMA, pp. 25-28, ISBN 86-81571-09-5, Zagreb-Tuheljske Toplice, Jugoslavija, 18-20.04.1991. **MTMT/0.05**

c1⁽⁴⁹¹⁾ Pletl Szilveszter: Korszerű adaptív, fuzzy és neurális elvű robotirányítási algoritmusok, Budapest University of Technology and Economics, Ph.D. Thesis, pages 102, Budapest, Hungary, 2001. **MTMT**

E110. Zoltan Jeges, Djula Mester, Branko Zuzic: "Analiza robustnosti algoritma adaptivnog upravljanja sa referentnim modelom". Zbornik radova VII Simpozija o sistemima automatskog upravljanja, JUREMA, pp. 20-24, ISBN 86-81571-09-5, Zagreb-Tuheljske Toplice, Jugoslavija, 18-20.04.1991. **MTMT/0.066**

E111. **GooSch** J. I. Rudas, Gy. Mester: Industrial Robot Control in Case of Uncertain Dynamical Parameters. Proceedings of the 1991 IEEE/RSJ International Workshop on Intelligent Robots and Systems'91, (IROS'91), Vol. 2, pp. 937-944, DOI: 10.1109/IROS.1991.174607, Osaka, Japan, 03/11/1991-05/11/1991. **MTMT/0.1**

E112. Zoltan Jeges, Gyula Mester: "Kontralabilnost elasticnog mehanickog reduktora robota u prisustvu ekscentricnosti". Jugoslovensko Savetovanje o robotizaciji, JUROB '89, Zbornik radova, 4, 195-201, Opatija, Jugoslavija, 1989. **MTMT/0.1**

E113. Gyula Mester, Zoltan Jeges, Szilveszter Pletl: "Modeliranje elektromehanickih prenosnika u robotici". Jugoslovensko Savetovanje o robotizaciji, Zbornik radova, pp. 1-4, JUROB '88, Opatija, Jugoslavija, 1988. **MTM/0.066**

E114. Gyula Mester, Vytautas Turla: "Automatsko sastavljenja dinamickih modela elektromehanickih prenosnika". Zbornik radova „XVIII Jugoslovenski kongres teorijske i primenjene mehanike”, pp. 145-148, Vrnjacka Banja, Jugoslavija, 1988. **MTMT/0.1**

E115. Zoltan Jeges, Gyula Mester, Szilveszter Pletl: "Analiza uticaja torzionih vibracija na elektromotorni pogon". Zbornik radova XVIII Jugoslovenskog kongresa teorijske i primenjene mehanike, pp. 93-96, Vrnjacka Banja, Jugoslavija, 1988. **MTMT/0.066**

E116. Gyula Mester: "Prikaz softverskog paketa DINPOS". Zbornik radova „II Simpozijum o elektromehanickim prenosnicima”, pp. 1-5, Subotica, Jugoslavija, 1988. **MTMT/0.2**

E117. Zoltan Jeges, Gyula Mester, at al.: "Problémy diskrétneho adaptívneho riedenia s referencnym modelom". Proceedings of the Konferencia „Pocitačove riadnenie diskrétnich procesov”, 186/87, pp. 148-153, Bratislava, CSSR, 1987.

E118. Gyula Mester, Vytautas Turla, Gajin Slobodan, Lajos Kutri: "Dinamicko ponasanje zupcastih prenosnika sa asinhronim motorom". Zbornik radova „XVII Jugoslovenski kongres teorijske i primenjene mehanike”, C1-61, pp. 379-384, Zadar, Jugoslavija, 1986. **MTMT/0.05**

E119. Gyula Mester at al., "A gyalogos és kerékpáros balesetek okainak kutatása". Proceedings of the Country Meeting, BAM 359/86, pp. 31-44, Pécs, Hungary, 1986.

- E120. Zoltan Jeges, Gyula Mester, Jozsa Lajos: "Robust Adaptive Control of DC Series Motor". Proceedings of the 3rd Conference on Electronik, Electrical Engineering and Automartic in Railway Transport SEMTRAK, 24-31, Krakow-Janowice, Poland, 1986. **MTMT/0.66**
- E121. Gyula Mester, Lajos Kutri, Gajin Slobodan: "Razmatranje istovremenog uticaja promenljivog momenta inercije radne masine i promenljive krutosti zubaca zupcanika na oscilacije elektromehanickih prenosnika". Zbornik radova „Simpozijum’85 Mehanizmi i masine - opšti problemi dinamike masina”, pp. 374-379, Subotica, Jugoslavija, 1985. **MTMT/0.066**
- E122. Gajin Slobodan, Gyula Mester, Lajos Kutri, Kovacevic Miroljub: "O mogućnosti primene konzolnog antivibratora kod temelja rotacionih električnih masina". Zbornik radova „Simpozijum’85 Mehanizmi i masine - opšti problemi dinamike masina”, pp. 367-373, Subotica, Jugoslavija, 1985.
- E123. Gajin Slobodan, Pavlović Miroljub, Gyula Mester: "Neki aspekti primene nelinearne analize u dinamici temelja masina". Zbornik radova II savetovanja drustva za mehaniku tla i fundiranje SR Srbije, pp. 353-366, Donji Milanovac, Jugoslavija, 1984. **MTMT/0.066**
- E124. **GooSch** Gyula Mester, Lajos Kutri, Gajin Slobodan: "Nelinearna oscilatorna analiza elektromehanickih prenosnika". Zbornik radova „XVI Jugoslovenski kongres teorijske i primenjene mehanike”, A3-14, pp. 377-383, Bečici, Jugoslavija, 1984. **MTMT/0.066**
c1⁽⁴⁹²⁾ Livija Cveticanin, Miodrag Zlokolica: "Parametarske oscilacije elektromehaničkih prenosnika" Zbornik radova II. Znanstveno – stručnog skupa Vibracije rotacionih strojeva i sistema, IFToMM, pp. 289-296, Karlovac, Jugoslavija, 15-17.10.1986..... Matematički model prenosnika prema radu /1/, je [...] **MTMT**
c2⁽⁴⁹³⁾ Jozsef Nyers: "Untersuchung der Torsionsschwingungen beim Zahnraddreuduktor mit Multiskalarer Zeitaufteilungsmethode" Bulletins for Applied Mathematics (495/87), ISSN 0133-3526, pp. 193-202, Budapest, Hungary, 1987. **MTMT**
- E125. Gajin Slobodan, Pavlović Miroljub, Gyula Mester. "Nelinearne oscilacije bloka temelja masine sa obrtnim dejstvom". Zbornik radova „XVI Jugoslovenski kongres teorijske primenjene mehanike, A3-13, pp. 369-376, Bečići, Jugoslavija, 1984. **MTMT/0.066**
- E126. Pavlović Miroljub, Gajin Slobodan, Gyula Mester: "Prilog dinamici krutog plocastog temelja na elasticnom sloju Vlasova - Leontijeva". Zbornik radova VII Kongresa gradjevinskih konstruktora Jugoslavije, TE-68, pp. 241-247, Cavtat, Jugoslavija, 1983. **MTMT/0.066**
- E127. Pavlović Miroljub, Gajin Slobodan, Gyula Mester: "Matematicko modeliranje nelinearnih oscilacija blok temelja na elasticnom sloju". Zbornik radova Simpozijum’83, "Nelinearni problemi dinamike", II-15, pp. 271-278, Arandjelovac, Jugoslavija, 1983. **MTMT/0.066**
- E128. Kutri Lajos, Gyula Mester: "Problematika projektovanja familije zupcastih motornih prenosnika". Zbornik radova Jugoslovensko-Madjarskog simpozijuma "Primjenjena matematika i mehanika u savremenoj tehnici", pp. 223-232, Subotica - Szeged, 1983. **MTMT/0.1**
- E129. Gyula Mester, Lajos Kutri, Gajin Slobodan: "O oscilatornoj analizi dinamičkih zupcastih prenosnika". Zbornik radova Jugoslovensko-Madjarskog simpozijuma "Primjenjena matematika i mehanika u savremenoj tehnici", pp. 235-238, Subotica - Szeged, 1983. **MTMT/0.066**
- E 130. Kuzmanovic Sinisa, Kovacević Dragica, Gyula Mester: "Analiza opteretnosti izlaznih vratila elektromehanickih prenosnika posredstvom elektronskog racunara". Zbornik radova Jugoslovensko-Madjarskog simpozijuma "Primjenjena matematika i mehanika u savremenoj tehnici", pp. 171- 183, Subotica-Szeged 1983. **MTMT/0.066**
- E131. Gyula Mester, Gajin Slobodan: "Prilog resenju problema dinamicke stabilnosti nelinearnih parametarskih torzionih vibracija vratila elektromehanickih prenosnika" Zbornik radova „Savremeni problemi opšte stabilnosti i stabilnosti kontinuma, Simpozijum’82”, pp. 77-85, Tara, Jugoslavija, 1982. **MTM/0.1**
- E132. Gyula Mester, Lajos Kutri, Gajin Slobodan: Prilog dinamici elektromehanickih prenosnika. Zbornik radova III. Jugoslovenskog Simpozijuma Kinematika i dinamika masina i mehanizama, IFToMM, B-12, pp. 231-240, Ljubljana, Jugoslavija, 1981. **MTMT/0.066**
- E133. Gyula Mester, Lajos Kutri: "Non-linear Parametric Vibrations of Motor Gear Machinery" Proceedings of the International Symposium on Gearing & Power Transmissions, pp. 37-42, Tokio, Japan, 1981. **MTM/0.1**
c1⁽⁴⁹⁴⁾ Josip Kasac, Vladimir Milic, Josip Stepanic, Gyula Mester, A Computational Approach to Parameter

E134. Gyula Mester, Lajos Kutri, Zoltan Jeges: "Nelinearne parametarske torzionate oscilacije vratila motor - reduktora". Zbornik radova „XV Jugoslovenski kongres racionalne i primenjene mehanike”, C-52, pp. 423-430, Kupari, Jugoslavija, 1981. **MTMT/0.066**

c1⁽⁴⁹⁵⁾ Branko Gligoric, Vladimir Raicevic, Xhevati Perjuci, "Analiza uticaja ucestanosti promene obrtnog momenta tehnološke masine na nivo torzionih oscilacija vratila masinskog agregata" Zbornik radova II. Znanstveno – stručnog skupa Vibracije rotacionih strojeva i sistema, IFToMM, pp. 281-288, Karlovac, Jugoslavija, 15-17.10.1986 „Ponasanje ovakvog sistema zavisi od brojnih faktora [1,2,3]”. **MTMT**

E135. Gyula Mester, Lajos Kutri: "Nelinearne parametarske torzionate oscilacije vratila reduktora pri uticaju promenljivog momenta inercije radne masine". Zbornik radova Jugoslovenskog Simpozijuma Masina i mehanizam – buka, vibracije i uravnotezenje rotora i masina, IFToMM, pp. 1-9, Beograd, Jugoslavija, 1980. **MTMT/0.1**

E136. Gyula Mester: "Slobodne uzduzne oscilacije prizmaticnog stapa pri nelinearnim spoljasnjim i visokoelastичnim prigusenjem". Zbornik radova XIV Jugoslovenskog kongresa racionalne i primenjene mehanike, C3-10, pp. 251-258, Portorož, Jugoslavija, 5-9.06.1978. **MTMT/0.2**

E137. Gyula Mester, "Prilog resavanju problema slobodnih prigusenih poprecnih oscilacija prizmaticnog stapa pri nelinearnom zakonu elasticnosti". Zbornik radova „XIII Jugoslovenski kongres racionalne i primenjene mehanike”, C3-13, pp. 1-8, Sarajevo, Jugoslavija, 1976. **MTMT/0.2**

F. Meghívott előadó

- F1. Gyula Mester, keynote talk, Új tudományos eredmények mérése, XXX Kandó Conference, Budapest, Hungary, November 20, 2014.
- F2. Gyula Mester, keynote talk, Massive Open Online Courses for Flying Robots, Vipsi Conference, Becici, Montenegro, December 30, 2014 – January 2, 2015.
- F3. Gyula Mester, Cloud Robotics, invited lecture, 10 October 2014, Institute Mihajlo Pupin, Robotics Laboratory, Belgrade, Serbia.
- F4. Gyula Mester, Maxeler Dataflow Supercomputing, invited talk, International Workshop on Advanced Computational Intelligence and Intelligent Informatics (IWACIII), 18-21 October 2013, Shanghai, China.
- F5. Gyula Mester, Magyar nyelvű mérnökképzés a Szabadkai Műszaki Főiskolán 1976-2013, Gyökerek, utak, jövők: az anyanyelv megőrzésének kérdései a Kárpát-medencében konferencia, Pécs, 2013, szeptember 13-14.
- F6. V. Milutinovic, G. Rakocevic, S. Stojanovic, and Z. Sutran, Oskar Mencer, Oliver Pell, Michael Flynn, Gyula Mester, DataFlow SuperComputing for ExaScale Applications: Revisiting the Algorithms, invited talk, Workshop Modern Approach to Product Development and Business Improvement, Balatonfüred, Hungary, 16-19th May 2013.
- F7. Gyula Mester, Aleksandar Rodic, Josip Stepanic, Nonlinear Control of Aerial Robotics, invited talk, Workshop Modern Approach to Product Development and Business Improvement, Balatonfüred, Hungary, 16-19th May 2013.
- F8. Gyula Mester, Methods of Scientific Metrics and Ranking of Scientific Results, invited talk, Workshop Modern Approach to Product Development and Business Improvement, Balatonfüred, Hungary, 16-19th May 2013.
- F9. Gyula Mester, Négy rotoros autonóm robohelikopter modellje, ütközésmentes navigációja, pályatervezése és irányítása, Vajdasági Magyar Tudóstalálkozó, Konferenciakiadvány, pp. &, ISBN &, Szabadka, Szerbia, 2013, április 13.
- F10. Gyula Mester, The Traditional Journal Impact Factor and h Index, invited lecture, 26 May 2011, Institute Mihajlo Pupin, Robotics Laboratory, Belgrade, Serbia.

- F11. Gyula Mester, "Intelligent Mobile Robot Navigation in Unknown Environments", invited lecture, University of Josipa Jurja Strossmayera Osijek, Croatia, May 10 2012.
- F12. Aleksandar Rodić, Gyula Mester, "Remotely Controlled Ground-Aerial Robot-Sensor Network for 3D Environmental Surveillance and Monitoring", invited talk, TAMOP 422 Workshop, Szeged, Hungary, 2011.
- F13. Aleksandar Rodić, Gyula Mester, "Sensor-Based Navigation, Motion Planning and Control of Autonomous Indoor Ambient Adaptive Wheel-Based Robots in Environments with Contingency Risks", invited talk, TAMOP 422 Workshop, Budapest, Hungary, 2011.
- F14. Gyula Mester, "Ranking of World Universities the Latest Update", keynote talk, Vipsi Conference, Tivat, Montenegro, 2010.
- F15. Gyula Mester, "The Impact Factor", invited talk, Univesity of Budensis, Budapest, Hungary, 2010.
- F16. Aleksandar Rodić, Gyula Mester, "Virtual WRSN – Modeling and Simulation of Wireless Robot-Sensor Networked Systems", invited talk, TAMOP 422 Workshop, University of Szeged, Szeged, Hungary, 2010.
- F17. Aleksandar Rodić, Gyula Mester, "Autonomous Locomotion of Humanoid Robots in Presence of Mobile and Immobile Obstacles - Path Planning, Trajectory Prediction, Control and Simulation", invited talk, TAMOP 422 Workshop, University of Szeged, Szeged, Hungary, 2010.
- F18. Gyula Mester, Tamas Szepe, "Intelligent Wheeled Mobil Robot Control in Unknown Environments", TAMOP 422 Workshop, University of Szeged, Szeged, Hungary, 2010.
- F19. Gyula Mester, "Academic Ranking of World Universities 2009/2010", keynote talk, Proceedings of the VIPSI – 2010 Conference, pp. 1-36, Amalfi Italy, 2010.
- F20. Gyula Mester, Ranking 2009 of World Higher Education Institutions, keynote talk, ProSense Workshop, Institute Jožef Stefan, Ljubljana, Slovenia, 2009.
- F21. Gyula Mester, Aleksandar Rodic, Autonomous Locomotion of Humanoid Robots in Presence of Mobile and Immobile Obstacles, invited lecture, Budapest Tech Jubilee Conference, September 1-2, Budapest, Hungary, 2009.
- F22. Gyula Mester, "Lisbon Strategy 2000 in Higher Education of Europe", Proceeding of the International Conference on Advances in the Internet, Processing, Systems, and Interdisciplinary research, VIPSI 2009, keynote talk,, pp. 1-5, ISBN: 86-7466-117-3, Belgrade, Serbia, 03-04th April 2009. **MTMT**
- c1 ⁽⁴⁹⁶⁾ Michael Domijan, "Doctor and Master Professionals – Towards a New Innovative Strategy in the CEE“, Proceedings of the TREND 2010, pp. 141-143, ISBN, 978-86-7892-236-7, Kopaonik, Serbia, 01-04.03.2010. **MTMT**
 - c2 ⁽⁴⁹⁷⁾ Norbert Sabic, "Komparativni Prikaz Svetskih Rang-Lista Visokoobrazovnih Institucija“, Proceedings of the TREND 2011, pp. 65-69, ISBN 978-86-7892-236-7, Kopaonik, Serbia, 07-01.03.2011. **MTMT**
 - c3 ⁽⁴⁹⁸⁾ Gyula Mester, "Academic Ranking of World Universities 2009/2010", Invited Lecture, Proceedings of the VIPSI – 2010 Conference, pp. 1-36, Amalfi Italy, 2010.
 - c4 ⁽⁴⁹⁹⁾ Gyula Mester, "The valuation of the Impact Factor of the Journal Acta Polytechnica Hungarica", Proceedings of the TREND 2011, pp. 70-73, ISBN 978-86-7892-323-4, Kopaonik, Serbia, 2011.
 - c5 ⁽⁵⁰⁰⁾ Gyula Mester, Univerziteti regionali na Sangajskoj rang listi univerziteta u svetu 2012, Proceedings of the XIX Skup Trendovi Razvoja: "Univerzitet na Tržištu...", paper No.T1.1-1, pp. 1-5, Maribor, Pohorje, Slovenija, 18-21.02.2013.
 - c6 ⁽⁵⁰¹⁾ Gyula Mester, "Predlog poboljsanja statusa visokih strukovnih skola Srbije u Bolonjskom sistemu studija", XVI Skup Trendovi Razvoja: Bolonja 2010, pp. 58-61, ISBN 978 86 7892 236 7, Kopaonik, 2010.
- F23. Gyula Mester, "Would we Realise the Aims of the Lisbon Strategy 2000 in Higher Education of Europe? ", invited lecture, Technical University of Applied Sciences, TH Wildau, Berlin, Germany, 2009. **MTMT**
- c1 ⁽⁵⁰²⁾ Anita Sabo, Bojan Kuljić, Tibor Szakáll, " Educational Tools for Object-Oriented DSP Interactive DSL Framework“, Computing and Informatics, CAI, Vol 32, No 3, pp. 509-526, ISSN 1335-9150, 2013. **MTMT**
- F24. Gyula Mester, „Egyetemek világranglistája 2008”, University of Szeged, Hungary, 2008.
- F25. Gyula Mester: „E-learning tananyagfejlesztés LAMP környezetben”, MPV konferencia, Budapest, Hungary, 2004.
- F26. Gyula Mester: „Web alapú oktatórendszer LAMP környezetben”, PHP RoadShow, Dunaújváros, Hungary, 2004.
- F27. Gyula Mester, „Távoktatás fejlesztés a műszaki informatikai felsőoktatásban”, A Kárpát-medencei magyar

professzorok 5. találkozója, plenáris előadás, Nyíregyháza, Hungary, November 9-10. 2001.

- F28. Gyula Mester, „Intelligent Vehicle-Highway System”, Invited Lecture, Conference „Savremene računarske tehnologije 2000“, Subotica, 23.09. 2000.
- F29. Gyula Mester, Szilveszter Pletl: “Structure Optimization of Fuzzy Control Systems by Multi-Population Genetic Algorithm”, Invited Lecture, Prim’97, Subotica, Yugoslavia, 1997.
- F30. Gyula Mester, Attila Nemes, Peter Odri, Szilveszter Pletl: “Design of the Optimal Fuzzy Modeling of Noise pollution using Multi-population Genetic Algorithm”, Invited Lecture, SCPE’97, Nis, Yugoslavia, 1997.
- F31. Gyula Mester, Szilveszter Pletl: “Design of the Optimum Number of Membership Functions in Neuro-Fuzzy Control Systems”. ETFA’96, IEEE International Conference on Emerging Technologies and Factory Automation, Kauai Marriott, Kauai, Hawaii, USA, November 18-21, 1996.
- F32. Gyula Mester, Basic Djuro, Zoltan Jeges: "Modeliranje dinamike pogonskog sistema sa asinhronim motorom". SEITH, IV savetovanje Elektromotorni pogoni, Zadar, 1988.
- F33. Gyula Mester: "Neuralne mreze sa primenama u mehanici", Matematicki institut, SANU, Beograd, Yugoslavia, 1987.
- F34. Gyula Mester: "Istrazivanje i razvoj sistema savremenih elektromehanickih prenosnika". Simpozijum o prenosnicima, Subotica, Yugoslavia, 1987.
- F35. Gyula Mester, Vytautas Turla, Lajos Kutri: "Digitalna simulacija dinamike prenosnika". PAMM simpozijum, Balatonfüred, Hungary, 1986.
- F36. Gyula Mester, Lajos Kutri, Gajin Slobodan: "Prilog nelinearnoj oscilatornoj analizi elektromehanickih prenosnika" Simpozijum "Dinamika masina i mehanizama", Kragujevac, Jugoslavija, 1984.
- F37. Gyula Mester, Lajos Kutri: "Nichtlineare gedämpfte Drehschwingungen des systems bei der Beeinflussung des wechselden Massentrengheitsmoments". GAMM Tagung, Würzburg, Deutschland, 1981.
- F38. Gyula Mester: "Vibrations of the Timoshenko Beam with on a Nonlinear Elastic Basement". GAMM Tagung, Berlin, Deutschland, 1980.
- F39. Gyula Mester, Vibracija Timosenkove grede na nelinearnoj elasticnoj podlozi. Zbornik abstrakata Simpozijum'80 Savremeni problemi nelinearne mehanike kontinuma, pp. II-25, Tara, Jugoslavija, 1980.
- F40. Gyula Mester: "Varijacioni prilaz problemu slobodnih prigusenih uzdužnih oscilacija elasticnih stupova sa nelinearnom elasticnom karakteristikom", Matematicki Institut, Odeljenje za Mehaniku, SANU, Beograd, 1976.

E. További tudományos közlemények

- E1. Mester Gyula, Bevezetés a tudományometriába, A Vajdasági Magyar Mérnökök Műszakiak Egyesülete, Szabadka, Serbia, november 3, 2014.
- E2. Gyula Mester, Wheeled and Humanoid Mobile Robot Navigation, Report on the Research at the Institute of Informatics of the University of Szeged 2006-2009, pp. 16-17, Szeged, Hungary, 2010. **MTMT**
- E3. Gyula Mester, "Academic Ranking of World Universities 2009/2010", University of Belgrade, 2010.
- E4. Gyula Mester, "Sensor Based Wheeled Mobile Robot Navigation", Proceedings from PROSENSE Seminar Presentations, pp. 32-33, Ljubljana, Slovenia, 2010. **MTMT**
- E5. Gyula Mester, "Rangiranje svetskih univerziteta 2009/10", <http://www.ftn.uns.ac.rs/ieee/jch-ns/>, University of Novi Sad, Serbia, 2010.
- E6. Gyula Mester, "Position Correction System of Wheeled Mobile Robots Using Ultrasonic Sensors", Proceeding of the 2nd International Congress of Serbian Society of Mechanics, D11, Palic, Serbia, 2009. **MTMT**
- E7. Gyula Mester, "Internet technológiák", Tankönyv, 123 oldal, Szabadkai Műszaki Szakfőiskola, Szabadka, Serbia, 2008.

- E8. Gyula Mester: "Virtual College of Engineering". Conference of Effect of Information Society on Education of Electric Engineers, (előadás), Budapest, 2000.
- E9. Gyula Mester: "Istrazivanje i razvoj savremenih pogonskih sistema". Pregledni rad, Ministarstvo za nauku i tehnologiju Republike Srbije, Beograd, Jugoslavija, 1995.
- E10. Gyula Mester: "Sinteza neuro-fuzzy upravljanja manipulacionih robota sa elasticnim zglobovima". Zbornik radova naučnog skupa mehanika, materijali i konstrukcije, pp. 151, SANU, Beograd, Yugoslavia, 1995. **MTMT**
- E11. Gyula Mester: "Prikaz softverskog paketa za simulaciju dinamike pogonskog sistema". I medjunarodni simpozijum o elektromehaničkim sistemima, 1990, Subotica.
- E12. Gyula Mester, "A SCARA robotmanipulatorok direkt kinematikai feladata megoldásáról". PAMM, Budapest-God, 1990.
- E13. Gyula Mester, Lajos Kutri, Zoltán Jéges: "Prilog dinamickom modeliranju elektromehanickih prenosnika u robotici". III simpozijum, Teorijska i primenjena mehanika, Skoplje, 1989.
- E14. Gyula Mester, Vytautas Turla, Lajos Kutri: "Gear Dynamic Digital Simulation ". PAMM Simposium, Balatonfüred, Hungary, 1986.
- E15. Gyula Mester: "Varijacioni prilaz problemu prigusenih oscilacija elasticnih stupova sa nelinearnom elasticnom karakteristikom", pp. 1-114, doktorska disertacija, Univerzitet u Novom Sadu, Fakultet Tehnickih Nauka, Novi Sad, Jugoslavija, 1977. **MTM**
- E16. Gyula Mester, "Slobodne poprečne oscilacije prizmatičnog štapa pri nelinearnom zakonu elastičnosti"pp. 85-95, Zbornik radova I, Institut za elektro i mašinsku automatiku, Subotica, Jugoslavija, 1977. **MTMT**

Tudományometriai adatai

Közlemények száma:	246
Idézetek száma:	502
SCI-ben/WoS-ban megtalálható idézetek száma:	92
Független idézetek száma:	400
Összesített impaktfaktor:	3.106
h index:	12
g index:	13
i10 index:	13

Budapest
2014.12.21

Dr. Mester Gyula